

Review Article

Pell Collocation Method for Solving the Nonlinear Time– Fractional Partial Integro–Differential Equation with a Weakly Singular Kernel

M. Taghipour (D^1) and H. Aminikhah $(D^{1,2})$

¹Department of Applied Mathematics and Computer Science, Faculty of Mathematical Sciences, University of Guilan, P.O. Box 1914, Rasht 41938, Iran

²Center of Excellence for Mathematical Modelling, Optimization and Combinational Computing (MMOCC), University of Guilan, P.O. Box 1914, Rasht 41938, Iran

Correspondence should be addressed to H. Aminikhah; aminikhah@guilan.ac.ir

Received 31 December 2021; Accepted 21 April 2022; Published 23 May 2022

Academic Editor: Youssri Hassan Youssri

Copyright © 2022 M. Taghipour and H. Aminikhah. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

This article focuses on finding the numerical solution of the nonlinear time-fractional partial integro-differential equation. For this purpose, we use the operational matrices based on Pell polynomials to approximate fractional Caputo derivative, nonlinear, and integro-differential terms; and by collocation points, we transform the problem to a system of nonlinear equations. This nonlinear system can be solved by the fsolve command in Matlab. The method's stability and convergence have been studied. Also included are five numerical examples to demonstrate the veracity of the suggested strategy.

1. Introduction

Nowadays, fractional partial differential equations (FPDEs) have emerged as one of the most crucial issues due to their vast applications in various branches of science, such as medicine [1, 2], control theory [3–5], engineering [6, 7], viscoelasticity [8], mathematical physics [9], geo-hydrology [10], signals [11], stochastic models [12], electrical engineering, [13], and financial economics [14]. Due to the fact that analytical solutions of FPDEs are rarely available, the use of numerical methods is inevitable. Hitherto, a number of numerical methods for FPDEs have been suggested, such as finite difference [15, 16], spectral methods [17-21], homotopy methods [22, 23], and finite element [24, 25]. The nonlinear FPDEs have been extensively analyzed using numerical methods. Dehghan et al. used the homotopy analysis method to construct a scheme for solving the fractional KdV equation [26]. Nikan et al. proposed a meshless technique in order to solve the nonlinear fractional fourth-order diffusion equation [27]. Safari and Azarsa introduced a meshless method based on Muntz polynomials to solve nonlinear and linear space fractional partial differential equations [28]. Yaslan applied the Legender collocation method for solving nonlinear fractional partial differential equations [29].

When it comes to solving differential equations, spectral approaches are extremely effective. The solution to the differential equation is sought as a series of basis polynomials using this method. The Galerkin, Tao, and collocation approximations are the most common spectral methods [30, 31]. For example, Samiee et al. [20] designed a Petrov–Galerkin spectral method for distributed–order PDEs. Agarwal et al. [32] suggested a spectral collocation approach for variable–order fractional integro–differential equations. In [33], the authors used the polynomial–sinc collocation method for solving distributed order fractional differential equations. Abbaszadeh et al. proposed a Crank–Nicolson

Galerkin spectral method for distributed order weakly singular integro-partial differential equations [34].

In the present paper, we offer a numerical technique for solving the nonlinear time-fractional partial integro-differential equation (TFPIDEs) with a weakly singular kernel

$$\begin{split} & \overset{C}{}_{0} \mathcal{D}_{\eta}^{\alpha} \mathcal{V}(\xi,\eta) + \mathcal{V}(\xi,\eta) \mathcal{V}_{\xi}(\xi,\eta) \\ & = \int_{0}^{\eta} (\eta - \mathbf{s})^{\beta - 1} \mathcal{V}_{\xi\xi}(\xi, \mathbf{s}) \mathrm{d}\mathbf{s} + \mathcal{G}(\xi,\eta), \xi \in [0, \mathrm{L}], \eta \in [0, \mathrm{T}], \end{split}$$

with initial and boundary conditions

$$\mathcal{V}(0,\eta) = \Phi_1(\eta), \mathcal{V}(L,\eta) = \Phi_2(\eta), 0 < \eta \le T, \qquad (2)$$

$$\mathscr{V}(\xi, 0) = \Psi(\xi), 0 < \xi \le L, \tag{3}$$

where $0 < \alpha, \beta < 1$, $g(\xi, \eta) \in C([0, L] \times [0, T])$, and ${}_{0}^{C} \mathcal{D}_{\eta}^{\alpha}$ signify the fractional operator. This problem appears in the modeling of heat transfer materials with memory, population dynamics [35], and nuclear reaction theory [36].

To the best of the author's knowledge, little work has been done on problem (1). For example, Guo et al. [37] proposed a numerical technique for solving (1)–(3). In the case of $\alpha = 1$, Zheng et al. [35] described three semi-implicit compact finite difference schemes for problem (1)–(3). This encourages us to suggest a numerical scheme for the problem (1)-(3). The finite difference schemes are the easiest methods for solving these equations. It is, however, difficult to apply the mathematical study of finite difference methods to nonlinear TFPIDEs. Polynomial spectral techniques are effective tools for solving PDEs. To build spectral methods, many polynomials have been developed (see [38–41]). The coefficients of Pell polynomials are integers, and the number of terms increases slowly. This leads to less CPU time and fewer computational errors. Because of this, the Pell polynomials with both of these two characteristics will be employed.

In this paper, we will focus on the spectral collocation method based on two-variable Pell polynomials. We use them as the basis polynomials to solve the main problem numerically. With the use of operational matrices, the problem is turned into a system of nonlinear equations in the approach based on these polynomials. The error analysis is presented. Several test problems are provided to illustrate the method's efficacy.

