# Numerical Investigation of Fractional-Order Differential Equations via $\varphi$-Haar-Wavelet Method 

F. M. Alharbi, ${ }^{1}$ A. M. Zidan $\mathbb{D}^{2},{ }^{2,3}$ Muhammad Naeem ${ }^{(1)},{ }^{1}$ Rasool Shah $\left(\mathbb{D},{ }^{4}\right.$ and Kamsing Nonlaopon (1) ${ }^{5}$<br>${ }^{1}$ Deanship of Common First Year, Umm Al-Qura University, Makkah, Saudi Arabia<br>${ }^{2}$ Department of Mathematics, College of Science, King Khalid University, P.O. Box 9004, Abha 61413, Saudi Arabia<br>${ }^{3}$ Department of Mathematics, Faculty of Science, Al-Azhar University, Assiut 71511, Egypt<br>${ }^{4}$ Department of Mathematics, Abdul Wali khan university, Mardan 23200, Pakistan<br>${ }^{5}$ Department of Mathematics, Faculty of Science, Khon Kaen University, Khon Kaen 40002, Thailand

Correspondence should be addressed to Kamsing Nonlaopon; nkamsi@kku.ac.th
Received 18 April 2021; Accepted 9 July 2021; Published 28 July 2021
Academic Editor: Fu-Dong Ge
Copyright © 2021 F. M. Alharbi et al. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.


#### Abstract

In this paper, we propose a novel and efficient numerical technique for solving linear and nonlinear fractional differential equations (FDEs) with the $\varphi$-Caputo fractional derivative. Our approach is based on a new operational matrix of integration, namely, the $\varphi$ -Haar-wavelet operational matrix of fractional integration. In this paper, we derived an explicit formula for the $\varphi$-fractional integral of the Haar-wavelet by utilizing the $\varphi$-fractional integral operator. We also extended our method to nonlinear $\varphi$-FDEs. The nonlinear problems are first linearized by applying the technique of quasilinearization, and then, the proposed method is applied to get a numerical solution of the linearized problems. The current technique is an effective and simple mathematical tool for solving nonlinear $\varphi$-FDEs. In the context of error analysis, an exact upper bound of the error for the suggested technique is given, which shows convergence of the proposed method. Finally, some numerical examples that demonstrate the efficiency of our technique are discussed.


## 1. Introduction

Fractional differential equations are used to describe a wide range of phenomena in natural science, and because of its numerous applications in physical, chemical, and biological sciences, fractional calculus has captivated the scientific community. Several researchers have recently focused their attention on the concept of the fractional derivative. The fractional derivative is introduced in fractional calculus through the fractional integral. Riemann, Liouville, Caputo, Hadamard, Grunwald, and Letinkow are the pioneers in this field, having contributed and published extensively on the subject. The nonlinear fractional Schrodinger equations with the Riesz space and the Caputo time-fractional derivatives are studied using the finite difference/spectral-Galerkin method in [1]. For the Higgs boson equation in the de Sitter spacetime, a finite difference/Galerkin spectral scheme was introduced in
[2] which retains the discrete energy dissipation property. For the two-dimensional fractional wave equation with the Weyl space-fractional operators, Ref. [3] proposes a highorder compact difference method with fourth-order precision in space and second order in time. Explicit solutions to differential equations of complex fractional orders with respect to functions and continuous variable coefficients are determined in [4]. Different types of fractional derivatives have appeared in the literature that strengthen and generalize the classical fractional operators defined by the aforementioned authors [5, 6]. Katugampola recently discovered a new type of fractional integral operator which encompasses the Riemann-Liouville and Hadamard operators in a single form [7, 8]. Moreover, several other fractional operators are being introduced to date. Due to a wide range of definitions for fractional-order integrals and derivatives [9-11], the idea of a fractional derivative of one function with respect to
another function emerged. This class of fractional operators depends on a kernel function and unifies many definitions of fractional operators. Almeida used the idea of fractional derivatives in the Caputo sense and introduced the $\varphi$-Caputo fractional derivative of one function with respect to some other function [12]. The proper choice of a trial function helps in the modeling of physical phenomenon and makes the approach more suitable from the application point of view [13, 14].

Wavelet analysis is a well-known and widely used mathematical method in engineering and other sciences [15, 16]. Wavelets are made up of function expressions that have been extended into a sum of basic functions. A mother wavelet function is translated and compressed to obtain these basic functions. As a result, it inherits properties of locality and smoothness, making it simple to research the properties of integer and locality during the process of expressing functions. Wavelets have sparked a lot of interest in using them to solve classical ordinary and partial differential equations numerically. Researchers have recently succeeded in extending several standard wavelet methods to numerical solutions for fractional differential equations. Numerical integration and numerical solutions of fractional ordinary and fractional partial differential equations are some of the other applications of wavelet methods in applied mathematics. So, for now, wavelets such as the Haar-wavelet, B-spline, Daubechies, and Legendre wavelet are used [17-21]. In Ref. [22], the Genocchi wavelet-like operational matrix was used together with the collocation method to solve nonlinear FDEs. For solving fractional integrodifferential equations, the Jacobi wavelet operational matrix of fractional integration is constructed and utilized in [23]. The Haar-wavelet is a simple form of orthonormal wavelets with compact support and has been used by many researchers. The Haar-wavelet family consisted of rectangular functions. It also includes the lower member of the Daubechies wavelet family, which is suitable for computer implementation. The Haarwavelets are used to transform a fractional differential equation into an algebraic structure of finite variables [24-27].

For modeling different physical problems, it is difficult to pick the right operator. Therefore, generalized operators of fractional order should be developed for which classical operators are special cases. An effective way to deal with such a variety is to merge these definitions into one by considering fractional derivatives of function $f$ with respect to another function $\varphi$. The Riemann-Liouville operators of fractional order are generalized by introducing the fractional-order differentiation and integration of a function by another function [28, 29]. In [12, 30], Almeida defined the $\varphi$-Caputo fractional differential and integral operators and discussed its characteristics. The contribution made by Almeida et al. plays a pivotal role in putting together a wide range of fractional operators. Moreover, recent work on the $\varphi$-Caputo derivative indicates that $\varphi$-Caputo fractional differential-based mathematical models are more flexible and provide felicitous results in many situations. In order to evaluate the growth of the world population, Almeida [12] implemented the $\varphi$ Caputo derivative and illustrated that the appropriate selection of a fractional operator determines the model's precision. Using fixed-point theorems, Almeida et al. in [13]
investigated the existence and uniqueness of a solution for nonlinear FDEs involving a $\varphi$-Caputo derivative. Almeida et al. in [31] introduced the $\varphi$-shifted Legendre polynomials for solving fractional oscillation equations containing the $\varphi$ Caputo derivative of fractional order. We therefore see the theory of $\varphi$-FDEs as a promising field for further study. In this paper, taking motivation by the work cited above, we developed a new numerical method for solving linear and nonlinear boundary value problems in $\varphi$-FDEs.

The rest of the paper is organized as follows: We start Section 2 with an overview of the fractional calculus followed by a discussion of the classical Haar-wavelet and an approximation of the functions by the Haar-wavelet. In Section 3, we developed the $\varphi$-Haar operational matrix of fractionalorder integration of the Haar-wavelet and then utilize it for a numerical solution of the $\varphi$-FDEs. In Section 3.1, the error estimate of the developed technique is discussed in depth. Section 4 is devoted to some numerical results and figures that show the precision and effectuality of the developed technique. Finally, a conclusion is given in the last section.

## 2. Preliminaries

Here, we present some vital definitions of $\varphi$-fractional operators and their basic properties which will be used in the subsequent sections of the paper.

Let the function $f:[\alpha, \beta] \longrightarrow \mathbb{R}$ be integrable, $\rho$ a positive real number, $n$ a natural number, and $\varphi \in C^{1}([\alpha, \beta])$ an increasing function such that $\varphi^{\prime}(\zeta) \neq 0 \forall \zeta \in[\alpha, \beta]$.

