# A System of Differential Set-Valued Variational Inequalities in Finite Dimensional Spaces 

Wei Li, ${ }^{1}$ Xing Wang, ${ }^{2}$ and Nan-Jing Huang ${ }^{1}$<br>${ }^{1}$ Department of Mathematics, Sichuan University, Chengdu 610064, China<br>${ }^{2}$ School of Information Technology, Jiangxi University of Finance and Economics, Nanchang 330013, China

Correspondence should be addressed to Nan-Jing Huang; nanjinghuang@hotmail.com
Received 29 May 2013; Revised 5 November 2013; Accepted 19 November 2013; Published 4 february 2014
Academic Editor: John R. Akeroyd
Copyright © 2014 Wei Li et al. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.


#### Abstract

A system of differential set-valued variational inequalities is introduced and studied in finite dimensional Euclidean spaces. An existence theorem of weak solutions for the system of differential set-valued variational inequalities in the sense of Carathéodory is proved under some suitable conditions. Furthermore, a convergence result on Euler time-dependent procedure for solving the system of differential set-valued variational inequalities is also given.


## 1. Introduction

For a set-valued mapping $F: R^{n} \rightrightarrows R^{n}$ and a nonempty closed convex set $K$ in $R^{n}$, the $\operatorname{VI}(K, F)$, is to find $u \in K$ and $u^{*} \in F(u)$ such that $\left\langle u^{*}, u^{\prime}-u\right\rangle \geq 0$ for all $u^{\prime} \in K$. Let $\operatorname{SOL}(K, F)$ denote the solution set of this problem. We write $\dot{x}:=d x / d t$ for the time-derivative of a function $x(t)$. In this paper, we consider the following system of differential set-valued variational inequalities:

$$
\begin{gather*}
\dot{x}(t)=f(t, x(t))+B_{1}(t, x(t)) u(t)+B_{2}(t, x(t)) v(t), \\
\left\langle G_{1}(t, x(t))+F_{1}(u(t)), u^{\prime}-u(t)\right\rangle \geq 0, \quad \forall u^{\prime} \in K,  \tag{1}\\
\left\langle G_{2}(t, x(t))+F_{2}\left(v^{\prime}(t)\right), v^{\prime}-v(t)\right\rangle \geq 0, \quad \forall v^{\prime} \in K, \\
x(0)=x_{0},
\end{gather*}
$$

where $\Omega \equiv[0, T] \times R^{m}, f: \Omega \rightarrow R^{m}, B_{i}: \Omega \rightarrow R^{m \times n}$, $G_{i}: \Omega \rightarrow R^{n}$, and $F_{i}: R^{n} \rightrightarrows R^{n}(i=1,2)$ are given mappings.

In [1], Pang and Stewart introduced a class of differential variational inequalities in finite dimensional Euclidean spaces. For some related results, we refer to [2-17]. Recently, the differential variational inequalities have been used in cellular biology (see [18]). In [18], the authors needed two or more variational inequalities to formulate the switching
between the metabolic models. Sometimes it is convenient to apply the differential vector variational inequalities in [19] to show the fermentation dynamics. However, when we study the fermentation model (20) in [18], we find that the system (1) in this paper can help us a lot.

In this paper, we establish an existence theorem of weak solutions for the system (1) in the sense of Carathéodory under some suitable conditions. Furthermore, we give a convergence result on Euler time-dependent procedure for solving the system (1).

## 2. Preliminaries

In this section, we will introduce some basic notations and preliminary results.

In the rest of this paper, we will use the following assumptions (A) and (B).
(A) $f, B_{1}, B_{2}, G_{1}$, and $G_{2}$ are Lipschitz continuous functions on $\Omega$ with Lipschitz constants $L_{f}, L_{B_{1}}, L_{B_{2}}, L_{G_{1}}$, and $L_{G_{2}}$, respectively.
(B) $B_{1}$ is bounded on $\Omega$ with $\sigma_{B_{1}} \equiv \sup _{(t, x) \in \Omega}\left\|B_{1}(t, x)\right\|<$ $\infty ; B_{2}$ is bounded on $\Omega$ with $\sigma_{B_{2}} \equiv$ $\sup _{(t, x) \in \Omega}\left\|B_{2}(t, x)\right\|<\infty$.

Definition 1. A set-valued map $F: R^{n} \rightrightarrows R^{n}$ is said to be
(i) monotone on a convex set $K \subset R^{n}$ if for each pair of points $x, y \in K$, and for all $x^{*} \in F(x)$ and $y^{*} \in F(y)$, $\left\langle x^{*}-y^{*}, x-y\right\rangle \geq 0$;
(ii) pseudo monotone on a convex set $K \subset R^{n}$ if for each pair of points $x, y \in K$, and for all $x^{*} \in F(x)$ and $y^{*} \in$ $F(y),\left\langle y^{*}, x-y\right\rangle \geq 0$ implies that $\left\langle x^{*}, x-y\right\rangle \geq 0$.

Definition 2. A function $f: \Omega \rightarrow R^{n}$ (resp., $B: \Omega \rightarrow R^{n \times m}$ ) is said to be Lipschitz continuous if there exists a constant $L_{f}>0$ (resp., $L_{B}>0$ ) such that, for any $\left(t_{1}, x\right),\left(t_{2}, y\right) \in \Omega$,

$$
\begin{gather*}
\left\|f\left(t_{1}, x\right)-f\left(t_{2}, y\right)\right\| \leq L_{f}\left(\left|t_{1}-t_{2}\right|+\|x-y\|\right) \\
\left(\operatorname{resp} .,\left\|B\left(t_{1}, x\right)-B\left(t_{2}, y\right)\right\| \leq L_{B}\left(\left|t_{1}-t_{2}\right|+\|x-y\|\right)\right) \tag{2}
\end{gather*}
$$

Definition 3. Let $X, Y$ be topological spaces and let $F$ : $X \rightrightarrows Y$ be a set-valued mapping with nonempty values. One says that $F$ is upper semicontinuous at $x_{0} \in X$ if and only if, for any neighborhood $\mathcal{N}\left(F\left(x_{0}\right)\right)$ of $F\left(x_{0}\right)$, there exists a neighborhood $\mathcal{N}\left(x_{0}\right)$ of $x_{0}$ such that

$$
\begin{equation*}
F(x) \subset \mathcal{N}\left(F\left(x_{0}\right)\right), \quad \forall x \in \mathcal{N}\left(x_{0}\right) \tag{3}
\end{equation*}
$$

Lemma 4 (see [1]). Let $\mathbb{F}: \Omega \rightrightarrows R^{m}$ be an upper semicontinuous set-valued map with nonempty closed convex values. Suppose that there exists a scalar $\rho_{\mathbb{F}}>0$ satisfying

$$
\begin{equation*}
\sup \{\|y\|: y \in \mathbb{F}(t, x)\} \leq \rho_{\mathbb{F}}(1+\|x\|), \quad \forall(t, x) \in \Omega . \tag{4}
\end{equation*}
$$

For every $x^{0} \in R^{n}$, the $D I: \dot{x} \in \mathbb{F}(t, x), x(0)=x^{0}$ has a weak solution in the sense of Carathéodory.

