

Research Article **Adjoining a Constant Function to** *n***-Dimensional Chebyshev Space**

Mansour Alyazidi-Asiry

Department of Mathematics, College of Sciences, King Saud University, P.O. Box 2455, Riyadh 11451, Saudi Arabia

Correspondence should be addressed to Mansour Alyazidi-Asiry; yazidi@ksu.edu.sa

Received 7 April 2016; Accepted 26 July 2016

Academic Editor: Giuseppe Marino

Copyright © 2016 Mansour Alyazidi-Asiry. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

This paper is concerned with extending a Chebyshev system of n continuous nonconstant functions into a set of n + 1 functions including a constant function. Necessary and sufficient conditions for the new set to be a Chebyshev system are discussed and some results are obtained.

1. Introduction

Most of the material in this section and Section 2 can be found in any standard book in approximation theory and related topics; see, for example, [1–5]. The finite set of functions $\{g_1, \ldots, g_n\} \in C[a, b]$ is called a Chebyshev system on [a, b] if it is linearly independent and $D\begin{pmatrix} g_1, \ldots, g_n\\ x_1, \ldots, x_n \end{pmatrix} = Det[g_i(x_j)] \neq 0$, $i, j = 1, \ldots, n$, for all $\{x_j\}_{j=1}^n$ such that $a \leq x_1 < x_2 < \cdots < x_n \leq b$, and the *n*-dimensional subspace $G = \langle g_1, \ldots, g_n \rangle$ of C[a, b] will be called a Chebyshev subspace or Haar subspace. Using the continuity of the determinant, it can be shown that the sign of the determinant is constant (see [6]), so we will assume that the determinant is always positive throughout this paper (replace g_1 by $-g_1$ if necessary). If each g_i is continuously differentiable function on [a, b], $i = 1, \ldots, n$ and $a \leq x_1 \leq x_2 \leq \cdots \leq x_n \leq b$, then the determinant $D^*\begin{pmatrix} g_1, \ldots, g_n\\ x_1, \ldots, x_n \end{pmatrix}$ is defined as follows:

$$D^{*}\begin{pmatrix} g_{1}, \dots, g_{n} \\ x_{1}, \dots, x_{n} \end{pmatrix} = \begin{bmatrix} g_{1}(t_{1}) & \cdots & g_{n}(t_{1}) \\ g_{1}'(t_{1}) & \cdots & g_{n}'(t_{1}) \\ \vdots & & \vdots \\ g_{1}^{(r_{1}-1)}(t_{1}) & \cdots & g_{n}^{(r_{1}-1)}(t_{1}) \\ \vdots & & \vdots \\ g_{1}(t_{p}) & \cdots & g_{n}(t_{p}) \\ \vdots & & \vdots \\ g_{1}^{(r_{p}-1)}(t_{p}) & \cdots & g_{n}^{(r_{p}-1)}(t_{p}) \end{bmatrix}, \quad (1)$$

where x_i is repeated r_i times, i = 1, ..., p, $a \le t_1 < t_2 < \cdots < t_p \le b$, and $\{t_1, t_2, ..., t_p\} = \{x_1, x_2, ..., x_n\}$. The set of functions $\{g_1, ..., g_n\}$ is called an extended Chebyshev system on [a, b] if $D^* \begin{pmatrix} g_1, ..., g_n \\ x_1, ..., x_n \end{pmatrix} > 0$, and the *n*-dimensional subspace $G = \langle g_1, ..., g_n \rangle$ of C[a, b] will be called an extended Chebyshev subspace.

In this paper we will consider the following problem.

If $G = \langle g_1, \ldots, g_n \rangle$ is a Chebyshev subspace of C[a, b] such that $1 \notin G$ then what property must G have so that the subspace $U = \langle u_0, u_1, \ldots, u_n \rangle$ is (n + 1)-dimensional Chebyshev subspace of C[a, b], where $u_0 = 1$, $u_i = g_i$, $i = 1, \ldots, n$? We will present some results in Section 3 which give a partial answer to this question.