Definition 1. The Caputo fractional derivative of a function $f$ is defined by

$$
\begin{equation*}
{ }^{C} D_{\alpha}^{\rho} f(\zeta)=\frac{1}{\Gamma(n-\rho)} \int_{\alpha}^{\zeta}[\zeta-\mathfrak{J}]^{n-\rho-1}\left(\frac{d}{d \mathfrak{I}}\right)^{n} f(\mathfrak{J}) d \mathfrak{I} \tag{1}
\end{equation*}
$$

where $\zeta \in[\alpha, \beta], \rho \in \mathbb{R}^{+}$, and $n=\lceil\rho\rceil$.
Definition 2 (see [9,30, 32]). The $\varphi$-Riemann-Liouvile ( $\varphi$-RL) integration operator of fractional-order $\rho$ of a function $f(\zeta)$ is defined as follows:

$$
\begin{equation*}
\mathscr{J}_{\alpha}^{\rho, \varphi} f(\zeta)=\frac{1}{\Gamma(\rho)} \int_{\alpha}^{\zeta} \varphi^{\prime}(\mathfrak{J})[\varphi(\zeta)-\varphi(\mathfrak{J})]^{\rho-1} f(\mathfrak{J}) d \mathfrak{J} \tag{2}
\end{equation*}
$$

The $\varphi$-RL derivative operator of fractional-order $\rho$ of the function $f(\zeta)$ is defined as follows:

$$
\begin{align*}
D_{\alpha}^{\rho, \varphi} f(\zeta)= & \left(\frac{1}{\varphi^{\prime}(\zeta)} \frac{d}{d \zeta}\right)^{n} \mathscr{J}_{\alpha}^{n-\rho, \varphi} f(\zeta) \\
= & \frac{1}{\Gamma(n-\rho)}\left(\frac{1}{\varphi^{\prime}(\zeta)} \frac{d}{d \zeta}\right)^{n}  \tag{3}\\
& \cdot \int_{\alpha}^{\zeta} \varphi^{\prime}(\mathfrak{\Im})[\varphi(\zeta)-\varphi(\mathfrak{J})]^{n-\rho-1} f(\mathfrak{J}) d \mathfrak{I}
\end{align*}
$$

where $n=\lfloor\rho\rfloor+1$.

Definition 3 (see [12]). Let $\rho$ be a positive real number, $n$ a natural number, and $f, \varphi \in C^{n}([\alpha, \beta])$ such that $\varphi$ is increasing and $\varphi^{\prime}(\zeta) \neq 0 \forall \zeta \in[\alpha, \beta]$. The $\varphi$-Caputo differential operator of fractional-order $\rho$ is defined by

$$
\begin{equation*}
{ }^{C} D_{\alpha}^{\rho, \varphi} f(\zeta)=\frac{1}{\Gamma(n-\rho)} \int_{\alpha}^{\zeta} \varphi^{\prime}(\mathfrak{J})[\varphi(\zeta)-\varphi(\mathfrak{J})]^{n-\rho-1} D^{n, \varphi} f(\mathfrak{J}) d \mathfrak{I}, \tag{4}
\end{equation*}
$$

where $f_{\varphi}^{[n]}(\zeta)=\left(\left(1 / \varphi^{\prime}(\zeta)\right)(\mathrm{d} / d \zeta)\right)^{n} f(\zeta), n=\lfloor\rho\rfloor+1$ if $\rho \notin \mathbb{N}$, whereas $n=\rho$ if $\rho \in \mathbb{N}$.

Remark 4. For particular choices of $\varphi(\zeta)$, these operators are reduced to the following given operators of the fractional order:
(i) $\varphi(\zeta)=\zeta$ refer to the classical RL and Caputo fractional operators
(ii) $\varphi(\zeta)=\ln (\zeta)$ refer to the classical Hadamard and Caputo-Hadamard fractional operators
2.1. Characteristics of the $\varphi$-Fractional Operators. Some fundamental characteristics of the $\varphi$-fractional operators are listed below $[12,30]$.

Let $f(\zeta)=(\varphi(\zeta)-\varphi(\alpha))^{\gamma}$, where $\gamma>n$ and $\rho>0$. Then,

$$
\begin{align*}
I_{\alpha}^{\rho, \varphi} f(\zeta) & =\frac{\Gamma(\gamma+1)}{\Gamma(\rho+\gamma+1)}(\varphi(\zeta)-\varphi(\alpha))^{\rho+\gamma}, \\
D_{\alpha}^{\rho, \varphi} f(\zeta) & =\frac{\Gamma(\gamma+1)}{\Gamma(\gamma+1-\rho)}(\varphi(\zeta)-\varphi(\alpha))^{\gamma-\rho},  \tag{5}\\
I_{\alpha}^{\rho, \varphi} D_{\alpha}^{\rho, \varphi} f(\zeta) & =f(\zeta)-\sum_{k=0}^{n-1} \frac{D^{k, \varphi} f(\zeta)}{k!}(\varphi(\zeta)-\varphi(\alpha))^{k} .
\end{align*}
$$

Example 5. Let $f(\zeta)=(\zeta-\alpha)^{\gamma}$, with $\gamma>n$ and $\rho>0$. Then, the Caputo fractional derivative is given by

$$
\begin{equation*}
{ }^{C} D_{\alpha}^{\rho} f(\zeta)=\frac{\Gamma(\gamma+1)}{\Gamma(\gamma+1-\rho)}(\zeta-\alpha)^{\gamma-\rho} . \tag{6}
\end{equation*}
$$

The Caputo fractional derivatives of $\sin (\zeta)$ and $\cos (\zeta)$ are given by

$$
\begin{gather*}
{ }^{C} D_{\alpha}^{\rho} \sin (\zeta)=(\zeta)^{(1-\rho)} E_{2,2-\rho}\left(-\zeta^{2}\right)  \tag{7}\\
{ }^{C} D_{\alpha}^{\rho} \cos (\zeta)=(\zeta)^{-\rho} E_{2,1-\rho}\left(-\zeta^{2}\right)
\end{gather*}
$$

where $E_{\alpha, \beta}$ is the two-parameter Mittag-Leffler function defined by

$$
\begin{equation*}
E_{\alpha, \beta}=\sum_{\ell=0}^{\infty} \frac{\zeta^{\ell}}{\Gamma(\alpha \ell+\beta)} \tag{8}
\end{equation*}
$$

2.2. Existence and Uniqueness of Solution for Nonlinear $\varphi$ FDEs. In this section, we provide existence and uniqueness theorems for nonlinear $\varphi$-FDEs.

Consider the nonlinear $\varphi$-FDE:

$$
\begin{gather*}
D_{\alpha}^{\rho, \varphi} y(\zeta)=f(\zeta, y(\zeta))  \tag{9}\\
t \in[\alpha, \beta] .
\end{gather*}
$$

We have the initial conditions, namely, $y(\alpha)=y_{\alpha}$ and $y_{\varphi}^{[\ell]}(\alpha)=y_{\alpha}^{\ell}, \ell=1, \cdots, n-1$, where
(1) $0<\rho \notin N$ and $n=[\rho]+1$
(2) $y_{\alpha}$ and $y_{\alpha}^{\ell}$, where $\ell=1, \cdots, n-1$, are fixed reals
(3) $y \in C^{n-1}[\alpha, \beta]$, such that $D_{\alpha}^{\rho, \varphi}$ exists and is continuous in $[\alpha, \beta]$
(4) $f:[\alpha, \beta] \times \mathbb{R} \longrightarrow \mathbb{R}$ is continuous

Theorem 6. A function $y \in C^{n-1}[\alpha, \beta]$ is a solution to problem (9) if and only if $y$ satisfies the following fractional integral equation:

$$
\begin{equation*}
y(\zeta)=f(\zeta, y(\zeta))-\sum_{\ell=0}^{n-1} \frac{y_{\alpha}^{\ell}}{\ell!}(\varphi(\zeta)-\varphi(\alpha))^{\ell} \tag{10}
\end{equation*}
$$

Theorem 7. Let $f$ be a Lipschitz continuous function with respect to the second variable, that is, $\exists$ is a positive constant $L$ such that

$$
\begin{equation*}
\left|f\left(\zeta, x_{1}\right)-f\left(\zeta, x_{2}\right)\right| \leq L\left|x_{1}-x_{2}\right|, \quad \forall \zeta \in[\alpha, \beta], \forall x_{1}, x_{2} \in \mathbb{R} . \tag{11}
\end{equation*}
$$

Then, there is a constant $h \in \mathbb{R}^{+}$, such that there exists a unique solution to problem (9) on the interval $[\alpha, \alpha+h] \subseteq[\alpha$ $, \beta]$.

Proof of Theorems 6 and 7 can be seen in [13].
2.3. Approximation of Function by the Haar-Wavelet. The $i$ th Haar-wavelet defined on the interval $[\alpha, \beta]$ is given by

$$
h_{i}(\zeta)= \begin{cases}1, & \text { for } \zeta \in\left[\varkappa_{1}(i), \varkappa_{2}(i)\right)  \tag{12}\\ -1, & \text { for } \zeta \in\left[\varkappa_{2}(i), \varkappa_{3}(i)\right) \\ 0, & \text { elsewhere }\end{cases}
$$

where $\varkappa_{1}(i)=\alpha+(\beta-\alpha)(k / m), x_{2}(i)=\alpha+(\beta-\alpha)(2 k+1 /$ $m), x_{3}(i)=\alpha+(\beta-\alpha)(k+1 / m)$, and $m=2^{j}$, where $j=0$, $1,2,3, \cdots, J$ and $k=0,1,2,3, \cdots, m-1$. Here, $j$ and $k$ are the wavelet's dilation and translation parameters, whereas $J$ is the maximum level of resolution. The relationship $i$ $=m+k+1$ identifies the wavelet number $i$. For $i \geq 3$, equation (12) holds true.

