

## Research Article

# On Best Approximations in Hyperconvex Spaces

Reny George <sup>1,2</sup>, Zoran D. Mitrović <sup>3</sup>, and Hassen Aydi <sup>4,5,6</sup>

<sup>1</sup>Department of Mathematics, College of Science and Humanities in Al-Kharj, Prince Sattam bin Abdulaziz University, Al-Kharj 11942, Saudi Arabia

<sup>2</sup>Department of Mathematics and Computer Science, St. Thomas College, Bhilai, Chhattisgarh, India

<sup>3</sup>University of Banja Luka, Faculty of Electrical Engineering, 78000 Banja Luka, Patre 5, Bosnia and Herzegovina

<sup>4</sup>Institut Supérieur d'Informatique et des Techniques de Communication, Université de Sousse, H. Sousse, Tunisia

<sup>5</sup>Department of Mathematics and Applied Mathematics, Sefako Makgatho Health Sciences University, Ga-Rankuwa, South Africa

<sup>6</sup>China Medical University Hospital, China Medical University, Taichung 40402, Taiwan

Correspondence should be addressed to Reny George; [renygeorge02@yahoo.com](mailto:renygeorge02@yahoo.com) and Hassen Aydi; [hassen.aydi@isima.rnu.tn](mailto:hassen.aydi@isima.rnu.tn)

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In this manuscript, we present further extensions of the best approximation theorem in hyperconvex spaces obtained by Khamsi.

## 1. Introduction

The importance of fixed point theory emerges from the fact that it gives a unified approach and constitutes an essential tool in resolving problems which are not necessarily linear. A variant number of problems can be expressed as nonlinear equations of the form  $f(u) = u$ , where  $f$  is a self-mapping, see [1–6]. Nevertheless, an equation of the type  $f(u) = u$  does not necessarily have a solution if  $f$  is a non-self-mapping. Let  $(X, d)$  be a metric space. Here, we search an optimal solution in the sense that  $d(u, f(u))$  is minimum. That is, we resolve a problem of searching an element  $u \in X$  so that  $u$  is in best proximity to  $f$  in some sense. A best proximity point result presents the condition under which the optimisation problem, i.e.,  $\inf_{u \in A} d(u, f(u))$ , possesses a solution. The element  $u$  is called the best proximity point of  $f : A \rightarrow B$  if  $d(u, f(u)) = d(A, B) = \inf \{d(a, b), a \in A, b \in B\}$ . Observe that the best proximity point is reduced to a fixed point if  $f$  is a self-mapping. For more related works, see [7–11].

The concept of a hyperconvex space was initiated in [12] by Aronszajn and Panitchpakdi. In hyperconvex spaces, many results on coincidence points, fixed points, best approximations, and coupled best approximations are obtained. See, for example, [13–23]. For more details on the best approximation and KKM principle, we refer readers to the classic book [24]. Due to Aronszajn and Panitchpakdi

[12], the definition of a hyperconvex metric space is as follows.

A metric space  $(\Lambda, \omega)$  is named to be a hyperconvex space if for any set of points  $\{\ell_\alpha\}$  of  $\Lambda$  and for any family of nonnegative real numbers  $\{r_\alpha\}$  with  $\omega(\ell_\alpha, \ell_\beta) \leq r_\alpha + r_\beta$ , we have  $\cap_\alpha B(\ell_\alpha, r_\alpha) \neq \emptyset$ , where  $B(\ell, r) = \{j \in \Lambda : \omega(\ell, j) \leq r\}$  represents the closed ball with center  $\ell \in \Lambda$  and radius  $r$ .

Suppose that a subset  $A$  of  $\Lambda$  is bounded. Consider,

$$\begin{aligned} co(A) &= \cap \{B \subseteq \Lambda : B \text{ is a closed ball so that } A \subseteq B\}, \\ \mathcal{A}(\ell) &= \{A \subseteq \Lambda : A = co(A)\}, \end{aligned} \quad (1)$$

i.e.,  $A \in \mathcal{A}(\ell)$  iff  $A$  is an intersection of closed balls. Here,  $A$  is named to be an admissible subset of  $\Lambda$ . In the linear case, the notation  $\text{conv}(A)$  describes the convex hull of  $A$ . Note that  $co(A)$  is always defined and is in  $\mathcal{A}(\ell)$ . If  $(\Lambda, \omega)$  is a hyperconvex space, then it is complete [17].