Lemma 5 (see [1]). Let $h: \Omega \times R^{m} \rightarrow R^{n}$ be a continuous function and let $U: \Omega \rightrightarrows R^{m}$ be a closed set-valued map such that, for some constant $\eta_{U}>0$,

$$
\begin{equation*}
\sup _{u \in U(t, x)}\|u\| \leq \eta_{U}(1+\|x\|), \quad \forall(t, x) \in \Omega \tag{5}
\end{equation*}
$$

Let v : $[0, T] \rightarrow R^{n}$ be a measurable function and let $x:[0, T]$ $\rightarrow R^{n}$ be a continuous function satisfying $v(t) \in h(t, x(t)$, $U(t, x(t)))$ for almost all $t \in[0, T]$. There exists a measurable function $u:[0, T] \rightarrow R^{m}$ such that $u(t) \in U(t, x(t))$ and $v(t)=h(t, x(t), u(t))$ for almost all $t \in[0, T]$.

Lemma 6 (see [20]). Let $\widehat{m}$ denote the Lebesgue measure on $R^{n}$ and let $f: R^{n} \rightarrow R^{m}$ be a measurable function. Let $L$ be a measurable set in $R^{n}$ with $\widehat{m}(L)<\infty$. Then, for any $\varepsilon>0$, there exists a compact set $K \subseteq L$ with $\widehat{m}(L \backslash K)<\varepsilon$ such that the restriction of $f$ to $K$ is continuous.

Definition 7 (see [21]). An acyclic set is a set whose homology is the same as the homology of the space consisting of just one point. An acyclic map is an upper semicontinuous set-valued map which has compact acyclic values.

In [21], we can find that every homeomorphic image of a compact convex set is an acyclic set.

Lemma 8 (see [1]). Every acyclic set-valued map $F: X \rightarrow X$ on a compact convex set $X$ has a fixed point: $x \in F(x)$ for some $x \in X$.

## 3. Main Results

In this section, we obtain existence theorem for weak solutions of the differential set-valued variational inequality in the sense of Carathéodory. Furthermore, we establish a convergence result for solving differential set-valued variational inequality.

Theorem 9. Assume that $\left(f, B_{1}, B_{2}, G_{1}, G_{2}\right)$ satisfy conditions (A) and $(B)$ and $F_{i}: R^{n} \rightrightarrows R^{n}(i=1,2)$ are upper semicontinuous with nonempty and compact values such that $q_{i}+F_{i}(i=1,2)$ are pseudo monotone on $R^{n}$ for each $q_{i} \in$ $G_{i}(\Omega)(i=1,2)$. If $K$ is a bounded, closed, and convex subset of $R^{n}$, then initial-value system (1) has a weak solution.

Proof. From the proofs of Lemmas 3.2, 3.3, and 3.4 and Theorem 3.1 in [19], it is easy to see that the assumption " $F$ is pseudo monotone on $R^{n "}$ in there should be replaced by the assumption " $q+F$ is pseudo monotone on $R^{n}$ for each $q \in G(\Omega)$." Since $K$ is a bounded, closed, and convex subset of $R^{n}$, it follows from Lemma 3.3 in [19] that $\operatorname{SOL}\left(K, q_{i}+\right.$ $\left.F_{i}\right)(i=1,2)$ are nonempty and bounded. Let $u=\left(u_{1}, u_{2}\right)$, where $u_{i} \in \operatorname{SOL}\left(K, q_{i}+F_{i}\right),(i=1,2)$. Then it follows that $u$ is bounded on $R^{2 n}$. Moreover, Lemma 3.4 in [19] shows that $\operatorname{SOL}\left(K, q_{i}+F_{i}\right)(i=1,2)$ are closed and convex for all $q_{i} \in G_{i}(\Omega)$. Therefore, $\operatorname{SOL}\left(K, q_{1}+F_{2}\right) \times \operatorname{SOL}\left(K, q_{2}+F_{2}\right)$ is closed and convex. Let

$$
\begin{gather*}
\mathbb{F}(t, x) \equiv\left\{f(t, x)+B_{1}(t, x) u_{1}+B_{2}(t, x) u_{2}:\right. \\
\left.u_{i} \in \operatorname{SOL}\left(K, G_{i}(t, x)+F_{i}\right)\right\} . \tag{6}
\end{gather*}
$$

We can prove in a similar way as Lemma 6.3 in [1] that $\mathbb{F}$ has linear growth and it is upper semicontinuous on $\Omega$. Now it follows from Lemmas 4 and 5 that system (1) has a weak solution. This completes the proof.

Remark 10. If $F_{i}: R^{n} \rightrightarrows R^{n}(i=1,2)$ are monotone, then it is easy to see that $q_{i}+F_{i}(i=1,2)$ are pseudo monotone on $R^{n}$ for each $q_{i} \in G_{i}(\Omega)(i=1,2)$.

Lemma 11. Let $G: \Omega \times R^{m} \rightarrow R^{n}$ be a continuous function, $F: L^{2}[0, T] \rightrightarrows L^{2}[0, T]$ a set-valued function, and $u(t) \in K$ with $u \in L^{2}[0, T]$. Suppose there exists $u^{*} \in F(u)$ such that, for any continuous function $\tilde{u}:[0, T] \rightarrow K$, one has

$$
\begin{equation*}
\int_{0}^{T}\left\langle G(t, x(t))+u^{*}(t), \tilde{u}(t)-u(t)\right\rangle d t \geq 0 \tag{7}
\end{equation*}
$$

Then, for almost all $t \in[0, T], u(t) \in \operatorname{SOL}(K, G(t, x(t))+F(\cdot))$.
Proof. We assume that the contrary holds. Then there exists a set $E \subset[0, T]$ with $\widehat{m}(E)>0$ (where $\widehat{m}(E)$ denotes the Lebesgue measure of $E$ such that, for all $t \in E, u(t) \notin$ $\operatorname{SOL}(K, G(t, x(t))+F(\cdot))$. By Lemma 6, we know that there exists a closed subset $E_{1}$ of $E$ with $\widehat{m}\left(E_{1}\right)>0$ such that $u(t)$
and $u^{*}(t)$ are continuous on $E_{1}$, where $u^{*}(t) \in F(u(t))$. Then there exists a closed subset $E_{2}$ of $E_{1}$ with $\widehat{m}\left(E_{2}\right)>0$ and $v_{0} \in K$ such that

$$
\begin{equation*}
\left\langle G(t, x(t))+u^{*}(t), v_{0}-u(t)\right\rangle<0, \tag{8}
\end{equation*}
$$

and so

$$
\begin{equation*}
\int_{E_{2}}\left\langle G(t, x(t))+u^{*}(t), v_{0}-u(t)\right\rangle d t<0 . \tag{9}
\end{equation*}
$$

Let

$$
u_{0}(t)= \begin{cases}v_{0}, & t \in E_{2}  \tag{10}\\ u(t), & t \in[0, T] \backslash E_{2}\end{cases}
$$

We know that $u_{0}(t) \in K$ is an integrable function on $[0, T]$. Since the space of continuous functions $C\left([0, T] ; R^{m}\right)$ is dense in $L^{1}\left([0, T] ; R^{m}\right)$, we can approximate $u_{0}(t) \in L^{1}\left([0, T] ; R^{m}\right)$ by continuous functions $\bar{u}(t) \in K$ and obtain that there exists a continuous function $\bar{u}(t)$ such that

$$
\begin{equation*}
\int_{0}^{T}\left\langle G(t, x(t))+u^{*}(t), \bar{u}(t)-u(t)\right\rangle d t<0 \tag{11}
\end{equation*}
$$

which contradicts (7). This completes the proof.
Remark 12. If $u(t)$ is an integrable function satisfying, for almost all $t \in[0, T]$,

$$
\begin{equation*}
u(t) \in \operatorname{SOL}(K, G(t, x(t), \cdot)+F(\cdot)) \tag{12}
\end{equation*}
$$

then the integral inequality (7) must hold for any continuous $\widehat{\mathcal{u}}:[0, T] \rightarrow K$.