The corresponding scaling functions of the Haar-wavelet family for $i=1$ and $i=2$ are

$$
\begin{align*}
& h_{1}(\zeta)= \begin{cases}1, & \text { for } \zeta \in[\alpha, \beta] \\
0, & \text { elsewhere },\end{cases} \\
& h_{2}(\zeta)= \begin{cases}1, & \text { if } \zeta \in\left[\alpha, \frac{\alpha+\beta}{2}\right) \\
-1, & \text { if } \zeta \in\left[\frac{\alpha+\beta}{2}, \beta\right), \\
0, & \text { elsewhere }\end{cases} \tag{13}
\end{align*}
$$

Any function $y(\zeta)$ defined and square integrable over the interval $[0,1)$ can be expressed in terms of the Haar-wavelet as follows:

$$
\begin{equation*}
y(\zeta)=\sum_{i=0}^{\infty} c_{i} h_{i}(\zeta), \tag{14}
\end{equation*}
$$

where the coefficients $c_{i}$ of the Haar-wavelet are defined by

$$
\begin{equation*}
c_{i}=\left\langle y(\zeta), h_{i}(\zeta)\right\rangle=\int_{0}^{1} y(\zeta) h_{i}(\zeta) d \zeta \tag{15}
\end{equation*}
$$

In practice, only the first $m$ terms of the series in equation (14) are considered, where $m$ is a power of 2 , that is,

$$
\begin{equation*}
y(\zeta) \cong y_{m}(\zeta)=\sum_{i=0}^{m-1} c_{i} h_{i}(\zeta) \tag{16}
\end{equation*}
$$

with vector form as

$$
\begin{equation*}
y(\zeta) \cong y_{m}(\zeta)=C_{m}^{T} H_{m}(\zeta) \tag{17}
\end{equation*}
$$

where $\quad C_{m}^{T}=\left[c_{0}, c_{1}, c_{2}, \cdots, c_{m-1}\right] \quad$ and $\quad H_{m}(\zeta)=$ $\left[h_{0}(\zeta), h_{1}(\zeta), h_{2}(\zeta), \cdots, h_{m-1}(\zeta)\right]^{T}$.

$$
P_{m \times m}^{\rho, \varphi}=\left[\begin{array}{cccccccc}
0.4342 & -0.2816 & -0.0998 & -0.1763 & -0.0356 & -0.0623 & -0.0806 & -0.0953  \tag{22}\\
-0.0210 & 0.1735 & -0.0998 & 0.2392 & -0.0356 & -0.0623 & 0.1297 & 0.1153 \\
-0.0739 & 0.0653 & 0.0613 & -0.0204 & -0.0356 & 0.0833 & -0.0173 & -0.0058 \\
0.0653 & -0.0653 & 0 & 0.1167 & 0 & 0 & -0.1051 & 0.1635 \\
-0.0285 & 0.0022 & 0.0221 & -0.00291 & 0.0211 & -0.0066 & -0.0019 & -0.0010 \\
-0.0094 & 0.0318 & -0.0224 & -0.00901 & 0 & 0.0435 & -0.0088 & -0.0020 \\
0.0064 & -0.0064 & 0 & 0.06786 & 0 & 0 & 0.0616 & -0.0113 \\
0.0280 & -0.0280 & 0 & -0.05604 & 0 & 0 & 0 & 0.0779
\end{array}\right] .
$$

Also, the approximate and exact $\varphi$-RL fractional integration of $\varphi(\zeta)=\sin (5 \zeta)$ for $J=6$ and various choices of $\rho$ is plotted in Figure 1.
3.1. Convergence Analysis of the $\varphi$-Haar-Wavelet Method. In [33], the Caputo-type FDEs were recently analyzed for error. Furthermore, utilizing the Haar wavelet, [34] proves convergence for the solution of the nonlinear Fredholm integral equations. In the present work, the upper limit for the error estimate is calculated using the $\varphi$-Caputo fractional differential operator. The $\varphi$-Haar-wavelet method for FDEs is shown to be convergent.

Theorem 8. Let $y^{n}(\zeta)$ be continuous on interval $[\alpha, \beta]$, and suppose $\exists K>0$, such that $\left|y_{\varphi}^{[n]}(\zeta)\right| \leq K \forall \zeta \in[\alpha, \beta]$, where $\alpha, \beta$ $\in \mathbb{R}^{+}, y_{\varphi}^{[n]}(\zeta)=\left(\left(1 / \varphi^{\prime}(\zeta)\right)(d / d \zeta)\right)^{n} y(\zeta)$, and $D_{\alpha}^{\rho, \varphi} y_{m}(\zeta)$ is the approximation of $D_{\alpha}^{\rho, \varphi} y(\zeta)$. Then, we have
$\left\|D_{\alpha}^{\rho, \varphi} y(\zeta)-D_{\alpha}^{\rho, \varphi} y_{m}(\zeta)\right\|_{E} \leq \frac{(\beta-\alpha) K\left(\varphi^{\prime}(\beta)\right)^{m-\rho}}{\Gamma(m-\rho+1)} \frac{1}{k^{(m-\rho)}} \frac{1}{\left[1-2^{2(\rho-m)}\right]^{(112)}}$.

Proof. $D_{\alpha}^{\rho, \varphi} y$ can be approximated as follows:

$$
\begin{equation*}
D_{\alpha}^{\rho, \varphi} y(\zeta)=\sum_{i=\alpha}^{\infty} c_{i} h_{i}(\zeta) \tag{24}
\end{equation*}
$$

where

$$
\begin{equation*}
c_{i}=\left\langle D_{\alpha}^{\rho, \varphi} y(\zeta), h_{i}(\zeta)\right\rangle=\int_{\alpha}^{\beta}\left(D_{\alpha}^{\rho, \varphi} y(\zeta)\right) h_{i}(\zeta) d \zeta . \tag{25}
\end{equation*}
$$

Suppose that $D_{\alpha}^{\rho, \varphi} y_{m}$ is the following approximation of $D_{\alpha}^{\rho, \varphi} y:$

$$
\begin{equation*}
D_{\alpha}^{\rho, \varphi} y_{m}(\zeta)=\sum_{i=0}^{m-1} c_{i} h_{i}(\zeta) \tag{26}
\end{equation*}
$$

where $m=2^{\kappa+1}, \kappa=1,2,3, \cdots$. Then,

$$
\begin{equation*}
D_{\alpha}^{\rho, \varphi} y(\zeta)-D_{\alpha}^{\rho, \varphi} y_{m}(\zeta)=\sum_{i=m}^{\infty} c_{i} h_{i}(\zeta)=\sum_{i=2^{k+1}}^{\infty} c_{i} h_{i}(\zeta) \tag{27}
\end{equation*}
$$

which implies that

$$
\begin{align*}
\left\|D_{\alpha}^{\rho, \varphi} y(\zeta)-D_{\alpha}^{\rho, \varphi} y_{m}(\zeta)\right\|_{E}^{2} & =\int_{\alpha}^{\zeta}\left(D_{\alpha}^{\rho, \varphi} y(\zeta)-D_{\alpha}^{\rho, \varphi} y_{m}(\zeta)\right)^{2} d \zeta \\
& =\sum_{i=2^{\kappa+1}}^{\infty} \sum_{i^{\prime}=2^{k+1}}^{\infty} c_{i} c_{i^{\prime}} \int_{\alpha}^{\zeta} h_{i}(\zeta) h_{i^{\prime}}(\zeta) d \zeta . \tag{28}
\end{align*}
$$

By orthogonality of the sequence $\left\{h_{m}(\zeta)\right\}$, we have $\int_{\alpha}^{\beta}$ $h_{m}(\zeta) h_{m}(\zeta) d \zeta=I_{m}$, where $I_{m}$ is the identity matrix of order $m$. Therefore,

$$
\begin{equation*}
\left\|D_{\alpha}^{\rho, \varphi} y(\zeta)-D_{\alpha}^{\rho, \varphi} y_{m}(\zeta)\right\|_{E}^{2}=\sum_{i^{\prime}=2^{k+1}}^{\infty} c_{i}^{2} \tag{29}
\end{equation*}
$$

From equation (25), we have

$$
\begin{align*}
c_{i}= & \int_{\alpha}^{\beta}\left(D_{\alpha}^{\rho, \varphi} y(\zeta)\right) h_{i}(\zeta) d \zeta \\
= & 2^{(j / 2)}\left\{\int_{\alpha+(\beta-\alpha) k 2^{-j}}^{\alpha+(\beta-\alpha)(k+(1 / 2))^{-j}} D_{\alpha}^{\rho, \varphi} y(\zeta) d \zeta\right.  \tag{30}\\
& \left.-\int_{\alpha+(\beta-\alpha)(k+(1 / 2)) 2^{-j}}^{\alpha+(\beta-\alpha)(k+1) 2^{-j}} D_{\alpha}^{\rho, \varphi} y(\zeta) d \zeta\right\} .
\end{align*}
$$