Let  $\Lambda$  be a nonempty set. We denote by  $\langle \Lambda \rangle$  and  $2^\Lambda$  the set of all nonempty finite subsets of  $\Lambda$  and the set of all nonempty subsets of  $\Lambda$ , respectively. Let  $\Lambda$  and  $\Omega$  be topological spaces with  $A \subseteq \Lambda$  and  $B \subseteq \Omega$ . Given a set-valued map  $F : \Lambda \rightarrow 2^\Omega$ , the image of  $A$  under  $F$  is the set  $F(A) = \cup_{a \in A} F(a)$  and the inverse image of  $B$  under  $F$  is  $F^{-}(B) = \{\ell \in \Lambda : F(\ell) \cap B \neq \emptyset\}$ . The map  $F$  is lower (upper) semicontinuous if, for each open (closed) set  $B \subseteq \Omega$ ,

$F^-(B)$  is open (closed) set in  $\Lambda$ . The map  $F$  is continuous if  $F$  is both upper semicontinuous and lower semicontinuous.

Let  $A$  be an admissible subset of  $\Lambda$ . The set-valued map  $F : A \rightarrow 2^\Lambda$  is named to be quasicontinuous if for any admissible set  $A$  of  $\Lambda$ ,  $F^-(A)$  is also admissible (see [15]). Observe that if  $F$  is a quasicontinuous map, then the set  $F^-(B(\ell, r))$  is admissible for each closed ball  $B(\ell, r)$ . Note that, if  $A \in \mathcal{A}(\ell)$ , then  $A + r \in \mathcal{A}(\ell)$  (see [25]), where  $A + r = \cup_{a \in A} B(a, r)$ .

Khamsi [17] presented a hyperconvex version of the KKM principle in hyperconvex spaces. As an application, he gave a hyperconvex version of the best approximation result of Fan for continuous single-valued maps. In this manuscript, we ensure the existence of a solution of a best approximation problem for set-valued maps  $F$  and  $G$ : for a set  $K$ , find  $\ell_0 \in K$  so that

$$\omega(G(\ell_0), F(\ell_0)) \leq \omega(G(\ell), F(\ell_0)) \text{ for all } \ell \in K. \quad (2)$$

Let  $\Lambda$  be a metric space and  $K \subset \Lambda$ . A multivalued map  $H : K \rightarrow 2^\Lambda$  is said to be a KKM map if

$$\text{co}(A) \subset H(A) \text{ for any } A \in \langle K \rangle. \quad (3)$$

**Theorem 1** (see [17], KKM principle). *Let  $\Lambda$  be a hyperconvex space,  $K$  be an arbitrary subset of  $\Lambda$ , and  $H : K \rightarrow 2^\Lambda$  be a KKM map so that  $H(\ell_0)$  is compact for some  $\ell_0 \in K$  and  $H(\ell)$  is closed for any  $\ell \in K$ . Then,  $\bigcap_{\ell \in K} H(\ell) \neq \emptyset$ .*

**Theorem 2** (see [17], best approximation). *Let  $\Lambda$  be a hyperconvex space and  $K \in \mathcal{A}(\ell)$  be compact. Given a continuous map  $f : K \rightarrow \Lambda$ , there is  $\ell_0 \in K$  so that*

$$\omega(\ell_0, f(\ell_0)) = \inf_{\ell \in K} \omega(\ell, f(\ell_0)). \quad (4)$$

*This result has been generalized to other forms of maps. For more details, see [13–16, 18, 22].*

*Now, we give the definition of a measure of noncompactness of Pasicki [26].*

**Definition 3** (see [26]). Let  $\Lambda$  be a metric space. An arbitrary function  $\theta : 2^\Lambda \rightarrow [0, \infty]$  is named to be a measure of noncompactness on  $\Lambda$  if

- (1)  $\theta(A) = 0$  iff  $A$  is a totally bounded set
- (2) for  $A, B \in 2^\Lambda$ ,  $A \subset B$ , implies  $\theta(A) \leq \theta(B)$
- (3) for all  $A \subset \Lambda$  and  $\ell \in \Lambda$ ,  $\theta(A \cup \{\ell\}) = \theta(A)$

**Definition 4** (see [19]). Let  $\Lambda$  be a metric space,  $\theta$  be a measure of noncompactness on  $\Lambda$ , and  $K \subset \Lambda$ . The map  $H : K \rightarrow 2^\Lambda$  is condensing if for any  $\varepsilon > 0$ , there is  $A \in \langle K \rangle$  so that  $\theta(\bigcap_{a \in A} H(a)) < \varepsilon$ . A condensing map  $H : K \rightarrow 2^\Lambda$  is a condensing KKM map if it is a KKM map.