Now we begin to design a computational method for solving DVI (1). With $x^{h, 0}:=x^{0}$, we compute

$$
\begin{align*}
& \left\{x^{h, 1}, x^{h, 2}, \ldots, x^{h, N_{h}+1}\right\} \subset R^{n}, \\
& \left\{u^{h, 1}, u^{h, 2}, \ldots, u^{h, N_{h}+1}\right\} \subset K  \tag{13}\\
& \left\{v^{h, 1}, v^{h, 2}, \ldots, v^{h, N_{h}+1}\right\} \subset K
\end{align*}
$$

by the recursion, for $i=0,1, \ldots, N_{h}$, where $N_{h}=(T / h)-1$,

$$
\begin{align*}
& x^{h, i+1}=x^{h, i}+h[ f\left(t_{h, i+1}, \theta x^{h, i}+(1-\theta) x^{h, i+1}\right) \\
&\left.+B_{1}\left(t_{h, i}, x^{h, i}\right) u^{h, i+1}+B_{2}\left(t_{h, i}, x^{h, i}\right) v^{h, i+1}\right] \\
& u^{h, i+1} \in \operatorname{SOL}\left(K, G_{1}\left(t_{h, i+1}, x^{h, i+1}\right)+F_{1}\right) \\
& v^{h, i+1} \in \operatorname{SOL}\left(K, G_{2}\left(t_{h, i+1}, x^{h, i+1}\right)+F_{2}\right) \tag{14}
\end{align*}
$$

that is,

$$
\begin{aligned}
x^{h, i+1}=x^{h, i}+h[ & f\left(t_{h, i+1}, \theta x^{h, i}+(1-\theta) x^{h, i+1}\right) \\
& \left.+B_{1}\left(t_{h, i}, x^{h, i}\right) u^{h, i+1}+B_{2}\left(t_{h, i}, x^{h, i}\right) v^{h, i+1}\right], \\
\left\langle G_{1}\left(t_{h, i+1}, x^{h, i+1}\right)+\right. & \left.F_{1}\left(u^{h, i+1}\right), u^{\prime}-u^{h, i+1}\right\rangle \geq 0, \quad \forall u^{\prime} \in K, \\
\left\langle G_{2}\left(t_{h, i+1}, x^{h, i+1}\right)+\right. & \left.F_{2}\left(v^{h, i+1}\right), v^{\prime}-v^{h, i+1}\right\rangle \geq 0, \quad \forall v^{\prime} \in K .
\end{aligned}
$$

Lemma 13. Let $\left(f, B_{1}, B_{2}, G_{1}, G_{2}\right)$ satisfy conditions (A) and (B). Then there exists an $h_{0}>0$ such that, for any $h \in$ $\left(0, h_{0}\right],\left(x^{r e f}, u, v\right) \in R^{n+m+m}$ with $\theta \in[0,1]$ and $t, t_{\text {ref }}$ in $[0, T]$, there exists a unique vector $x_{u v}$ satisfying

$$
\begin{align*}
x_{u v}-x^{r e f}=h[ & f\left(t, \theta x^{r e f}+(1-\theta) x_{u v}\right)+B_{1}\left(t_{r e f}, x^{r e f}\right) u \\
& \left.+B_{2}\left(t_{r e f}, x^{r e f}\right) v\right] . \tag{16}
\end{align*}
$$

Moreover, for any $u, v, u^{\prime}, v^{\prime} \in R^{m}$, one has

$$
\begin{gather*}
\left\|x_{u v}-x_{u^{\prime} v^{\prime}}\right\| \leq \frac{h \sigma_{B_{1}}\left\|u-u^{\prime}\right\|+h \sigma_{B_{2}}\left\|v-v^{\prime}\right\|}{1-h(1-\theta) L_{f}},  \tag{17}\\
\left\|x_{u v}-x^{r e f}\right\| \leq \frac{\rho_{f}\left(1+\left\|x^{r e f}\right\|\right)+\sigma_{B_{1}}\|u\|+\sigma_{B_{2}}\|v\|}{1-h(1-\theta) \rho_{f}} .
\end{gather*}
$$

Proof. It suffices to choose $h_{0}$ satisfying

$$
\begin{equation*}
0<h_{0}<\min \left\{\frac{1}{(1-\theta) L_{f}}, \frac{1}{(1-\theta) \rho_{f}}\right\} \tag{18}
\end{equation*}
$$

The right-hand side is taken to be $\infty$ if $\theta=1$. Under this choice, consider any tuple ( $h, x^{\text {ref }}, u, v, t, t_{\text {ref }}$ ) as specified. Let

$$
\begin{align*}
\mathscr{F}(x)= & h f\left(t, \theta x^{\mathrm{ref}}+(1-\theta) x\right)+h B_{1}\left(t_{\mathrm{ref}}, x^{\mathrm{ref}}\right) u \\
& +h B_{2}\left(t_{\mathrm{ref}}, x^{\mathrm{ref}}\right) v+x^{\mathrm{ref}} . \tag{19}
\end{align*}
$$

Then

$$
\begin{align*}
\| \mathscr{F} & \left(x_{1}\right)-\mathscr{F}\left(x_{2}\right) \| \\
& =\left\|h f\left(t, \theta x^{\text {ref }}+(1-\theta) x_{1}\right)-h f\left(t, \theta x^{\text {ref }}+(1-\theta) x_{2}\right)\right\| \\
& \leq h L_{f}(1-\theta)\left\|x_{1}-x_{2}\right\|, \tag{20}
\end{align*}
$$

with $0<h L_{f}(1-\theta)<1$. This shows that the map $\mathscr{F}$ is contractive and so there exists a unique vector $x_{u v}$ such that

$$
\begin{align*}
x_{u v}-x^{\mathrm{ref}}=h[ & f\left(t, \theta x^{\mathrm{ref}}+(1-\theta) x_{u v}\right)+B_{1}\left(t_{\mathrm{ref}}, x^{\mathrm{ref}}\right) u \\
& \left.+B_{2}\left(t_{\mathrm{ref}}, x^{\mathrm{ref}}\right) v\right] . \tag{21}
\end{align*}
$$

It implies that, for any $\left(u_{1}, v_{1}\right),\left(u_{2}, v_{2}\right) \in R^{m \times m}$, there exist $x_{u_{1} v_{1}}$ and $x_{u_{2} v_{2}}$ such that

$$
\begin{align*}
x_{u_{1} v_{1}}-x^{\mathrm{ref}}=h[ & f\left(t, \theta x^{\mathrm{ref}}+(1-\theta) x_{u_{1} v_{1}}\right)+B_{1}\left(t_{\mathrm{ref}}, x^{\mathrm{ref}}\right) u_{1} \\
& \left.+B_{2}\left(t_{\mathrm{ref}}, x^{\mathrm{ref}}\right) v_{1}\right] \\
x_{u_{2}, v_{2}}-x^{\mathrm{ref}}=h[ & f\left(t, \theta x^{\mathrm{ref}}+(1-\theta) x_{u_{2}, v_{2}}\right)+B_{1}\left(t_{\mathrm{ref}}, x^{\mathrm{ref}}\right) u_{2} \\
& \left.+B_{2}\left(t_{\mathrm{ref}}, x^{\mathrm{ref}}\right) v_{2}\right] . \tag{22}
\end{align*}
$$