By the mean value theorem for integration, we have $\exists \zeta_{1}$, $\zeta_{2} \in(\alpha, \beta)$, such that

$$
\begin{align*}
& \alpha+(\beta-\alpha) k 2^{-j}<\zeta_{1}<\alpha+(\beta-\alpha)\left(k+\frac{1}{2}\right) 2^{-j}, \\
& \alpha+(\beta-\alpha)\left(k+\frac{1}{2}\right) 2^{-j}<\zeta_{2}<\alpha+(\beta-\alpha)(k+1) 2^{-j}, \\
& c_{i}=2^{(j / 2)}(\beta-\alpha)\left\{\left(\alpha+\left(k+\frac{1}{2}\right) 2^{-j}-\left(\alpha+k 2^{-j}\right)\right) D_{\alpha}^{\rho, \varphi} y\left(\zeta_{1}\right)\right. \\
& -\left(\left(\alpha+(k+1) 2^{-j}\right)-\left(\alpha+\left(k+\frac{1}{2}\right) 2^{-j}\right) D_{\alpha}^{\rho, \varphi} y\left(\zeta_{2}\right)\right\} \\
& =2^{(j / 2)}(\beta-\alpha)\left\{2^{-j-1}\left(D_{\alpha}^{\rho, \varphi} y\left(\zeta_{1}\right)-D_{\alpha}^{\rho, \varphi} y\left(\zeta_{2}\right)\right)\right\} . \tag{31}
\end{align*}
$$

Hence,

$$
\begin{equation*}
c_{i}^{2}=2^{-j-2}(\beta-\alpha)^{2}\left(D_{\alpha}^{\rho, \varphi} y\left(\zeta_{1}\right)-D_{\alpha}^{\rho, \varphi} y\left(\zeta_{2}\right)\right)^{2} . \tag{32}
\end{equation*}
$$



Figure 1: Exact and approximate $\varphi$-RL integration of the function $f(\zeta)=\sin (5 \zeta)$ for $J=6$ and various choices of $\rho$ and their maximum absolute error.

Employing the definition of the $\varphi$-Caputo fractional derivative, the fact that $\varphi$ is increasing and the condition | $y_{\varphi}^{[n]}(\zeta) \mid \leq K$, we arrive at

$$
\begin{align*}
&\left|D_{\alpha}^{\rho, \varphi} y\left(\zeta_{1}\right)-D_{\alpha}^{\rho, \varphi} y\left(\zeta_{2}\right)\right| \\
&= \left.\frac{1}{\Gamma(m-\rho)} \right\rvert\, \int_{\alpha}^{\zeta_{1}} \varphi^{\prime}(\zeta)\left(\varphi\left(\zeta_{1}\right)-\varphi(\zeta)\right)^{m-\rho-1} y_{\varphi}^{[n]}(\zeta) d \zeta \\
& \quad-\int_{\alpha}^{\zeta_{2}} \varphi^{\prime}(\zeta)\left(\varphi\left(\zeta_{2}\right)-\varphi(\zeta)\right)^{m-\rho-1} y_{\varphi}^{[n]}(\zeta) d \zeta \mid \\
& \leq \left.\frac{1}{\Gamma(m-\rho)} \right\rvert\, \int_{\alpha}^{\zeta_{1}} \varphi^{\prime}(\zeta)\left(\varphi\left(\zeta_{1}\right)-\varphi(\zeta)\right)^{m-\rho-1} y_{\varphi}^{[n]}(\zeta) d \zeta \\
& \quad-\int_{\alpha}^{\zeta_{1}} \varphi^{\prime}(\zeta)\left(\varphi\left(\zeta_{2}\right)-\varphi(\zeta)\right)^{m-\rho-1} y_{\varphi}^{[n]}(\zeta) d \zeta \mid  \tag{33}\\
& \quad+\left|\int_{\zeta_{1}}^{\zeta_{2}} \varphi^{\prime}(\zeta)\left(\varphi\left(\zeta_{2}\right)-\varphi(\zeta)\right)^{m-\rho-1} y_{\varphi}^{[n]}(\zeta) d \zeta\right| \\
& \leq \frac{1}{\Gamma(m-\rho)}\left(\int _ { \alpha } ^ { \zeta _ { 1 } } \varphi ^ { \prime } ( \zeta ) \left[\left(\varphi\left(\zeta_{1}\right)-\varphi(\zeta)\right)^{m-\rho-1}\right.\right. \\
&\left.\quad-\left(\varphi\left(\zeta_{2}\right)-\varphi(\zeta)\right)^{m-\rho-1}\right]\left|y_{\varphi}^{[n]}(\zeta)\right| d \zeta \\
&\left.\quad+\int_{\zeta_{1}}^{\zeta_{2}} \varphi^{\prime}(\zeta)\left(\varphi\left(\zeta_{2}\right)-\varphi(\zeta)\right)^{m-\rho-1}\left|y_{\varphi}^{[n]}(\zeta)\right| d \zeta\right) \tag{36}
\end{align*}
$$

where

$$
\begin{aligned}
m-\rho-1>0= & \frac{K}{\Gamma(m-\rho+1)}\left(\left(\varphi\left(\zeta_{1}\right)-\varphi(\alpha)\right)^{m-\rho}-\left(\varphi\left(\zeta_{2}\right)\right.\right. \\
& \left.-\varphi(\alpha))^{m-\rho}+2\left(\varphi\left(\zeta_{2}\right)-\varphi\left(\zeta_{1}\right)\right)^{m-\rho}\right)
\end{aligned}
$$

Since $\zeta_{1}>\alpha, \zeta_{2}>\alpha$, and $\zeta_{2}>\zeta_{1}$ and $\varphi(\zeta)$ is an increasing function, so

$$
\begin{equation*}
\left(\varphi\left(\zeta_{1}\right)-\varphi(\alpha)\right)^{m-\rho}-\left(\varphi\left(\zeta_{2}\right)-\varphi(\alpha)\right)^{m-\rho}<0 \tag{35}
\end{equation*}
$$

Table 2: Maximum absolute error for various choices of $\rho$ and $J$.

| $J$ | $\rho=0.50$ | $\rho=0.70$ | $\rho=0.90$ | $\rho=1$ |
| :--- | :---: | :---: | :---: | :---: |
| 0.5 | $3.2914 \times 10^{-4}$ | $2.4211 \times 10^{-4}$ | $2.3518 \times 10^{-4}$ | $2.4036 \times 10^{-4}$ |
| 0.6 | $1.1220 \times 10^{-4}$ | $6.9659 \times 10^{-5}$ | $5.9464 \times 10^{-5}$ | $6.0560 \times 10^{-5}$ |
| 0.7 | $3.8646 \times 10^{-5}$ | $2.0316 \times 10^{-5}$ | $1.5089 \times 10^{-5}$ | $1.5199 \times 10^{-5}$ |
| 0.8 | $1.3413 \times 10^{-5}$ | $5.9901 \times 10^{-6}$ | $3.8355 \times 10^{-6}$ | $3.8072 \times 10^{-6}$ |

Therefore,
$\left|D_{\alpha}^{\rho, \varphi} y\left(\zeta_{1}\right)-D_{\alpha}^{\rho, \varphi} y\left(\zeta_{2}\right)\right| \leq \frac{2 K}{\Gamma(m-\rho+1)}\left(\varphi\left(\zeta_{2}\right)-\varphi\left(\zeta_{1}\right)\right)^{m-\rho}$.
Table 1: Optimal value of the upper bound of error at different $J$ and $\alpha=0.25$.

| $J$ | $y_{\text {exact }}-y_{\text {approx }}(x) \\|_{E}$ | Optimality of the upper bound of error |
| :--- | :---: | :---: |
| 4 | $3.5102 \times 10^{-4}$ | 0.0714 |
| 5 | $2.8937 \times 10^{-5}$ | 0.0216 |
| 6 | $6.8632 \times 10^{-6}$ | 0.0542 |
| 7 | $3.2381 \times 10^{-6}$ | 0.0139 |

By mean value theorem, $\exists \varkappa \in\left[\zeta, \zeta_{2}\right] \subseteq[\alpha, \beta]$, such that $\varphi$ $\left(\zeta_{2}\right)-\varphi\left(\zeta_{1}\right) \leq\left(\zeta_{2}-\zeta_{1}\right) \varphi^{\prime}(\varkappa)$, we get

$$
\begin{align*}
\left|D_{\alpha}^{\rho, \varphi} y\left(\zeta_{1}\right)-D_{\alpha}^{\rho, \varphi} y\left(\zeta_{2}\right)\right| & \leq \frac{2 K}{\Gamma(m-\rho+1)}\left(\left(\zeta_{2}-\zeta_{1}\right) \varphi^{\prime}(\varkappa)\right)^{m-\rho}  \tag{34}\\
& \leq \frac{2 K}{\Gamma(m-\rho+1) 2^{j(m-\rho)}}\left(\varphi^{\prime}(\beta)\right)^{m-\rho} \tag{37}
\end{align*}
$$



Figure 2: For $J=5, \rho=0.6$, and $\varphi(\zeta)=\sin (\zeta)$ : (a) approximate and exact solutions; (b) maximum absolute error.
which gives
$\left(D_{\alpha}^{\rho, \varphi} y\left(\zeta_{1}\right)-D_{\alpha}^{\rho, \varphi} y\left(\zeta_{2}\right)\right)^{2} \leq \frac{4 K^{2}}{\Gamma^{2}(m-\rho+1) 2^{2 j(m-\rho)}}\left(\varphi^{\prime}(\beta)\right)^{2(m-\rho)}$.