In this paper, we present further extensions of the best approximation result (Theorem 2) obtained by Khamsi.

Finally, we present a problem related to the Schauder conjecture.

## 2. Results

The following result generalizes Theorem 1. The proof is essentially the same as Theorem 3.1 in [19].

**Theorem 5.** *Let  $\theta$  be a measure of noncompactness on  $\Lambda$  a hyperconvex space,  $K$  be an arbitrary subset of  $\Lambda$ , and  $H : K \rightarrow 2^\Lambda$  be a condensing KKM map such that each  $H(\ell)$  is closed, then  $\bigcap_{\ell \in K} H(\ell)$  is nonempty and compact set.*

We introduce the concept of a  $\varphi$ -quasicontinuous map in hyperconvex spaces.

**Definition 6.** Let  $\Lambda$  be a hyperconvex space and  $K \in \mathcal{A}(\ell)$ . A set-valued map  $G : K \rightarrow 2^\Lambda$  is said to be a  $\varphi$ -quasicontinuous if for any  $\ell \in K$  and  $r > 0$ ,

$$\text{co}G^-(B(\ell, r)) \subseteq G^-(B(\ell, \varphi(r))), \quad (5)$$

where  $\varphi : [0, \infty) \rightarrow [0, \infty)$  is a continuous monotone increasing function so that  $\varphi(u) \geq u$  for any  $u \geq 0$  and  $\varphi(0) = 0$ .

Let  $i_\omega : [0, \infty) \rightarrow [0, \infty)$  be the identity map and  $I_\omega : K \rightarrow 2^K$  be the identity set-valued map so that  $I_\omega(\ell) = \{\ell\}$  for any  $\ell \in K$ . Note that a quasicontinuous map is  $i_\omega$ -quasicontinuous and  $I_\omega$  is  $i_\omega$ -quasicontinuous in hyperconvex spaces.

If  $(\Lambda, \omega)$  is a linear metric space, then  $I_\omega$  may not be  $i_\omega$ -quasicontinuous.

**Example 1.** Denote by  $S$  the linear space of real sequences. The Fréchet metric  $\omega_F$  for  $S$  is given as follows (see [27]):

Let  $\ell = (\ell_1, \ell_2, \dots, \ell_n, \dots)$ ,  $j = (j_1, j_2, \dots, j_n, \dots)$ , and  $0 = (0, 0, \dots, 0, \dots)$ ,

$$d_F(\ell, j) = \sum_{n=1}^{+\infty} \frac{1}{2^n} \frac{|\ell_n - j_n|}{1 + |\ell_n - j_n|}, \quad (6)$$

then, we obtain

$$\text{conv}B\left(0, \frac{1}{3}\right) \subseteq B\left(0, \frac{1}{3}\right). \quad (7)$$

Namely, for  $\ell = (1, 0, 1, 0, \dots)$  and  $j = (1/2, 1/2, \dots)$ , we have that  $\ell \in B(0, 1/3)$ ,  $j \in B(0, 1/3)$ , and  $(\ell + j)/2 \notin B(0, 1/3)$ .

Note that for any  $\ell \in S$  and  $r > 0$ , one writes

$$\text{conv}B(\ell, r) \subseteq B(\ell, 2r). \quad (8)$$

So, in the linear metric space  $(S, \omega_F)$ , the map  $I_\omega$  is not  $i_\omega$ -quasi-convex and  $I_\omega$  is  $\varphi$ -quasicontinuous, where  $\varphi(u) = 2u$ ,  $u \in [0, \infty)$ .