By (22), we have

$$
\begin{align*}
& \left\|x_{u_{1} v_{1}}-x_{u_{2}, v_{2}}\right\| \\
& \quad \leq  \tag{23}\\
& \quad h L_{f}(1-\theta)\left\|x_{u_{1} v_{1}}-x_{u_{2}, v_{2}}\right\|+h \sigma_{B_{1}}\left\|u_{1}-u_{2}\right\| \\
& \quad+h \sigma_{B_{2}}\left\|v_{1}-v_{2}\right\|
\end{align*}
$$

and so

$$
\begin{equation*}
\left\|x_{u_{1} v_{1}}-x_{u_{2}, v_{2}}\right\| \leq \frac{h \sigma_{B_{1}}\left\|u_{1}-u_{2}\right\|+h \sigma_{B_{2}}\left\|v_{1}-v_{2}\right\|}{1-h L_{f}(1-\theta)} \tag{24}
\end{equation*}
$$

Now the Lipschitz continuity of $f$ implies that there exists $\rho_{f}$ satisfying

$$
\begin{equation*}
\|f(t, x)\| \leq \rho_{f}(1+\|x\|) \tag{25}
\end{equation*}
$$

It follows that

$$
\begin{align*}
& \left\|x_{u v}-x^{\mathrm{ref}}\right\| \\
& =h \| f\left(t, \theta x^{\mathrm{ref}}+(1-\theta) x_{u v}\right)+B_{1}\left(t_{\mathrm{ref}}, x^{\mathrm{ref}}\right) u \\
& \quad+B_{2}\left(t_{\mathrm{ref}}, x^{\mathrm{ref}}\right) v \| \\
& \leq \\
& =h \rho_{f}\left(1+\left\|\theta x^{\mathrm{ref}}+(1-\theta) x_{u v}\right\|\right)+h \sigma_{B_{1}}\|u\|+h \sigma_{B_{2}}\|v\| \\
& \leq h \rho_{f}\left(1+(1-\theta)\left\|x_{u v}-x^{\mathrm{ref}}\right\|+\left\|x^{\mathrm{ref}}\right\|\right)  \tag{26}\\
& \quad+h \sigma_{B_{1}}\|u\|+h \sigma_{B_{2}}\|v\|
\end{align*}
$$

and so

$$
\begin{equation*}
\left\|x_{u v}-x^{\text {ref }}\right\| \leq \frac{h \rho_{f}\left(1+\left\|x^{\text {ref }}\right\|\right)+h \sigma_{B_{1}}\|u\|+h \sigma_{B_{2}}\|v\|}{1-h \rho_{f}(1-\theta)} . \tag{27}
\end{equation*}
$$

This completes the proof.
Lemma 14. Let $\left(f, B_{1}, B_{2}, G_{1}, G_{2}\right)$ satisfy conditions (A) and (B). Suppose that $\operatorname{SOL}\left(K, q_{1}+F_{1}\right)$ and $\operatorname{SOL}\left(K, q_{2}+F_{2}\right)$ satisfy the linear growth properties

$$
\begin{align*}
\sup \left\{\|u\|: u \in \operatorname{SOL}\left(K, q_{1}+F_{1}\right)\right\} \leq & \rho_{1}\left(1+\left\|q_{1}\right\|\right) \\
& \forall q_{1} \in G_{1}(\Omega) \tag{28}
\end{align*}
$$

$\sup \left\{\|u\|: u \in \operatorname{SOL}\left(K, q_{2}+F_{2}\right)\right\} \leq \rho_{2}\left(1+\left\|q_{2}\right\|\right)$,

$$
\forall q_{2} \in G_{2}(\Omega)
$$

Then there exist positive scalars $C_{0 x}, C_{1 x}, C_{0 u}, C_{1 u}, C_{0 v}, C_{1 v}$, and $h_{1}$ such that, for any $h \in\left(0, h_{1}\right]$ and $i=0,1, \ldots, N_{h}$,

$$
\begin{align*}
& \left\|x^{h, i+1}\right\| \leq C_{0 x}+C_{1 x}\left\|x^{0}\right\|, \\
& \left\|u^{h, i+1}\right\| \leq C_{0 u}+C_{1 u}\left\|x^{0}\right\|,  \tag{29}\\
& \left\|v^{h, i+1}\right\| \leq C_{0 v}+C_{1 v}\left\|x^{0}\right\| . \tag{34}
\end{align*}
$$

$$
\begin{array}{ll}
M_{1}=\rho_{1}+\rho_{1} \rho_{G_{1}}+h \rho_{1} \rho_{G_{1}} \rho_{x}, & N_{1}=\rho_{1} \rho_{G_{1}} \rho_{x} \\
M_{2}=\rho_{2}+\rho_{2} \rho_{G_{2}}+h \rho_{2} \rho_{G_{2}} \rho_{x}, & N_{2}=\rho_{2} \rho_{G_{2}} \rho_{x} . \tag{33}
\end{array}
$$

Then, we have

$$
\begin{aligned}
& \left(1-h N_{1}\right)\left\|u^{h, i+1}\right\| \leq M\left(1+\left\|x^{h, i}\right\|\right)+h N_{1}\left\|v^{h, i+1}\right\| \\
& \left(1-h N_{2}\right)\left\|v^{h, i+1}\right\| \leq M\left(1+\left\|x^{h, i}\right\|\right)+h N_{2}\left\|u^{h, i+1}\right\|
\end{aligned}
$$

Letting $0<h<\min \left\{1 / N_{1}, 1 / N_{2}\right\}$, one has

$$
\begin{align*}
\left\|u^{h, i+1}\right\| \leq & \frac{1}{1-h N_{1}} \\
& \times\left[M\left(1+\left\|x^{h, i}\right\|\right)+h N_{1}\right. \\
& \left.\times\left(\frac{1}{1-h N_{2}}\left(M\left(1+\left\|x^{h, i}\right\|\right)+h N_{2}\left\|u^{h, i+1}\right\|\right)\right)\right] . \tag{35}
\end{align*}
$$

When $h$ is sufficiently small, there exists $\rho_{M_{1}}>0$ such that

$$
\begin{equation*}
\left\|u^{h, i+1}\right\| \leq \rho_{M_{1}}\left(1+\left\|x^{h, i}\right\|\right) . \tag{36}
\end{equation*}
$$

In a similar way, we can prove that there exists $\rho_{M_{2}}>0$ such that

$$
\begin{equation*}
\left\|v^{h, i+1}\right\| \leq \rho_{M_{2}}\left(1+\left\|x^{h, i}\right\|\right) \tag{37}
\end{equation*}
$$

It follows from (31) that

$$
\begin{align*}
& \left\|x^{h, i+1}-x^{h, i}\right\| \\
& \quad \leq h \rho_{x}\left(1+\left\|x^{h, i}\right\|+\rho_{M_{1}}\left(1+\left\|x^{h, i}\right\|\right)+\rho_{M_{2}}\left(1+\left\|x^{h, i}\right\|\right)\right) \\
& \quad=\left(h \rho_{x}+h \rho_{x} \rho_{M_{1}}+h \rho_{x} \rho_{M_{2}}\right)\left(1+\left\|x^{h, i}\right\|\right) \tag{38}
\end{align*}
$$