Putting equation (38) into equation (32), we get

$$
\begin{equation*}
c_{i}^{2} \leq 2^{-j-2}(\beta-\alpha)^{2} \frac{4 K^{2}}{\Gamma^{2}(m-\rho+1) 2^{2 j(m-\rho)}}\left(\varphi^{\prime}(\beta)\right)^{2(m-\rho)} \tag{39}
\end{equation*}
$$

Equations (29) and (39) give

$$
\begin{aligned}
& \left\|D_{\alpha}^{\rho, \varphi} y(\zeta)-D_{\alpha}^{\rho, \varphi} y_{m}(\zeta)\right\|_{E}^{2} \\
& =\sum_{i=2^{\kappa+1}}^{\infty} c_{i}^{2}=\sum_{j=\kappa+1}^{\infty}\left(\sum_{i=2^{j}}^{2^{j+1}-1} c_{i}^{2}\right) \\
& \leq \\
& \quad \sum_{j=\kappa+1}^{\infty}(\beta-\alpha)^{2} \frac{K^{2}}{\Gamma^{2}(m-\rho+1) 2^{2 j(m-\rho)+j}} \\
& \quad \cdot\left(\varphi^{\prime}(\beta)\right)^{2(m-\rho)}\left(2^{j+1}-1-2^{j}+1\right) \\
& = \\
& =\frac{(\beta-\alpha)^{2} K^{2}\left(\varphi^{\prime}(\beta)\right)^{2(m-\rho)}}{\Gamma^{2}(m-\rho+1)} \sum_{j=\kappa+1}^{\infty} \frac{1}{2^{2 j(m-\rho)}} \\
& \Gamma^{2}(m-\rho+1) \\
& 2^{2(\kappa+1)(m-\rho)} \frac{1}{1-2^{2(\rho-m)}}
\end{aligned}
$$

which implies that

$$
\begin{align*}
& \left\|D_{\alpha}^{\rho, \varphi} y(\zeta)-D_{\alpha}^{\rho, \varphi} y_{m}(\zeta)\right\|_{E} \\
& \quad \leq \frac{(\beta-\alpha) K\left(\varphi^{\prime}(\beta)\right)^{m-\rho}}{\Gamma(m-\rho+1)} \frac{1}{2^{(\kappa+1)(m-\rho)}} \frac{1}{\left[1-2^{2(\rho-m)}\right]^{(1 / 2)}} \tag{41}
\end{align*}
$$

Let $k=2^{\kappa+1}$; (41) can also be written as

$$
\begin{align*}
& \left\|D_{\alpha}^{\rho, \varphi} y(\zeta)-D_{\alpha}^{\rho, \varphi} y_{m}(\zeta)\right\|_{E} \\
& \quad \leq \frac{(\beta-\alpha) K\left(\varphi^{\prime}(\beta)\right)^{m-\rho}}{\Gamma(m-\rho+1)} \frac{1}{k^{(m-\rho)}} \frac{1}{\left[1-2^{2(\rho-m)}\right]^{(1 / 2)}} \tag{42}
\end{align*}
$$

From the value of $K$, we can get an upper bound for the error.

We first estimate the value of $K$. Since $y^{n}(\zeta)$ is continuous and bounded on $[\alpha, \beta]$, so $y_{\varphi}^{[n]}(\zeta)$ is also continuous and bounded on $[\alpha, \beta]$ and is given by

$$
\begin{equation*}
y_{\varphi}^{[n]}(\zeta) \cong \sum_{i=0}^{m-1} c_{i} h_{i}(\zeta)=C_{m}^{T} H_{m}(\zeta) \tag{43}
\end{equation*}
$$

where $\quad C_{m}=\left[c_{0}, c_{1}, c_{2}, \cdots, c_{m-1}\right]^{T} \quad$ and $\quad H_{m}(\zeta)=$ $\left[h_{0}(\zeta), h_{1}(\zeta), h_{2}(\zeta), \cdots, h_{m-1}(\zeta)\right]^{T}$.


Figure 3: (a) Approximate and exact solutions of equation (57) for $\rho=0.6$ and $\varphi(\zeta)=\zeta^{2}-\zeta$. (b) Maximum absolute error. (c) Approximate solutions of equation (57) for $\varphi(\zeta)=\zeta^{2}$ and various choices of $\rho$.

Integrating equation (43), we have

$$
\begin{align*}
y_{\varphi}^{[n-1]}(\zeta) & =\int_{\alpha}^{\zeta} y_{\varphi}^{[n]}(\zeta) d \zeta+y_{\varphi}^{[n-1]}(\alpha)  \tag{44}\\
& =\int_{\alpha}^{\zeta} y_{\varphi}^{[n]}(\zeta) d \zeta \cong C_{m}^{T} P_{m \times m}^{1, \varphi} H_{m}(\zeta) .
\end{align*}
$$

Similarly,

$$
\begin{align*}
y_{\varphi}^{[n-2]}(\zeta) & =\int_{\alpha}^{\zeta} y_{\varphi}^{[n-1]}(\zeta) d \zeta+y_{\varphi}^{[n-2]}(\alpha)  \tag{45}\\
& =\int_{\alpha}^{\zeta} y_{\varphi}^{[n-1]}(\zeta) d \zeta \cong C_{m}^{T} P_{m \times m}^{2, \varphi} H_{m}(\zeta) .
\end{align*}
$$

Proceeding in the same way, we get

$$
\begin{equation*}
y_{\varphi}(\zeta) \cong C_{m}^{T} P_{m \times m}^{m, \varphi} H_{m}(\zeta) \tag{46}
\end{equation*}
$$

By defining the points $\zeta_{j}=((j-1 / 2) / m), j=0,1,2, \cdots, m$. Substituting $\zeta_{j}$ in equation (46), we have

$$
\begin{equation*}
y_{\varphi}\left(\zeta_{j}\right) \cong C_{m}^{T} P_{m \times m}^{m, \varphi} H_{m}\left(\zeta_{j}\right) \tag{47}
\end{equation*}
$$

The matrix form of equation (47) is as follows:

$$
\begin{equation*}
y_{\varphi} \cong C_{m}^{T} P_{m \times m}^{m, \varphi} H_{m}\left(\zeta_{j}\right) \tag{48}
\end{equation*}
$$

where $y_{\varphi}=\left[y_{\varphi}\left(\zeta_{1}\right), y_{\varphi}\left(\zeta_{2}\right), y_{\varphi}\left(\zeta_{3}\right), \cdots, y_{\varphi}\left(\zeta_{m}\right)\right]$.
By using equation (48), we can investigate $C_{m}^{T}$. From equation (43), we may know the value of $D^{m, \varphi}(\zeta)$ for each $\zeta$ $\in[\alpha, \beta]$.

Suppose $t_{i} \in[\alpha, \beta]$, for $i=1,2,3, \cdots, l, t_{i}=\left(t_{i}=(i-1 / l) / l\right)$ , and we calculate $y_{\varphi}^{[n]}\left(t_{i}\right)$ for $i=1,2,3, \cdots, l$; then, $\varepsilon+\max \mid$ $y_{\varphi}^{n}\left(t_{i}\right) \mid$ may be measured as the approximation for $K$.

Obviously, this approximation would have additional precision if $l$ increases and $\varepsilon$ is selected as $\beta$.

Theorem 9. Let $D_{\alpha}^{\rho, \varphi} y_{m}$, achieved by applying the $\varphi$-Haarwavelet, be the estimation of $D_{\alpha}^{\rho, \varphi} y$; then, the actual upperbound of error is given as follows:
$\left\|y(\zeta)-y_{m}(\zeta)\right\|_{E} \leq \frac{K N}{\Gamma(\rho+1) \Gamma(m-\rho+1)} \frac{1}{k^{(m-\rho)}} \frac{1}{\left[1-2^{2(\rho-m)}\right]^{(1 / 2)}}$,
where $N=\max \left|(\beta-\alpha)(\varphi(\beta))^{m-\rho}(\varphi(\zeta)-\varphi(0))^{\rho}\right|$.
Theorem 9 can be proven simply via Theorem 8. From equation (49), we can understand that $\left\|y(\zeta)-y_{m}(\zeta)\right\|_{E}$ tends to 0 as $m$ tends to $\infty$, which shows that the $\varphi$-Haar-wavelet technique converges.

Example 10. To demonstrate optimality of the upper bound in equation (49), we consider the following $\varphi$-FDE:
$D_{0}^{\rho, \varphi} y(\zeta)+y(\zeta)=(\varphi(\zeta))^{2 \rho}+\frac{\Gamma(2 \rho+1)}{\Gamma(\rho+1)}(\varphi(\zeta))^{\rho}, \quad 0<\rho \leq 1, \zeta \in[0,1]$,
with initial condition $y(0)=0$, having the exact solution $y(\zeta$ $)=(\varphi(\zeta))^{2} \rho$.