**Theorem 7.** *Let  $(\Lambda, \omega)$  be a hyperconvex space,  $K \in \mathcal{A}(\ell)$  be closed,  $\theta$  be a measure of noncompactness on  $\Lambda$ ,  $F, G : K$*

$\longrightarrow \mathcal{A}(\ell)$  be continuous maps with compact values and  $G$  be  $\varphi$ -quasi-convex. If for any  $u > 0$  there is  $j \in K$  so that

$$\theta(\{\ell \in K : \omega(G(\ell), F(\ell)) \leq \varphi(\omega(G(j), F(\ell)))\}) \leq u, \quad (9)$$

then, there is  $\ell_0 \in K$  so that

$$\omega(G(\ell_0), F(\ell_0)) \leq \inf_{\ell \in K} \varphi(\omega(G(\ell), F(\ell_0))). \quad (10)$$

*Proof.* Define  $H : K \longrightarrow 2^A$  by

$$H(j) = \{\ell \in K : \omega(G(\ell), F(\ell)) \leq \varphi(\omega(G(j), F(\ell)))\}. \quad (11)$$

From condition  $\varphi(t) \geq t$ , we obtain

$$\omega(G(j), F(j)) \leq \varphi(\omega(G(j), F(j))) \text{ for all } j \in K, \quad (12)$$

so  $H(j)$  is a nonempty set for all  $j \in K$ , because  $j \in H(j)$ .

From condition (9), one asserts that  $H$  is a condensing map.

Since  $F$  and  $G$  are continuous maps and  $\varphi$  is a continuous function, we get that  $H(j)$  is a closed set for all  $j \in K$ .

The map  $j \longmapsto H(j)$  is KKM. Indeed, suppose that for some  $A \in \langle K \rangle$ ,

$$co(A) \not\subseteq H(A). \quad (13)$$

Then, there is  $j \in co(A)$  so that  $j \notin H(a)$  for any  $a \in A$ . Thus,

$$\omega(G(j), F(j)) > \varphi(\omega(G(a), F(j))) \text{ for all } a \in A. \quad (14)$$

The function  $\varphi$  is increasing, so

$$\varphi^{-1}(\omega(G(j), F(j))) > \omega(G(a), F(j)) \text{ for all } a \in A. \quad (15)$$

Let  $\varepsilon > 0$  be so that

$$\varphi^{-1}(\omega(G(j), F(j))) - \varepsilon \geq \omega(G(a), F(j)) \text{ for all } a \in A. \quad (16)$$

Then,

$$A \subseteq G^{-}(F(j) + \varphi^{-1}(\omega(G(j), F(j))) - \varepsilon), \quad (17)$$

and hence,

$$co(A) \subseteq co(G^{-}(F(j) + \varphi^{-1}(\omega(G(j), F(j))) - \varepsilon)). \quad (18)$$

Since  $G$  is  $\varphi$ -quasi-convex, one gets from (18),

$$co(A) \subseteq G^{-}(F(j) + \varphi(\varphi^{-1}(\omega(G(j), F(j))) - \varepsilon)). \quad (19)$$

Since  $j \in co(A)$ , we deduce that

$$\omega(G(j), F(j)) \leq \varphi(\varphi^{-1}(\omega(G(j), F(j))) - \varepsilon). \quad (20)$$

Consequently,

$$\varphi^{-1}(\omega(G(j), F(j))) \leq \varphi^{-1}(\omega(G(j), F(j))) - \varepsilon, \quad (21)$$

which is not possible. Therefore,  $H$  must be a KKM map. Now, from Theorem 5, there is  $\ell_0 \in K$  so that

$$\ell_0 \in \bigcap_{\ell \in K} H(\ell). \quad (22)$$

Therefore,

$$\omega(G(\ell_0), F(\ell_0)) \leq \inf_{\ell \in K} \varphi(\omega(G(\ell), F(\ell_0))). \quad (23)$$

Taking the set  $K$  to be compact, we state from Theorem 7 the next results.