Let

$$
\begin{equation*}
\psi_{x}=\rho_{x}+\rho_{x} \rho_{M_{1}}+\rho_{x} \rho_{M_{2}} . \tag{39}
\end{equation*}
$$

Then

$$
\begin{equation*}
\left\|x^{h, i+1}-x^{h, i}\right\| \leq h \psi_{x}\left(1+\left\|x^{h, i}\right\|\right) . \tag{40}
\end{equation*}
$$

It follows from Lemma 7.2 in [1] that there exist positive scalars $C_{0 x}, C_{1 x}, C_{0 u}, C_{1 u}, C_{0 v}, C_{1 v}$, and $h_{1}$ such that, for any $h \in\left(0, h_{1}\right]$ and $i=0,1, \ldots, N_{h}$,

$$
\begin{align*}
& \left\|x^{h, i+1}\right\| \leq C_{0 x}+C_{1 x}\left\|x^{0}\right\|, \\
& \left\|u^{h, i+1}\right\| \leq C_{0 u}+C_{1 u}\left\|x^{0}\right\|,  \tag{41}\\
& \left\|v^{h, i+1}\right\| \leq C_{0 v}+C_{1 v}\left\|x^{0}\right\| .
\end{align*}
$$

This completes the proof.
Lemma 15. Let $K \subset R^{n}$ be a nonempty, closed, and convex set and let $\left(f, B_{1}, B_{2}, G_{1}, G_{2}\right)$ satisfy conditions (A) and (B). Suppose that the set-valued maps $F_{1}, F_{2}$ are upper semicontinuous with nonempty compact values such that $q_{i}+F_{i}(i=1,2)$ are pseudo monotone on $R^{n}$ for each $q_{i} \in G_{i}(\Omega)(i=1,2)$. For some constant $\rho>0, \operatorname{SOL}\left(K, q_{1}+F_{1}\right)$ and $\operatorname{SOL}\left(K, q_{2}+F_{2}\right)$ satisfy the linear growth properties

$$
\begin{array}{r}
\sup \left\{\|u\|: u \in \operatorname{SOL}\left(K, q_{1}+F_{1}\right)\right\} \leq \rho\left(1+\left\|q_{1}\right\|\right)  \tag{42}\\
\forall q_{1} \in G_{1}(\Omega)
\end{array}
$$

$\sup \left\{\|u\|: u \in \operatorname{SOL}\left(K, q_{2}+F_{2}\right)\right\} \leq \rho\left(1+\left\|q_{2}\right\|\right)$,

$$
\begin{equation*}
\forall q_{2} \in G_{2}(\Omega) \tag{43}
\end{equation*}
$$

Then there exists a scalar $h_{R}>0$ such that, for any $h \in\left(0, h_{R}\right]$ with $\theta \in[0,1]$ and $x^{0} \in R$, there exists $\left(x^{h, i+1}, u^{h, i+1}, v^{h, i+1}\right)$ satisfying (15) for every $i=0,1, \ldots, N_{h}$.

Proof. Assume that $\psi_{x}$ is defined by (39). For any scalar $h>0$ sufficiently small, we define the scalars $\rho_{1}, \rho_{2}, \ldots, \rho_{N_{h}+1}$ by

$$
\begin{equation*}
\rho_{i+1} \equiv\left(1+h \psi_{x}\right) \rho_{i}+h \psi_{x}, \quad i=0,1, \ldots, N_{h} \tag{44}
\end{equation*}
$$

where $\rho_{0}$ is arbitrary. By the proof of Lemma 7.2 in [1], we can show that

$$
\begin{equation*}
\rho_{i} \leq e^{T \psi_{x}} \rho_{0}+e^{T \psi_{x}}-1, \quad \forall i=0,1, \ldots, N_{i}+1 \tag{45}
\end{equation*}
$$

Let $\alpha$ denote the quantity on the right-hand side, which depends on $\rho_{0}$ but is independent of $h$. Let $0<h_{R}<$ $\min \left\{h_{0}, h_{1}\right\}$ satisfy

$$
\begin{equation*}
h_{R} \frac{\rho_{f}(1+\alpha)+\left(\sigma_{B_{1}}+\sigma_{B_{2}}\right) \rho \rho_{G_{1}}(1+2 \alpha)}{1-h_{R}(1-\theta) \rho_{f}}<\alpha, \tag{46}
\end{equation*}
$$

where $h_{0}$ and $h_{1}$ are as described in Lemmas 13 and 14, respectively.

Next we show that, for any fixed $h \in\left(0, h_{R}\right]$, there exists a triple ( $x^{h, i+1}, u^{h, i+1}, v^{h, i+1}$ ) satisfying (15) with $\left\|x^{h, i+1}\right\| \leq \rho_{i+1}$ for all $i=0,1, \ldots, N_{h}$. Let $B_{\alpha}$ denote the Euclidean ball in $R^{n}$ with center at the origin and radius $2 \alpha$. For any $x \in B_{\alpha}$, let $S_{j}(t, x)$ denote the nonempty set $\operatorname{SOL}\left(K, G_{j}(t, x)+F_{j}\right)$. Since $G_{j}$ is Lipschitz continuous on $\Omega$, we know that $G_{j}$ have linear growth on $\Omega$ in $x$; that is, for some positive constants $\rho_{G_{j}}$ and for all $(t, x) \in \Omega$,

$$
\begin{equation*}
\left\|G_{j}(t, x)\right\| \leq \rho_{G_{j}}(1+\|x\|) . \tag{47}
\end{equation*}
$$

By the linear growth assumption, for any $x \in B_{\alpha}$, we have

$$
\begin{align*}
\sup \left\{\|u\|: u \in S_{j}(t, x)\right\} & \leq \rho\left(1+\left\|G_{j}(t, x)\right\|\right) \\
& \leq \rho\left(1+\rho_{G_{j}}(1+\|x\|)\right) \\
& \leq \rho\left(1+\rho_{G_{j}}\right)(1+2 \alpha), \quad j=1,2 . \tag{48}
\end{align*}
$$

Define mappings $S^{i}$ from $B_{\alpha}$ to subset of $B_{\alpha}$ as follows: for any $x \in B_{\alpha}$,

$$
\begin{align*}
& S^{i}(x) \equiv\left(I-h f\left(t_{h, i+1}, \theta x^{h, i}+(1-\theta) x\right)\right)^{-1} \\
& \times {\left[x^{h, i}+h B_{1}\left(t_{h, i}, x^{h, i}\right) S_{1}\left(t_{h, i+1}, x\right)\right.}  \tag{49}\\
&\left.+h B_{2}\left(t_{h, i}, x^{h, i}\right) S_{2}\left(t_{h, i+1}, x\right)\right] .
\end{align*}
$$

Since $F_{1}$ and $F_{2}$ are upper semicontinuous with nonempty compact values such that $q_{i}+F_{i}(i=1,2)$ are pseudo monotone on $R^{n}$ for each $q_{i} \in G_{i}(\Omega)(i=1,2)$, it follows from Lemmas 3.3 and 3.4 in [19] that $\operatorname{SOL}\left(K, G_{1}(t, x)+\right.$ $\left.F_{1}\right)$ and $\operatorname{SOL}\left(K, G_{2}(t, x)+F_{2}\right)$ are nonempty, closed, and convex sets. By (48), we obtain that $\operatorname{SOL}\left(K, G_{1}(t, x)+F_{1}\right)$ and
$\operatorname{SOL}\left(K, G_{2}(t, x)+F_{2}\right)$ are compact and convex. Consider the map

$$
\begin{equation*}
(x, y) \longmapsto x^{h, i}+h B_{1}\left(t_{h, i}, x^{h, i}\right) x+h B_{2}\left(t_{h, i}, x^{h, i}\right) y . \tag{50}
\end{equation*}
$$