Table 1 shows the optimal values of the upper bound of error obtained for various options $J$ and $\rho=0.25$.

## 4. Numerical Solutions of $\varphi$-FDEs

In this section, we provide the solution to some problems in linear and nonlinear $\varphi$-FDEs by employing the $\varphi$-Haarwavelet operational matrix technique.

Table 3: Maximum absolute error for various choices of $\rho$ and $J$.

| $J$ | $\rho=0.60$ | $\rho=0.70$ | $\rho=0.80$ | $\rho=0.90$ |
| :--- | :---: | :---: | :---: | :---: |
| 0.5 | $4.7700 \times 10^{-5}$ | $4.4509 \times 10^{-5}$ | $3.833 \times 10^{-5}$ | $3.4673 \times 10^{-5}$ |
| 0.6 | $1.4816 \times 10^{-5}$ | $1.2922 \times 10^{-5}$ | $1.0871 \times 10^{-5}$ | $9.0534 \times 10^{-6}$ |
| 0.7 | $4.6410 \times 10^{-6}$ | $3.7700 \times 10^{-6}$ | $2.9758 \times 10^{-6}$ | $2.3511 \times 10^{-6}$ |
| 0.8 | $1.4674 \times 10^{-6}$ | $1.1071 \times 10^{-6}$ | $8.1696 \times 10^{-7}$ | $6.1074 \times 10^{-7}$ |

4.1. Linear Case. Here, we consider two examples of linear $\varphi$ FDEs for the numerical solution by the proposed method.

Example 11. Consider the composite oscillation equation of a fractional order with the $\varphi$-Caputo fractional derivative:

$$
\begin{equation*}
D_{0}^{\rho, \varphi} y(\zeta)+y(\zeta)=(\varphi(\zeta))^{2}+\frac{2}{\Gamma(3-\rho)}(\varphi(\zeta))^{2-\rho}, \quad 0<\rho \leq 1, \zeta \in[0,1] \tag{51}
\end{equation*}
$$

with the initial condition $y(0)=0$. The exact solution of equation (51) is given by $y(\zeta)=(\varphi(\zeta))^{2}$. For numerical solutions, we approximate $D_{0}^{\rho, \varphi} y(\zeta)$ as

$$
\begin{equation*}
D_{0}^{\rho, \varphi} y(\zeta)=C_{m}^{T} H_{m}(\zeta) \tag{52}
\end{equation*}
$$

Integrating equation (52) with the $\varphi$-Caputo integral operator, we have

$$
\begin{equation*}
y(\zeta)=\mathscr{F}_{0}^{\rho, \varphi} C_{m}^{T} H_{m}(\zeta)+c_{1}=C_{m}^{T} P_{m \times m}^{\rho, \varphi} H_{m}(\zeta)+c_{1} \tag{53}
\end{equation*}
$$

Substituting the initial conditions in equation (51), we get

$$
\begin{equation*}
y(\zeta)=C_{m}^{T} P_{m \times m}^{\rho, \varphi} H_{m}(\zeta)+(\varphi(0))^{2} \tag{54}
\end{equation*}
$$

Substituting equations (52) and (54) for equation (51), we have

$$
\begin{equation*}
C_{m}^{T}\left(H_{m}(\zeta)+P_{m \times m}^{\rho, \varphi} H_{m}(\zeta)\right)=f(\zeta) \tag{55}
\end{equation*}
$$

where $f(\zeta)=(\varphi(\zeta))^{2}+(2 / \Gamma(3-\rho))(\varphi(\zeta))^{2-\rho}-(\varphi(0))^{2}$.
Equation (55) can be expressed in the matrix form as follows:

$$
\begin{equation*}
C_{m}^{T}\left(H_{m}(\zeta)+A P_{m \times m}^{\rho, \varphi} H_{m}(\zeta)\right)=F \tag{56}
\end{equation*}
$$

where $F=f(\zeta)$. The value of $C_{m}^{T}$ can be obtained from equation (56). By using $C_{m}^{T}$ in equation (54), we can obtain the numerical solutions. Table 2 represents approximate solutions obtained for various choices of $\rho$ and $J$. The exact and numerical solutions of equation (51) and the maximum absolute error are plotted in Figures 2(a) and 2(b), respectively, for $J=5, \rho=0.6$, and $\varphi(\zeta)=\sin (\zeta)$.

Table 4: Maximum absolute error for $\varphi(\zeta)=\zeta^{3}$ and various choices of $J$ and $\rho$.

| $J$ | $\rho=0.60$ | $\rho=0.70$ | $\rho=0.80$ | $\rho=0.90$ | $\rho=1$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| 0.5 | $2.9805 \times 10^{-4}$ | $2.6189 \times 10^{-4}$ | $9.0556 \times 10^{-5}$ | $8.4937 \times 10^{-5}$ | $4.0843 \times 10^{-5}$ |
| 0.6 | $9.3858 \times 10^{-5}$ | $8.2375 \times 10^{-5}$ | $7.5629 \times 10^{-5}$ | $4.5815 \times 10^{-5}$ | $3.0209 \times 10^{-5}$ |
| 0.7 | $8.0570 \times 10^{-5}$ | $7.5617 \times 10^{-5}$ | $6.8581 \times 10^{-5}$ | $4.2393 \times 10^{-6}$ | $2.5527 \times 10^{-6}$ |
| 0.8 | $4.6741 \times 10^{-5}$ | $3.3469 \times 10^{-5}$ | $5.6175 \times 10^{-6}$ | $3.0351 \times 10^{-6}$ | $6.3818 \times 10^{-7}$ |
| 0.9 | $3.2109 \times 10^{-5}$ | $2.3126 \times 10^{-5}$ | $7.8318 \times 10^{-6}$ | $2.6165 \times 10^{-7}$ | $1.5954 \times 10^{-7}$ |



Figure 4: Approximate solutions for $\rho=1, J=5$, and different choices of $\varphi(\zeta)$.

Example 12. In this example, consider the FDE involving the $\varphi$-Caputo derivative:

$$
\begin{align*}
D_{0}^{\rho, \varphi} y(\zeta)+y(\zeta)= & (\varphi(\zeta))^{4}-\frac{1}{2}(\varphi(\zeta))^{3}-\frac{3}{\Gamma(4-\rho)}(\varphi(\zeta))^{3-\rho} \\
& +\frac{24}{\Gamma(5-\rho)}(\varphi(\zeta))^{4-\rho} \tag{57}
\end{align*}
$$

where $0<\rho \leq 1, \zeta \in[0,1]$, and the initial condition

$$
\begin{equation*}
y(0)=0 . \tag{58}
\end{equation*}
$$

The exact solution of the problem (57) is given as follows: $y(\zeta)=(\varphi(\zeta))^{4}-(1 / 2)(\varphi(\zeta))^{3}$. To get numerical solutions, the $\varphi$-Haar-wavelet method is employed as follows. Let

$$
\begin{equation*}
D_{0}^{\rho, \varphi} y(\zeta)=C_{m}^{T} H_{m}(\zeta) \tag{59}
\end{equation*}
$$

Table 5: Maximum absolute error for various choices of $\rho$ and $J$.

| $\rho$ | $J=0.5$ | $J=0.6$ | $J=0.7$ | $J=0.8$ |
| :--- | :---: | :---: | :---: | :---: |
| 0.60 | $3.9081 \times 10^{-4}$ | $2.1491 \times 10^{-4}$ | $1.6723 \times 10^{-4}$ | $3.0569 \times 10^{-5}$ |
| 0.70 | $3.6472 \times 10^{-4}$ | $1.7153 \times 10^{-4}$ | $3.2854 \times 10^{-5}$ | $3.7074 \times 10^{-5}$ |
| 0.80 | $3.2019 \times 10^{-4}$ | $1.3570 \times 10^{-4}$ | $2.8061 \times 10^{-5}$ | $5.8283 \times 10^{-6}$ |
| 0.90 | $2.6195 \times 10^{-4}$ | $9.0689 \times 10^{-5}$ | $1.8584 \times 10^{-5}$ | $4.1523 \times 10^{-6}$ |
| 0.1 | $2.2700 \times 10^{-4}$ | $5.8851 \times 10^{-5}$ | $1.4983 \times 10^{-5}$ | $3.7800 \times 10^{-6}$ |

Integrating equation (59) with the $\varphi$-Caputo integral operator, we have

$$
\begin{equation*}
y(\zeta)=\mathscr{J}_{0}^{\rho, \varphi} C_{m}^{T} H_{m}(\zeta)+c_{1} . \tag{60}
\end{equation*}
$$

Substituting initial conditions in equation (60), we get $c_{1}=y_{0}$. Equation (60) becomes

$$
\begin{equation*}
y(\zeta)=C_{m}^{T} P^{\rho, \varphi} H_{m}(\zeta)+y_{0} \tag{61}
\end{equation*}
$$



Figure 5: Exact solution for $\rho=1$ and numerical solutions for various choices of $\rho$.