2. Preliminary

Let $G = \langle g_1, \dots, g_n \rangle$ be a Chebyshev subspace of C[a, b] and let $\{x_j\}_{j=1}^{n+1}$ be a set of points such that $a \le x_1 < x_2 < \dots < x_{n+1} \le b$, and then for any $g \in G$ we have

$$0 = D\begin{pmatrix} g, g_1, \dots, g_n \\ x_1, \dots, x_{n+1} \end{pmatrix} = \sum_{i=1}^{n+1} (-1)^{i+1} \Delta_i g(x_i), \qquad (2)$$

where

$$\Delta_1 = D\begin{pmatrix} g_1, \dots, g_n \\ x_2, \dots, x_{n+1} \end{pmatrix},$$

$$\Delta_{n+1} = D\begin{pmatrix} g_1, \dots, g_n \\ x_1, \dots, x_n \end{pmatrix},$$

$$\Delta_i = D\begin{pmatrix} g_1, \dots, g_n \\ x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_{n+1} \end{pmatrix},$$

$$i = 2, \dots, n.$$

(3)

Taking $\theta_i = \Delta_i / \sum_{j=1}^{n+1} \Delta_j$ then $\theta_i > 0$ for all i = 1, ..., n+1with $\sum_{i=1}^{n+1} \theta_i = 1$ and $\sum_{i=1}^{n+1} (-1)^i \theta_i g(x_i) = 0$ for every $g \in G$.

This discussion proves the existence part of the following lemma.

Lemma 1. Let $G = \langle g_1, \ldots, g_n \rangle$ be a Chebyshev subspace of C[a,b] and let $\{x_j\}_{j=1}^{n+1}$ be a set of points such that $a \le x_1 < x_2 < \cdots < x_{n+1} \le b$, and then there exists a unique set of positive numbers $\{\theta_j\}_{j=1}^{n+1}$ with $\sum_{i=1}^{n+1} \theta_i = 1$ such that $\sum_{i=1}^{n+1} (-1)^i \theta_i g(x_i) = 0$ for every $g \in G$.

Proof. We only need to prove the uniqueness part of this lemma. Suppose that there are two sets of positive real numbers $\{\theta_j\}_{j=1}^{n+1}$ and $\{\lambda_j\}_{j=1}^{n+1}$ with $\sum_{i=1}^{n+1} \theta_i = \sum_{i=1}^{n+1} \lambda_i = 1$ such that

$$\sum_{i=1}^{n+1} (-1)^{i} \theta_{i} g(x_{i}) = \sum_{i=1}^{n+1} (-1)^{i} \lambda_{i} g(x_{i}) = 0$$
(4)
for every $g \in G$.

Since *G* is a Chebyshev subspace, then for each $k \in \{2, ..., n+1\}$ there exists a unique function $h^{(k)} \in G$ such that $h^{(k)}(x_1) = 1$ and $h^{(k)}(x_1) = 0$, $l \in \{2, ..., n+1\} \setminus \{k\}$ (see [6]), and from (4) we have

$$-\theta_{1} + (-1)^{k} \theta_{2} h^{(k)} (x_{k}) = 0,$$

$$-\lambda_{1} + (-1)^{k} \lambda_{2} h^{(k)} (x_{k}) = 0,$$

(5)

where k = 2, ..., n + 1.

Clearly $h^{(k)}(x_k) \neq 0$, and therefore (5) yield

$$\frac{\theta_k}{\theta_1} = \frac{\lambda_k}{\lambda_1}, \quad k = 2, \dots, n+1.$$
(6)

Hence $(1/\theta_1) \sum_{k=2}^{n+1} \theta_k = (1/\lambda_1) \sum_{k=2}^{n+1} \lambda_k \Rightarrow (1-\theta_1)/\theta_1 = (1-\lambda_1)/\lambda_1 \Rightarrow \theta_1 = \lambda_1$, and, by (6), $\theta_i = \lambda_i$, i = 2, ..., n+1, and the proof is complete.

3. The Main Result

We start this section by the following theorem.