It is easy to see that this map is continuous. Therefore, by the Tychonoff theorem, we know that $S_{1}(t, x) \times S_{2}(t, x)$ is compact and so

$$
\begin{equation*}
x^{h, i}+h B_{1}\left(t_{h, i}, x^{h, i}\right) S_{1}\left(t_{h, i+1}, x\right)+h B_{2}\left(t_{h, i}, x^{h, i}\right) S_{2}\left(t_{h, i+1}, x\right) \tag{51}
\end{equation*}
$$

is compact. Since the mapping $\left(I-h f\left(t_{h, i+1}, \theta x^{h, i}+(1-\theta) \cdot\right)\right)^{-1}$ is a homeomorphism for all $h>0$ sufficiently small, it follows that $S^{i}(x)$ is a compact acyclic set. We need to show that $S^{i}(x)$ is a subset of $B_{\alpha}$. Let $\widetilde{x}$ be an arbitrary element in $S^{i}(x)$ and let $u \in S_{1}\left(t_{h, i+1}, x\right), v \in S_{2}\left(t_{h, i+1}, x\right)$ be such that

$$
\begin{align*}
\tilde{x}=x^{h, i}+h[ & f\left(t_{h, i+1}, \theta x^{i}+(1-\theta) \tilde{x}\right)+B_{1}\left(t_{h, i}, x^{h, i}\right) u \\
& \left.+B_{2}\left(t_{h, i}, x^{h, i}\right) v\right] . \tag{52}
\end{align*}
$$

From Lemma 13, we have

$$
\begin{equation*}
\left\|\widetilde{x}-x^{h, i}\right\| \leq h \frac{\rho_{f}\left(1+\left\|x^{h, i}\right\|\right)+\sigma_{B_{1}}\|u\|+\sigma_{B_{2}}\|v\|}{1-h(1-\theta) \rho_{f}} . \tag{53}
\end{equation*}
$$

By induction hypothesis and $\left\|x^{h, i}\right\| \leq \rho_{i} \leq \alpha$, one has

$$
\begin{equation*}
\|\widetilde{x}\| \leq \rho_{i}+h \frac{\rho_{f}\left(1+\rho_{i}\right)+\left(\sigma_{B_{1}}+\sigma_{B_{2}}\right) \rho \rho_{G_{1}}(1+2 \alpha)}{1-h(1-\theta) \rho_{f}}<2 \alpha \tag{54}
\end{equation*}
$$

Now we need to prove that the solution mapping $S_{1}\left(t_{h, i+1}, x\right)$ is upper semicontinuous. To prove the upper semicontinuity of $S_{1}\left(t_{h, i+1}, x\right)$, it suffices to show that $S_{1}\left(t_{h, i+1}, x\right)$ is closed. Suppose that $\left\{x_{n}\right\} \subset R^{n}$ is a sequence converging to $x_{0} \in R^{n}$ and $u_{n} \in S_{1}\left(t_{h, i+1}, x_{n}\right)$. Then the linear growth condition implies that $\left\{u_{n}\right\}$ is bounded and so it has a convergent subsequence with a limit $u_{0}$. Since $u_{n} \in S_{1}\left(t_{h, i+1}, x_{n}\right)$, there exists $u_{n}^{\prime} \in F_{1}\left(u_{n}\right)$ such that

$$
\begin{equation*}
\left\langle G_{1}\left(t_{h, i+1}, x_{n}\right)+u_{n}^{\prime}, u^{\prime}-u_{n}\right\rangle, \quad \forall u^{\prime} \in K . \tag{55}
\end{equation*}
$$

Since $F_{1}$ is upper semicontinuous on $R^{n}$ with compact values, it follows that there exists a subsequence of $\left\{u_{n}^{\prime}\right\}$, denoted again by $\left\{u_{n}^{\prime}\right\}$, such that $u_{n}^{\prime} \rightarrow u_{0}^{\prime} \in F_{1}\left(u_{0}\right)$. Letting $n \rightarrow \infty$, we have

$$
\begin{equation*}
\left\langle G_{1}\left(t_{h, i+1}, x_{0}\right)+u_{0}^{\prime}, u^{\prime}-u_{0}\right\rangle \geq 0, \quad \forall u^{\prime} \in K \tag{56}
\end{equation*}
$$

and so $u_{0} \in S_{1}\left(t_{h, i+1}, x_{0}\right)$. It follows that $S_{1}\left(t_{h, i+1}, x\right)$ is closed and so upper semicontinuous. In a similar way, we can prove that $S_{2}\left(t_{h, i+1}, x\right)$ is upper semicontinuous. Thus, we know that $S^{i}: B_{\alpha} \rightarrow B_{\alpha}$ is a closed set-valued mapping with compact acyclic values. By Lemma $8, S^{i}$ has a fixed point and so there exists a triple $\left(x^{h, i+1}, u^{h, i+1}, v^{h, i+1}\right)$ satisfying (15). Now
we show that $\left\|x^{h, i+1}\right\| \leq \rho_{i+1}$. In fact, by (40) and Lemma 7.2 in [1], one has

$$
\begin{equation*}
\left\|x^{h, i+1}\right\| \leq e^{T \psi_{x}}\left\|x^{0}\right\|+e^{T \psi_{x}}-1 \tag{57}
\end{equation*}
$$

The definition of $\rho_{i+1}$ implies that $\left\|x^{h, i+1}\right\| \leq \rho_{i+1}$. This completes the proof.

Let $\hat{x}^{h}(\cdot)$ be the continuous piecewise linear interpolant of the family $\left\{x^{h, i+1}\right\}, \hat{u}^{h}(\cdot)$ the constant piecewise interpolant of the family $\left\{u^{h, i+1}\right\}$, and $\widehat{v}^{h}(\cdot)$ the constant piecewise interpolant of the family $\left\{v^{h, i+1}\right\}$; that is,

$$
\begin{gather*}
\widehat{x}^{h}(t)=x^{h, i}+\frac{t-t_{i}}{h}\left(x^{h, i+1}-x^{h, i}\right), \quad \forall t \in\left[t_{h, i}, t_{h, i+1}\right], \\
\hat{u}^{h}(t)=u^{h, i+1}, \quad \forall t \in\left(t_{i}, t_{i+1}\right], \\
\widehat{v}^{h}(t)=v^{h, i+1}, \quad \forall t \in\left(t_{i}, t_{i+1}\right], \tag{58}
\end{gather*}
$$