Substituting equations (59) and (60) for equation (57), we get

$$
\begin{equation*}
C_{m}^{T}\left(H_{m}(\zeta)+a(\zeta) P^{\rho-\kappa, \varphi} H_{m}(\zeta)+b(\zeta) P^{\rho, \varphi} H_{m}(\zeta)\right)=F(\zeta) \tag{62}
\end{equation*}
$$

where $\quad F(\zeta)=(\varphi(\zeta))^{4}-(1 / 2)(\varphi(\zeta))^{3}-(3 / \Gamma(4-\rho))$ $(\varphi(\zeta))^{3-\rho}+(24 / \Gamma(5-\rho))(\varphi(\zeta))^{4-\rho}$. Approximate solutions are obtained by solving equations (61) and (62). The exact solution, approximate solutions, and the maximum absolute error are plotted in Figure 3 for $J=6$ and $\rho=0.6$. Also, the maximum absolute errors obtained for various choices of $\rho$ and $J$ are given in Table 3. We noticed that the maximum absolute error decreases with an increase in $J$.

### 4.2. Nonlinear Case

Example 13. Consider the fractional-order Riccati differential equation with the $\varphi$-Caputo fractional derivative:

$$
\begin{equation*}
D_{0}^{\rho, \varphi} y(\zeta)=-y^{2}(\zeta)+1,0<\rho \leq 1, \zeta \in[0,1] \tag{63}
\end{equation*}
$$

subject to the initial condition $y(0)=0$. For $\rho=1$, the exact solution of equation (63) is given by $y(\zeta)=\left(e^{\varphi(2 \zeta)}-1 / e^{\varphi(2 \zeta)}\right.$ $+1)$. For numerical solutions, we first utilize the quasilinearization techniques to make the nonlinear terms of equation (63) linear and then solve the linearized problem with the $\varphi$ -Haar-wavelet method. The linearized form of (63) is

$$
\begin{equation*}
D_{0}^{\rho, \varphi} y_{r+1}(\zeta)+2 y_{r}(\zeta) y_{r+1}(\zeta)=y_{r}^{2}(\zeta)+1, \quad \zeta>0,0<\rho \leq 1 \tag{64}
\end{equation*}
$$

with the initial condition $y_{r+1}(0)=0$.

Table 6: Comparison of results obtained in [31] and by our method for $\varphi(\zeta)=\left(\zeta^{2} / 2\right)+(\zeta / 2)$.

| $\zeta$ | $y$ - <br> Exact | $y$-Approximate by <br> $[31]$ | Error by <br> $[31]$ | Error by our <br> method |
| :--- | :---: | :---: | :---: | :---: |
| 0.0 | 0.0000 | 0.00060 | $60 \times 10^{-4}$ | $60 \times 10^{-4}$ |
| 0.1 | 0.0031 | 0.0037 | $70 \times 10^{-4}$ | $60 \times 10^{-4}$ |
| 0.2 | 0.0144 | 0.0151 | $80 \times 10^{-4}$ | $70 \times 10^{-4}$ |
| 0.3 | 0.0380 | 0.0388 | $90 \times 10^{-4}$ | $80 \times 10^{-4}$ |
| 0.4 | 0.0783 | 0.0793 | $10 \times 10^{-4}$ | $10 \times 10^{-4}$ |
| 0.5 | 0.1416 | 0.1427 | $11 \times 10^{-4}$ | $12 \times 10^{-3}$ |
| 0.6 | 0.2313 | 0.2324 | $11 \times 10^{-3}$ | $11 \times 10^{-3}$ |
| 0.7 | 0.3542 | 0.3553 | $12 \times 10^{-4}$ | $11 \times 10^{-4}$ |
| 0.8 | 0.5274 | 0.5284 | $10 \times 10^{-3}$ | $10 \times 10^{-3}$ |
| 0.9 | 0.7411 | 0.7421 | $10 \times 10^{-4}$ | $10 \times 10^{-4}$ |
| 1.0 | 1.0000 | 1.0007 | $70 \times 10^{-4}$ | $70 \times 10^{-4}$ |

Now, we apply the $\varphi$-Haar-wavelet method to equation (64). Let

$$
\begin{equation*}
D_{0}^{\rho, \varphi} y_{r+1}(\zeta)=C_{m}^{T} H_{m}(\zeta) \tag{65}
\end{equation*}
$$

Operating the $\varphi$-Caputo integral on equation (65), we get

$$
\begin{equation*}
y_{r+1}(\zeta)=\mathscr{J}^{\rho, \varphi} C_{m}^{T} H_{m}(\zeta)+c_{1}=C_{m}^{T} P_{m \times m}^{\rho, \varphi} H_{m}(\zeta)+c_{1} \tag{66}
\end{equation*}
$$

Putting the initial conditions in equation (66) gives

$$
\begin{equation*}
y_{r+1}(\zeta)=C_{m}^{T} P_{m \times m}^{\rho, \varphi} H_{m}(\zeta) \tag{67}
\end{equation*}
$$

Substituting equations (65) and (66) for equation (64), we have

$$
\begin{equation*}
C_{m}^{T}\left(H_{m}(\zeta)+2 y_{r}(\zeta) P_{m \times m}^{\rho, \varphi} H_{m}(\zeta)\right)=1+y_{r}^{2}(\zeta) \tag{68}
\end{equation*}
$$

The matrix form of equation (68) is given by

$$
\begin{equation*}
C_{m}^{T}\left(H_{m}(\zeta)+2 y_{r} P_{m \times m}^{\rho, \varphi} H_{m}(\zeta)\right)=F \tag{69}
\end{equation*}
$$

where $F=1+y_{r}^{2}$. By solving the algebraic system given by equation (69) for $C_{m}^{T}$ and substituting this value into equation (67), we will have the required numerical solution. In Table 4, the maximum absolute error is given for $\varphi(\zeta)=\zeta^{3}$. Also, approximate solutions for different choices of the function $\varphi$ are plotted in Figure 4.

Example 14. Finally, consider the Riccati differential equation of fractional order having the $\varphi$-Caputo fractional derivative:

$$
\begin{equation*}
D_{0}^{\rho, \varphi} y(\zeta)=2 y(\zeta)-y(\zeta)^{2}+1 \tag{70}
\end{equation*}
$$

where $0<\rho \leq 1$ and $\zeta \in[0,1]$.
Then, we subject this to the initial condition:

$$
\begin{equation*}
y(0)=0 \tag{71}
\end{equation*}
$$

When $\rho=1, y(\zeta)=1+\sqrt{2} \tanh (\sqrt{2} \varphi(\zeta)+(1 / 2) \log (($ $\sqrt{2}-1) /(\sqrt{2}+1)))$ is the actual solution of problem (70). For numerical solutions, we first utilize the quasilinearization technique to linearize the nonlinear terms in equation (70) and then solve the linearized FDE by the $\varphi$-Haar-wavelet method.

Equation (70) in the linearized form is given by
$D_{0}^{\rho, \varphi} y_{r+1}-\left(2-2 y_{r}(\zeta)\right) y_{r+1}(\zeta)=y_{r}^{2}(\zeta)+1, \quad \zeta>0$ and $0<\rho \leq 1$,
with the initial condition $y_{r+1}(0)=0$.
Consider

$$
\begin{equation*}
D_{0}^{\rho, \varphi} y_{r+1}=C_{m}^{T} H_{m}(\zeta) \tag{73}
\end{equation*}
$$

Taking the $\varphi$-Caputo integral of (73),

$$
\begin{equation*}
y_{r+1}=\mathscr{J}_{0}^{\rho, \varphi} C_{m}^{T} H_{m}(\zeta)+c_{1} \tag{74}
\end{equation*}
$$

Substituting the initial condition in equation (74), we have $c_{1}=0$.

Using $c_{1}=0$ in equation (74), we get

$$
\begin{equation*}
y_{r+1}=C_{m}^{T} P_{m \times m}^{\rho, \varphi} H_{m} \tag{75}
\end{equation*}
$$

Substituting equations (73) and (75) for equation (70), we get

$$
\begin{equation*}
C_{m}^{T}\left(H_{m}(\zeta)-\left(2-2 y_{r}(\zeta)\right)\right) P_{m \times m}^{\rho, \varphi} H_{m}(\zeta)=F(\zeta) \tag{76}
\end{equation*}
$$

Required approximate solutions can be obtained by using
the value of $C_{m}^{T}$ from equation (76) in equation (75). Table 5 shows that the maximum absolute error decreases by increasing the values of $J$. Also, the approximate solutions are displayed in Figure 5 for various values of $\rho$.

Example 15. For comparison with another method, we consider the following problem:
$D_{0}^{(3 / 2), \varphi} y(\zeta)+\frac{2}{\Gamma(3 / 2)} y(\zeta)=\frac{2}{\Gamma(3 / 2)}\left(1+(\varphi(\zeta))^{(3 / 2)}\right), \quad \zeta \in[0,1]$,
with the initial condition $y(0)=0$. The exact solution of equation (77) is given by $y(\zeta)=(\varphi(\zeta))^{2}$. This problem is studied in [31] by using the operational matrix of the $\varphi$ -shifted Legendre polynomials.
For $\varphi(\zeta)=\left(\zeta^{2} / 2\right)+(\zeta / 2)$, a comparison of the results obtained in [31] and by the proposed method is given in Table 6.