Theorem 2. Let $G = \langle g_1, \ldots, g_n \rangle$, where $\{g_i\}_{i=1}^n \in C[a,b]$ is a Chebyshev system on [a,b]. Then $\{g_0 = 1, g_1, \ldots, g_n\}$ is a Chebyshev system on [a,b] if and only if, for each set of points $\{t_i\}_{i=0}^n$ such that $a \leq t_0 < t_1 < \cdots < t_n \leq b$ and the corresponding set of positive real numbers $\{\theta_i\}_{i=0}^n$ with $\sum_{i=0}^{n} \theta_i = 1 \text{ satisfying } \sum_{i=0}^{n} (-1)^i \theta_i g(t_i) = 0 \text{ for every } g \in G, \text{ we have}$

$$\sum_{i\in I} \theta_i \neq \sum_{j\in J} \theta_j,\tag{7}$$

where $I = \{i \in A : i \text{ is odd}\}, A = \{0, 1, ..., n\}, and J = A \setminus I.$

Proof. Let $\{t_i\}_{i=0}^n$ be a set of points such that $a \le t_0 < t_1 < \cdots < t_n \le b$ and the corresponding set of positive real numbers $\{\theta_j\}_{j=0}^n$ with $\sum_{i=0}^n \theta_i = 1$ satisfying $\sum_{i=0}^n (-1)^i \theta_i g(t_i) = 0$ for every $g \in G$, where $G = \langle g_1, \ldots, g_n \rangle$ is a Chebyshev subspace of C[*a*, *b*]. From Lemma 1 $\theta_i = \Delta_i/d$, where $d = \sum_{j=0}^n \Delta_j$ and $\Delta_i = D\left(\frac{g_1, \ldots, g_n}{t_0, \ldots, t_{i-1}, t_{i+1}, \ldots, t_n}\right)$, $i = 0, \ldots, n$. Hence

$$D\begin{pmatrix} g_0, g_1, \dots, g_n \\ t_0, \dots, t_n \end{pmatrix} = Det \begin{bmatrix} 1 & g_1(t_0) & \cdots & g_n(t_0) \\ 1 & g_1(t_1) & \cdots & g_n(t_1) \\ \vdots & \vdots & \dots & \vdots \\ 1 & g_1(t_n) & \cdots & g_n(t_n) \end{bmatrix},$$

$$= \sum_{i=0}^n (-1)^i \Delta_i = \sum_{i=0}^n (-1)^i d\theta_i$$

$$= d \left[\sum_{i \in I} \theta_i - \sum_{j \in J} \theta_j \right] \neq 0$$
(8)

if and only if $\sum_{i \in I} \theta_i \neq \sum_{j \in J} \theta$, where *I* and *J* are as defined above, and the theorem is proved.

Assumption 3. Let $g_i \in C^1[a, b]$ for all i = 1, ..., n and let $G = \langle g_1, ..., g_n \rangle$ be a Chebyshev subspace of C[a, b]. We say that *G* satisfies Assumption 3 if, for each nontrivial element *g* of *G*, *g'* can have at most n - 1 distinct zeros on (a, b). That is, if $g'(x_i) = 0$, $a < x_1 < x_2 < \cdots < x_k < b$, and $k \ge n$, then *g* is identically zero.

Theorem 4. Suppose $g_i \in C^1[a, b]$ for all i = 1, ..., n and $G = \langle g_1, ..., g_n \rangle$ is a Chebyshev subspace of C[a, b]. If G satisfies Assumption 3, then $\{g_0 = 1, g_1, ..., g_n\}$ is a Chebyshev system on [a, b].

Proof. If there is a function $\overline{h} = \overline{\alpha}_0 + \overline{\alpha}_1 g_1 + \dots + \overline{\alpha}_n g_n$ such that $\overline{h}(t_i) = 0$ at some set of points $a \le t_0 < t_1 < \dots < t_k \le b$; then by Rolle's theorem there exits a set of points $\{x_j\}_{j=1}^k, x_j \in (t_{j-1}, t_j)$, such that $(\overline{h})'(x_j) = 0 = (\overline{g})'(x_j)$, $j = 1, \dots, k$, where $\overline{g} = \overline{\alpha}_1 g_1 + \dots + \overline{\alpha}_n g_n \in G$. So if $k \ge n$ then $\overline{g} = 0$, and hence $\overline{h} = \overline{\alpha}_0 \Rightarrow \overline{h} = \overline{\alpha}_0 = 0$ and this shows that $\{g_0 = 1, g_1, \dots, g_n\}$ is a Chebyshev system on [a, b].