for $i=0,1, \ldots, N_{h}$.
Theorem 16. Let $\left(f, B_{1}, B_{2}, G_{1}, G_{2}\right)$ satisfy conditions (A) and (B) and let $K \subset R^{n}$ be a nonempty, closed, and convex set. Suppose that $\operatorname{SOL}\left(K, q_{1}+F_{1}\right)$ and $\operatorname{SOL}\left(K, q_{2}+F_{2}\right)$ satisfy the linear growth properties. Then there exists a sequence $\left\{h_{n}\right\} \downarrow 0$ such that $\widehat{x}^{h_{n}} \rightarrow \hat{x}$ uniformly on $[0, T]$ and $\hat{u}^{h_{n}} \rightarrow \widehat{u}$ weakly in $L^{2}[0, T]$ with $\widehat{v}^{h_{n}} \rightarrow \widehat{v}$ weakly in $L^{2}[0, T]$. Furthermore, assume that $F_{1}(u)=\psi_{1}\left(E_{1} u\right), F_{2}(v)=\psi_{2}\left(E_{2} v\right), E_{j} \in$ $R^{m \times m}, j=1,2$ and

$$
\begin{equation*}
\psi_{j}: L^{2}\left([0, T], R^{m}\right) \rightrightarrows L^{2}\left([0, T], R^{m}\right), \quad j=1,2 \tag{59}
\end{equation*}
$$

are upper semicontinuous set-valued mappings with nonempty compact values and there exist constants $C_{1}, C_{2}$ such that, for any $h$ sufficiently small,

$$
\begin{equation*}
\left\|E_{1} u^{h, i+1}-E_{1} u^{h, i}\right\| \leq h C_{1}, \quad\left\|E_{2} v^{h, i+1}-E_{2} v^{h, i}\right\| \leq h C_{2} \tag{60}
\end{equation*}
$$

Then the limit $(\widehat{x}, \widehat{u}, \widehat{v})$ is a weak solution of the system (1).
Proof. By (31) and Lemma 14, we deduce that, for $h>$ 0 sufficiently small, there exists an $L_{x_{0}}>0$, which is independent of $h$, such that

$$
\begin{equation*}
\left\|x^{h, i+1}-x^{h, i}\right\| \leq L_{x_{0}} h, \quad i=0,1, \ldots, N_{h} . \tag{61}
\end{equation*}
$$

It follows from (58) that $\hat{x}^{h}$ is also Lipschitz continuous on $[0, T]$ and the Lipschitz constant is independent of $h$. Thus, there exists an $h_{0}>0$ such that the family of functions $\left\{\hat{x}^{h}\right\}\left(h \in\left(0, h_{0}\right]\right)$ is an equicontinuous family of functions. Let

$$
\begin{equation*}
\left\|\widehat{x}^{h}\right\|_{L^{\infty}}=\sup _{t \in[0, T]}\left\|\hat{x}^{h}(t)\right\| . \tag{62}
\end{equation*}
$$

From (58) and Lemma 14, we deduce that $\left\{\hat{x}^{h}\right\}$ is uniformly bounded. By using the Arzelá-Ascoli theorem, there exists a
sequence $\left\{h_{n}\right\}$ with $h_{n} \downarrow 0$ such that $\left\{\hat{x}^{h_{n}}\right\}$ converges in the supremum norm to a Lipschitz function $\widehat{x}$ on $[0, T]$. Since $\operatorname{SOL}\left(K, q_{1}+F_{1}\right)$ and $\operatorname{SOL}\left(K, q_{2}+F_{2}\right)$ satisfy the linear growth properties, it follows from Lemma 14 that $\left\{u^{h, i+1}\right\}$ is uniformly bounded in the $L^{\infty}$ norm on $[0, T]$. From (58), we know that $\left\{\widehat{u}^{h}\right\}$ is uniformly bounded in the $L^{\infty}$ norm on $[0, T]$, which means that there exists a scalar $\gamma>0$ such that

$$
\begin{equation*}
\left\|\widehat{u}^{h}\right\|_{L^{\infty}} \leq \gamma . \tag{63}
\end{equation*}
$$

Since $L^{2}[0, T]$ is a reflective Banach space, every bounded sequence has a weakly convergent subsequence and so there is a sequence $\left\{h_{n}\right\} \downarrow 0$ such that $\widehat{u}^{h_{n}} \rightarrow \widehat{u}$ weakly in $L^{2}[0, T]$. In a similar way, we obtain that $\widehat{v}^{h_{n}} \rightarrow \widehat{v}$ weakly in $L^{2}[0, T]$.

Next, we show that $(\widehat{x}, \widehat{u}, \widehat{v})$ is a weak solution of the system (1). By Lemma 11, it is sufficient to prove the following three assertions:
(i) for any $0 \leq s \leq t \leq T$

$$
\begin{align*}
& \widehat{x}(t)-\widehat{x}(s) \\
& =\int_{s}^{t}\left[f(\tau, \widehat{x}(\tau))+B_{1}(\tau, \widehat{x}(\tau)) \widehat{u}(\tau)\right.  \tag{64}\\
& \\
& \left.\quad+B_{2}(\tau, \widehat{x}(\tau)) \widehat{v}(\tau)\right] d \tau ;
\end{align*}
$$

(ii) there exist $u_{0}^{*} \in F_{1}(\widehat{u})$ and $v_{0}^{*} \in F_{2}(\widehat{v})$ such that, for all continuous functions: $u:[0, T] \rightarrow K$,

$$
\begin{align*}
& \int_{0}^{T}\left\langle G_{1}(t, \widehat{x}(t))+u_{0}^{*}(t), u(t)-\widehat{u}(t)\right\rangle d t \geq 0  \tag{65}\\
& \int_{0}^{T}\left\langle G_{2}(t, \widehat{x}(t))+u_{0}^{*}(t), u(t)-\widehat{v}(t)\right\rangle d t \geq 0
\end{align*}
$$

(iii) the initial condition $\widehat{x}(0)=x_{0}$.

Since

$$
\begin{align*}
& x^{h, i+1}-x^{h, i}=h[ f\left(t_{h, i+1}, \theta x^{h, i}+(1-\theta) x^{h, i+1}\right) \\
&\left.+B_{1}\left(t_{h, i}, x^{h, i}\right) u^{h, i+1}+B_{2}\left(t_{h, i}, x^{h, i}\right) v^{h, i+1}\right] \\
&=\int_{t_{h, i}}^{t_{h, i+1}}\left[f\left(\tau, \hat{x}^{h}(\tau)\right)+B_{1}\left(\tau, \hat{x}^{h}(\tau)\right) u^{h, i+1}\right. \\
&\left.\quad+B_{2}\left(\tau, \widehat{x}^{h}(\tau)\right) v^{h, i+1}\right] d \tau+h^{2} \xi \tag{66}
\end{align*}
$$

where

$$
\begin{equation*}
\|\xi\| \leq L_{f}+L_{f} L_{x}+L_{B_{1}} \psi_{u}+L_{B_{2}} \psi_{u} \tag{67}
\end{equation*}
$$

$L_{x}$ and $\psi_{u}$ are the same as described in Theorem 7.1 in [1]; it follows that, for any $0 \leq s \leq t \leq T$,

$$
\begin{align*}
x^{h}(t)-x^{h}(s)=\int_{s}^{t}[ & f\left(\tau, \hat{x}^{h}(\tau)\right)+B_{1}\left(\tau, \hat{x}^{h}(\tau)\right) \hat{u}^{h}(\tau) \\
& \left.+B_{2}\left(\tau, \hat{x}^{h}(\tau)\right) \widehat{v}^{h}(\tau)\right] d \tau+O(h) . \tag{68}
\end{align*}
$$

