

Retraction

Retracted: Automatic Control of Mobile Industrial Robot Based on Multiobjective Optimization Strategy

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Journal of Electrical and Computer Engineering has retracted the article titled “Automatic Control of Mobile Industrial Robot Based on Multiobjective Optimization Strategy” [1] due to concerns that the peer review process has been compromised.

Following an investigation conducted by the Hindawi Research Integrity team [2], significant concerns were identified with the peer reviewers assigned to this article; the investigation has concluded that the peer review process was compromised. We therefore can no longer trust the peer review process, and the article is being retracted with the agreement of the editorial board.

References

- [1] Y. H. Zhu and J. Jiao, “Automatic Control of Mobile Industrial Robot Based on Multiobjective Optimization Strategy,” *Journal of Electrical and Computer Engineering*, vol. 2022, Article ID 7825906, 7 pages, 2022.
- [2] L. Ferguson, “Advancing Research Integrity Collaboratively and with Vigour,” 2022, <https://www.hindawi.com/post/advancing-research-integrity-collaboratively-and-vigour/>.