When n = 1, $u \in C[a, b]$, and $G = \langle u \rangle$ is a Chebyshev subspace of C[a, b] if $u(x) \neq 0$ for all $x \in [a, b]$. For this special case we have the following results which can be found in [3].

Proposition 5. Let $u \in C[a,b]$, and then $H = \langle 1, u \rangle$ is a Chebyshev subspace of C[a,b] if and only if u is strictly monotonic function on [a,b].

Remark 6. If *u* is an even function on [-a, a], a > 0, then $\{1, u\}$ is not a Chebyshev system on [-a, a], that is, since $D\begin{pmatrix} 1, u\\ -t, t \end{pmatrix} = 0, \forall t \in (0, a].$

Remark 7. Assumption 3 is not a necessary condition for Theorem 4 as the following example illustrates.

Example 8. Take $u = e^{x^3}$ and then $\{1, u\}$ is a Chebyshev system on [-a, a], a > 0 although u'(0) = 0.

Finally, we will give an example of a set of continuously differentiable functions $\{g_i\}_{i=1}^n$ which is an extended Chebyshev system on [a, b] and $\{g_0 = 1, g_1, \dots, g_n\}$ is a Chebyshev system on [a, b] but not an extended Chebyshev system.

Example 9. Let $g_1 = x$ and $g_2 = -\cos x$, then $D^* \begin{pmatrix} g_1, g_2 \\ t,t \end{pmatrix} = t \sin t + \cos t > 0$, $\forall t \in [0, \pi/2]$, and hence $G = \langle g_1, g_2 \rangle$ is an extended Chebyshev system on $[0, \pi/2]$. And if $g \in G$ then g' can have at most one zero on $[0, \pi/2]$; this means that *G* satisfies Assumption 3 and by Theorem 4 $\{1, g_1, g_2\}$ is a Chebyshev system on $[0, \pi/2]$. Taking $v(x) = -\pi/2 + x + \cos x$, then $v(\pi/2) = v'(\pi/2) = v''(\pi/2) = 0$; that is, $\{1, g_1, g_2\}$ is not an extended Chebyshev system on $[0, \pi/2]$.

Competing Interests

The author declares no competing interests.

Acknowledgments

This research was supported by King Saud University, Deanship of Scientific Research, College of Science Research Center.

References

- E. W. Cheney, *Introduction to Approximation Theory*, McGraw-Hill, New York, NY, USA, 1966.
- [2] S. Karlin and W. Studden, *Tchebycheff Systems, with Applications in Analysis and Statistics*, Interscience, New York, NY, USA, 1966.
- [3] R. Zielke, Discontinuous Cebysev Systems, vol. 707 of Lecture Notes in Mathematics, Springer, Berlin, Germany, 1979.
- [4] R. Haverkamp and R. Zielke, "On the embedding problem for Čebyšev systems," *Journal of Approximation Theory*, vol. 30, no. 2, pp. 155–156, 1980.
- [5] R. A. Zalik, "Existence of tchebycheff extensions," Journal of Mathematical Analysis and Applications, vol. 51, pp. 68–75, 1975.
- [6] G. Nurnberger, Approximation by Spline Functions, Springer, Berlin, Germany, 1989.





World Journal







Applied Mathematics



Journal of Probability and Statistics



International Journal of Differential Equations





Journal of Complex Analysis



International Journal of Mathematics and **Mathematical** Sciences





Hindawi

Submit your manuscripts at http://www.hindawi.com

> Mathematical Problems in Engineering



Journal of **Function Spaces**



Abstract and **Applied Analysis**



International Journal of Stochastic Analysis



Discrete Dynamics in Nature and Society