**Theorem 8.** Let  $(\Lambda, \omega)$  be a hyperconvex space,  $K \in \mathcal{A}(\ell)$  be compact,  $F, G : K \longrightarrow \mathcal{A}(\ell)$  be continuous maps with compact values, and  $G$  be  $\varphi$ -quasi-convex. Then, there is  $\ell_0 \in K$  so that

$$\omega(G(\ell_0), F(\ell_0)) \leq \inf_{\ell \in K} \varphi(\omega(G(\ell), F(\ell_0))). \quad (24)$$

**Theorem 9.** Let  $(\Lambda, \omega)$  be a hyperconvex space,  $K \in \mathcal{A}(\ell)$  be compact,  $F, G : K \longrightarrow \mathcal{A}(K)$  be continuous maps with compact values, and  $G$  be  $\varphi$ -quasi-convex onto a map. Then, there is  $\ell_0 \in K$  so that  $G(\ell_0) \cap F(\ell_0) \neq \emptyset$ .

**Theorem 10.** Let  $(\Lambda, \omega)$  be a hyperconvex space,  $K \in \mathcal{A}(\ell)$  be compact, and  $F, G : K \longrightarrow \mathcal{A}(\ell)$  be continuous maps with compact values. If there is  $\lambda \geq 1$  such that for any  $\ell \in X$  and  $r > 0$ ,

$$coG^{-}(B(\ell, r)) \subseteq G^{-}(B(\ell, \lambda r)), \quad (25)$$

then there is  $\ell_0 \in K$  so that

$$\omega(G(\ell_0), F(\ell_0)) \leq \inf_{\ell \in K} \lambda \omega(G(\ell), F(\ell_0)). \quad (26)$$

**Theorem 11.** Let  $(\Lambda, \omega)$  be a hyperconvex space,  $K \in \mathcal{A}(\ell)$  be compact, and  $F : K \longrightarrow \mathcal{A}(\ell)$  be a continuous map with compact values so that  $F(\ell) \cap K \neq \emptyset$  for any  $\ell \in K$ . Then, there is  $\ell_0 \in K$  so that  $\ell_0 \in F(\ell_0)$ .

*Remark 12.* If  $F$  is a single-valued map, we deduce from Theorem 11 the main theorem of Park [22] (Theorem 5. (iv)).

**Theorem 13** (see [18], Theorem 3.2). Let  $(\Lambda, \omega)$  be a hyperconvex space,  $K \in \mathcal{A}(\ell)$  be compact,  $F, G : K \longrightarrow \mathcal{A}(\ell)$  be continuous maps with compact values, and  $G$  be quasi-convex. Then, there is  $\ell_0 \in K$  so that

$$\omega(G(\ell_0), F(\ell_0)) \leq \inf_{\ell \in K} \omega(G(\ell), F(\ell_0)). \quad (27)$$

**Theorem 14** (see [16], Theorem 2.9). Let  $(\Lambda, \omega)$  be a hyperconvex space,  $K \in \mathcal{A}(\ell)$  be compact, and  $F : K \longrightarrow \mathcal{A}(\ell)$  be

a continuous map with compact values. Then, there is  $\ell_0 \in K$  so that

$$\omega(\ell_0, F(\ell_0)) = \inf_{\ell \in K} \omega(\ell, F(\ell_0)). \quad (28)$$

Finally, we give the following problems.

**Problem 15.** Does for every linear metric space  $(\Lambda, \omega)$  and for a compact subset  $K$  of  $\Lambda$ , there is a map  $\varphi$  so that the identity map  $I_\omega : K \longrightarrow 2^K$  (i.e.,  $I_\omega(\ell) = \{\ell\}$ ,  $\ell \in K$ ) is  $\varphi$ -quasiconvex?

In other words, does for a linear metric space, there is a continuous monotone increasing function  $\varphi : [0, \infty) \longrightarrow [0, \infty)$  so that  $\varphi(u) \geq u$  for any  $u \geq 0$ ,  $\varphi(0) = 0$  and

$$\text{conv}B(\ell, r) \subseteq B(\ell, \varphi(r)), \quad (29)$$

for any  $\ell \in K$  and  $r > 0$ ?

In 2001, Cauty [28] obtained the affirmative solution to the Schauder conjecture as follows:

**Problem 16.** Let  $K$  be a compact convex subset of a (metrizable) topological vector space. Does any continuous map  $f : K \longrightarrow K$  have a fixed point?

**Remark 17.** Note that if Problem 15 is affirmative, then Problem 16 is affirmative.

## Data Availability

Data sharing is not applicable to this article as no data set was generated or analyzed during the current study.

## Conflicts of Interest

The authors declare no conflict of interest.

## Authors' Contributions

All authors have read and agreed to the published version of the manuscript.

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