## 5. Conclusion

In this article, the $\varphi$-FDEs are solved numerically by introducing the $\varphi$-Haar-wavelet operational matrix of integration of fractional order. This operational matrix has been used to solve both linear and nonlinear problems with success. In comparison to the other methods, this approach is simple and more convergent. The developed method is used to solve a number of linear and nonlinear problems, demonstrating its efficiency and accuracy. Furthermore, the method's error analysis is thoroughly examined. As a future work, the proposed method may be applied to different wavelets as well as other operators.

## Data Availability

The numerical data used to support the findings of this study are included within the article.

## Conflicts of Interest

The authors declare that there are no conflicts of interest regarding the publication of this article.

## Acknowledgments

One of the coauthors (A. M. Zidan) extends his appreciation to the Deanship of Scientific Research at King Khalid University, Abha 61413, Saudi Arabia, for funding this work through a research group program under grant number R.G.P.$2 / 142 / 42$. The authors would like to thank the Deanship of Scientific Research at Umm Al-Qura University for supporting this research work under grant number 19-SCI-1-01-0056.

## References

[1] M. A. Zaky and A. S. Hendy, "Convergence analysis of an L 1continuous Galerkin method for nonlinear time-space fractional Schrodinger equations," International Journal of Computer Mathematics, vol. 98, no. 7, pp. 1420-1437, 2021.
[2] M. A. Zaky and A. S. Hendy, "An efficient dissipationpreserving Legendre-Galerkin spectral method for the Higgs boson equation in the de Sitter spacetime universe," Applied Numerical Mathematics, vol. 160, pp. 281-295, 2021.
[3] A. S. Hendy, J. E. Macias-Diaz, and A. J. Serna-Reyes, "On the solution of hyperbolic two-dimensional fractional systems via discrete variational schemes of high order of accuracy," Journal of Computational and Applied Mathematics, vol. 354, pp. 612-622, 2019.
[4] J. E. Restrepo, M. Ruzhansky, and D. Suragan, "Explicit solutions for linear variable-coefficient fractional differential equations with respect to functions," Applied Mathematics and Computation, vol. 403, p. 126177, 2021.
[5] A. Atangana and D. Baleanu, "New fractional derivatives with nonlocal and non-singular kernel: theory and application to heat transfer model," Thermal Science, vol. 20, no. 2, pp. 763-769, 2016.
[6] K. M. Owolabi and A. Atangana, "Analysis and application of new fractional Adams-Bashforth scheme with CaputoFabrizio derivative," Chaos, Solitons \& Fractals, vol. 105, pp. 111-119, 2017.
[7] U. N. Katugampola, "New approach to a generalized fractional integral," Applied Mathematics and Computation, vol. 218, no. 3, pp. 860-865, 2011.
[8] U. N. Katugampola, "A new approach to generalized fractional derivatives," Bulletin of Mathematical Analysis \& Applications, vol. 6, no. 4, 2014.
[9] A. A. A. Kilbas, H. M. Srivastava, and J. J. Trujillo, Theory and Applications of Fractional Differential Equations, vol. 204, Elsevier Science Limited, 2006.
[10] G. Sales Teodoro, J. A. Tenreiro Machado, and E. Capelas de Oliveira, "A review of definitions of fractional derivatives and other operators," Journal of Computational Physics, vol. 388, pp. 195-208, 2019.
[11] C. Milici, G. Drăgănescu, and J. T. Machado, Introduction to Fractional Differential Equations, vol. 25, Springer, 2018.
[12] R. Almeida, "A Caputo fractional derivative of a function with respect to another function," Communications in Nonlinear Science and Numerical Simulation, vol. 44, pp. 460481, 2017.
[13] R. Almeida, A. B. Malinowska, and M. T. T. Monteiro, "Fractional differential equations with a Caputo derivative with respect to a kernel function and their applications," Mathematical Methods in the Applied Sciences, vol. 41, no. 1, pp. 336-352, 2018.
[14] H. Aydi, M. Jleli, and B. Samet, "On positive solutions for a fractional thermostat model with a convex-concave source term via $\psi$-Caputo fractional derivative," Mediterranean Journal of Mathematics, vol. 17, no. 1, pp. 1-15, 2020.
[15] K. Shah, Z. A. Khan, A. Ali, R. Amin, H. Khan, and A. Khan, "Haar wavelet collocation approach for the solution of fractional order COVID-19 model using Caputo derivative," Alexandria Engineering Journal, vol. 59, no. 5, pp. 3221-3231, 2020.
[16] H. Alrabaiah, I. Ahmad, R. Amin, and K. Shah, "A numerical method for fractional variable order pantograph differential equations based on Haar wavelet," Engineering with Computers, 2021.
[17] F. A. Shah, R. Abass, and L. Debnath, "Numerical solution of fractional differential equations using Haar wavelet operational matrix method," International Journal of Applied and

Computational Mathematics, vol. 3, no. 3, pp. 2423-2445, 2017.
[18] M. S. Mechee, O. I. Al-Shaher, and G. A. Al-Juaifri, "Haar wavelet technique for solving fractional differential equations with an application," in AIP Conference Proceedings, 2019.
[19] M. Dehghan and M. Lakestani, "Numerical solution of nonlinear system of second-order boundary value problems using cubic B-spline scaling functions," International Journal of Computer Mathematics, vol. 85, no. 9, pp. 1455-1461, 2008.
[20] R. B. Burgos, M. A. C. Santos, and R. R. E. Silva, "DeslauriersDubuc interpolating wavelet beam finite element," Finite Elements in Analysis and Design, vol. 75, pp. 71-77, 2013.
[21] F. Saemi, H. Ebrahimi, and M. Shafiee, "An effective scheme for solving system of fractional Volterra-Fredholm integrodifferential equations based on the Muntz-Legendre wavelets," Journal of Computational and Applied Mathematics, vol. 374, p. 112773, 2020.
[22] A. Isah and C. Phang, "Genocchi wavelet-like operational matrix and its application for solving non-linear fractional differential equations," Open Physics, vol. 14, no. 1, pp. 463-472, 2016.
[23] L. J. Rong and P. Chang, "Jacobi wavelet operational matrix of fractional integration for solving fractional integro-differential equation," Journal of Physics: Conference Series, vol. 693, article 012002, 2016.
[24] R. Amin, K. Shah, M. Asif, and I. Khan, "A computational algorithm for the numerical solution of fractional order delay differential equations," Applied Mathematics and Computation, vol. 402, p. 125863, 2021.
[25] R. Amin, K. Shah, M. Asif, and I. Khan, "Efficient numerical technique for solution of delay Volterra-Fredholm integral equations using Haar wavelet," Heliyon, vol. 6, no. 10, p. e05108, 2020.
[26] K. Jong, H. Choi, K. Jang, and S. Pak, "A new approach for solving one-dimensional fractional boundary value problems via Haar wavelet collocation method," Applied Numerical Mathematics, vol. 160, pp. 313-330, 2021.
[27] R. Amin, K. Shah, M. Asif, I. Khan, and F. Ullah, "An efficient algorithm for numerical solution of fractional integrodifferential equations via Haar wavelet," Journal of Computational and Applied Mathematics, vol. 381, p. 113028, 2021.
[28] A. A. Kilbas, H. M. Srivastava, and J. J. Trujillo, "Theory and applications of fractional differential equations," in North-Holland Mathematical Studies, vol. 204, London and New York:Elsevier (North-Holland) Science Publishers, Amsterdam, 2006.
[29] T. J. Osler, "The fractional derivative of a composite function," SIAM Journal on Mathematical Analysis, vol. 1, no. 2, pp. 288293, 1970.
[30] R. Almeida, "Fractional differential equations with mixed boundary conditions," Bulletin of the Malaysian Mathematical Sciences Society, vol. 42, no. 4, pp. 1687-1697, 2019.
[31] R. Almeida, M. Jleli, and B. Samet, "A numerical study of fractional relaxation-oscillation equations involving $\psi$-Caputo fractional derivative," Revista de la Real Academia de Ciencias Exactas, Físicas y Naturales. Serie A. Matemáticas, vol. 113, no. 3, pp. 1873-1891, 2019.
[32] R. Almeida, A. B. Malinowska, and T. Odzijewicz, "An extension of the fractional Gronwall inequality," in Conference on Non-Integer Order Calculus and Its Applications, pp. 20-28, Springer, Cham, 2018.
[33] Y. Chen, M. Yi, and C. Yu, "Error analysis for numerical solution of fractional differential equation by Haar wavelets method," Journal of Computational Science, vol. 3, no. 5, pp. 367-373, 2012.
[34] E. Babolian and A. Shahsavaran, "Numerical solution of nonlinear Fredholm integral equations of the second kind using Haar wavelets," Journal of Computational and Applied Mathematics, vol. 225, no. 1, pp. 87-95, 2009.