By a similar proof to that in Theorem 7.1 of [1], we can obtain that

$$
\begin{align*}
\lim _{h \rightarrow 0} \int_{s}^{t} f\left(\tau, \widehat{x}^{h}(\tau)\right) d \tau & =\int_{s}^{t} f(\tau, \widehat{x}(\tau)) d \tau \\
\lim _{h \rightarrow 0} \int_{s}^{t} B_{1}\left(\tau, \widehat{x}^{h}(\tau)\right) \widehat{u}^{h}(\tau) d \tau & =\int_{s}^{t} B_{1}(\tau, \widehat{x}(\tau)) \widehat{u}(\tau) d \tau \\
\lim _{h \rightarrow 0} \int_{s}^{t} B_{2}\left(\tau, \widehat{x}^{h}(\tau)\right) \hat{v}^{h}(\tau) d \tau & =\int_{s}^{t} B_{2}(\tau, \widehat{x}(\tau)) \widehat{v}(\tau) d \tau \tag{69}
\end{align*}
$$

Noting the proof of Theorem 7.1 in [1], we have $\hat{x}^{h_{n}} \rightarrow \hat{x}$ and $E_{1} \widehat{u}^{h_{n}} \rightarrow E_{1} \widehat{u}$ as $n \rightarrow \infty$. Let $u_{n}^{*} \in \psi_{1}\left(E_{1} \hat{u}^{h_{n}}\right)$. Since $\psi_{1}$ is upper semicontinuous with nonempty compact values, there exists a subsequence of $\left\{u_{n}^{*}\right\}$, denoted again by $\left\{u_{n}^{*}\right\}$, such that $u_{n}^{*} \rightarrow u_{0}^{*}$ with $u_{0}^{*} \in \psi_{1}\left(E_{1} \widehat{u}\right)$. This implies that, for any continuous functions: $\widetilde{u}:[0, T] \rightarrow K$,

$$
\begin{align*}
\lim _{n \rightarrow \infty} & \int_{0}^{T}\left\langle G_{1}\left(t, \widehat{x}^{h_{n}}(t)\right)+u_{n}^{*}(t), \tilde{u}(t)-\widehat{u}^{h_{n}}(t)\right\rangle d t \\
& =\int_{0}^{T}\left\langle G_{1}(t, \widehat{x})+u_{0}^{*}(t), \tilde{u}-\widehat{u}\right\rangle d t \tag{70}
\end{align*}
$$

Then, in a similar way of Theorem 7.1 in [1], we can prove that

$$
\begin{equation*}
\int_{0}^{T}\left\langle G_{1}(t, \widehat{x})+u_{0}^{*}(t), \tilde{u}-\widehat{u}\right\rangle d t \geq 0 \tag{71}
\end{equation*}
$$

The proof in the case $j=2$ is similar and so we omit it here. This completes the proof.

Remark 17. Theorem 16 generalizes Theorem 7.1 in [1] from the differential variational inequality to the system of differential set-valued variational inequalities.

## Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

## Acknowledgments

The authors are grateful to the editor and the referees for their valuable comments and suggestions. This work was supported by the National Natural Science Foundation of China (11171237) and the Key Program of NSFC (Grant no. 70831005).

## References

[1] J.-S. Pang and D. E. Stewart, "Differential variational inequalities," Mathematical Programming A, vol. 113, no. 2, pp. 345-424, 2008.
[2] J.-P. Aubin and A. Cellina, Differential Inclusions, Springer, New York, NY, USA, 1984.
[3] B. Brogliato, A. Daniilidis, C. Lemaréchal, and V. Acary, "On the equivalence between complementarity systems, projected systems and differential inclusions," Systems \& Control Letters, vol. 55, no. 1, pp. 45-51, 2006.
[4] B. Brogliato and D. Goeleven, "Well-posedness, stability and invariance results for a class of multivalued Lure dynamical systems," Nonlinear Analysis. Theory, Methods \& Applications A, vol. 74, no. 1, pp. 195-212, 2011.
[5] B. Brogliato and W. P. M. H. Heemels, "Observer design for Lur'e systems with multivalued mappings: a passivity approach," IEEE Transactions on Automatic Control, vol. 54, no. 8, pp. 1996-2001, 2009.
[6] B. Brogliato and L. Thibault, "Existence and uniqueness of solutions for non-autonomous complementarity dynamical systems," Journal of Convex Analysis, vol. 17, no. 3-4, pp. 961990, 2010.
[7] M. K. Camlibel, L. Iannelli, and F. Vasca, "Passivity and complementarity," Mathematical Programming, 2013.
[8] M. K. Çamlıbel, W. P. M. H. Heemels, and J. M. Schumacher, "Consistency of a time-stepping method for a class of piecewiselinear networks," IEEE Transactions on Circuits and Systems I, vol. 49, no. 3, pp. 349-357, 2002.
[9] M. K. Çamlıbell, W. P. M. H. Heemels, and J. M. Schumacher, "On linear passive complementarity systems," European Journal of Control, vol. 8, pp. 220-237, 2002.
[10] L. Han and J.-S. Pang, "Non-Zenoness of a class of differential quasi-variational inequalities," Mathematical Programming A, vol. 121, no. 1, pp. 171-199, 2010.
[11] W. P. M. H. Heemels, J. M. Schumacher, and S. Weiland, "Linear complementarity systems," SIAM Journal on Applied Mathematics, vol. 60, no. 4, pp. 1234-1269, 2000.
[12] W. P. M. H. Heemels, J. M. Schumacher, and S. Weiland, "Projected dynamical systems in a complementarity formalism," Operations Research Letters, vol. 27, no. 2, pp. 83-91, 2000.
[13] X.-s. Li, N.-j. Huang, and D. O'Regan, "Differential mixed variational inequalities in finite dimensional spaces," Nonlinear Analysis. Theory, Methods \& Applications A, vol. 72, no. 9-10, pp. 3875-3886, 2010.
[14] A. Mandelbaum, "The dynamic complementarity problem," Unpublished Manuscript, 1989.
[15] J.-S. Pang and J. Shen, "Strongly regular differential variational systems," IEEE Transactions on Automatic Control, vol. 52, no. 2, pp. 242-255, 2007.
[16] P. Song, J.-S. Pang, and V. Kumar, "A semi-implicit timestepping model for frictional compliant contact problems," International Journal for Numerical Methods in Engineering, vol. 60, no. 13, pp. 2231-2261, 2004.
[17] D. E. Stewart, "Uniqueness for index-one differential variational inequalities," Nonlinear Analysis. Hybrid Systems, vol. 2, no. 3, pp. 812-818, 2008.
[18] A. U. Raghunathan, J. R. Pérez-Correa, E. Agosin, and L. T. Biegler, "Parameter estimation in metabolic flux balance models for batch fermentation-formulation and solution using differential variational inequalities," Annals of Operations Research, vol. 148, pp. 251-270, 2006.
[19] X. Wang and N.-J. Huang, "Differential vector variational inequalities in finite-dimensional spaces," Journal of Optimization Theory and Applications, vol. 158, no. 1, pp. 109-129, 2013.
[20] W. Rudin, Real and Complex Analysis, McGraw-Hill Book, New York, NY, USA, 2nd edition, 1974.
[21] L. Górniewicz, Topological Fixed Point Theory of Multivalued Mappings, vol. 495, Kluwer Academic Publishers, Dordrecht, The Netherlands, 1999.


Advances in Operations Research $-$


The Scientific World Journal


Advances in
Decision Sciences
= -


## Hindawi

Submit your manuscripts at
http://www.hindawi.com


Mathematical Problems in Engineering


Journal of Function Spaces
$\underline{=}$



International Journal of Differential Equations 5