The following is the body of the article: Section 2 introduces a number of key themes. To remedy the main problem, we suggest a polynomial spectral technique in Section 3. The error analysis is investigated in Section 4. Section 5 contains the experiments. The conclusion is addressed in Section 6.

2. Definitions

Definition 1 (see [15]). The Riemann–Liouville integral of a function $\mathfrak{z}(\xi, \eta)$ on $(0, L) \times (0, T)$ is defined as follows

$${}^{\mathrm{RL}}_{0}\mathcal{J}^{\alpha}_{\eta}\mathfrak{z}(\xi,\eta) = \frac{1}{\Gamma(\alpha)} \int_{0}^{\eta} (\eta-\tau)^{\alpha-1}\mathfrak{z}(\xi,\tau)d\tau, 0 < \alpha < 1.$$
(4)

Definition 2 (see [15]). The Riemann–Liouville derivative of a function $\mathfrak{z}(\xi, \eta)$ on $(0, L) \times (0, T)$ is defined as follows

$${}^{\mathrm{RL}}_{0} \mathcal{D}^{\alpha}_{\eta} \mathfrak{z}(\xi,\eta) = \frac{1}{\Gamma(1-\alpha)} \frac{d}{d\eta} \int_{0}^{\eta} (\eta-\tau)^{-\alpha} \mathfrak{z}(\xi,\tau) d\tau, 0 < \alpha < 1.$$
(5)

Definition 3 (see [15]). The Caputo derivative of a function $\mathfrak{z}(\xi, \eta)$ on $(0, L) \times (0, T)$ is defined as follows

$${}_{0}^{C}\mathcal{D}_{\eta}^{\alpha}\mathfrak{z}(\xi,\eta) = \frac{1}{\Gamma(1-\alpha)} \int_{0}^{\eta} (\eta-\tau)^{-\alpha}\mathfrak{z}'(\xi,\tau)d\tau, 0 < \alpha < 1.$$
(6)

With respect to these definitions, we have the following properties

$${}^{\mathrm{RL}}_{0}\mathcal{J}^{\alpha C}_{\eta_{0}}\mathcal{D}^{\alpha}_{\eta}\mathfrak{z}(\xi,\eta) = \mathfrak{z}(\xi,\eta) - \mathfrak{z}(\xi,0), 0 < \alpha < 1, 0.4 \mathrm{cm}, \quad (7)$$

$${}_{0}^{C}\mathcal{D}_{\eta}^{\alpha}c=0, \quad c=\text{constant}, \tag{8}$$

$${}_{0}^{C}\mathcal{D}_{\eta}^{\alpha}\eta^{m} = \begin{pmatrix} 0, & m = 0, \\ \frac{\Gamma(m+1)}{\Gamma(m+1-\alpha)}\eta^{m-\alpha}, & m = 1, 2, \cdots. \end{pmatrix}$$
(9)

The following relation can be used to construct Pell polynomials: [42]:

$$\mathscr{P}_{l+2}(\xi) = 2\xi \mathscr{P}_{l+1}(\xi) + \mathscr{P}_{l}(\xi), \ \mathscr{P}_{0}(\xi) = 0, \ \mathscr{P}_{1}(\xi) = 1.$$
(10)

According to [42], $\mathscr{P}_{n}(\xi)$ has the following form

$$\mathscr{P}_{l}(\xi) = \sum_{k=0}^{\lfloor l-1/2 \rfloor} {\binom{l-k-1}{k}} (2\xi)^{l-2k-1}.$$
(11)

We can represent a continuous function $\mathscr{V}(\xi)$ via the Pell polynomials as follows:

$$\mathscr{V}(\xi) \approx \mathscr{V}_{K}(\xi) = \sum_{i=0}^{K} \bar{\nu}_{i+1} \mathscr{P}_{i+1}(\xi) = \mathscr{V}^{T} \mathscr{P}_{K}(\xi), \qquad (12)$$

where

$$\mathscr{V} = [\bar{\nu}_1, \bar{\nu}_2, \cdots, \bar{\nu}_{K+1}]^T, \mathscr{P}_K(\xi) = [\mathscr{P}_1(\xi), \mathscr{P}_2(\xi), \cdots, \mathscr{P}_{K+1}(\xi)]^T.$$
(13)

Analogously, a function $\mathcal{V}(\xi, \eta)$ defined on $[0, L] \times [0, T]$ may be described as follows:

$$\begin{aligned} \mathscr{V}(\xi,\eta) &\approx \mathscr{V}_{KJ}(\xi) = \sum_{i=0}^{K} \sum_{j=0}^{J} \bar{\nu}_{i+1,j+1} \mathscr{P}_{i+1}(\xi) \mathscr{P}_{j+1}(\eta) \\ &= \mathscr{P}_{K}(\xi)^{T} \mathscr{W} \mathscr{P}_{J}(\eta) = \mathscr{V}^{T} \mathscr{P}_{KJ}(\xi,\eta), \end{aligned}$$
(14)

and \mathcal{W} denotes a matrix of suitable dimensions, as well as \mathcal{V} and $\mathcal{P}_{KJ}(\xi, \eta)$ are the following:

$$\mathscr{V} = \left[\bar{v}_{11}, \bar{v}_{12}, \cdots, \bar{v}_{1J+1}, \bar{v}_{21}, \cdots, \bar{u}_{2J+1}, \cdots, \bar{v}_{K1}, \cdots, \bar{v}_{K+1J+1}\right]^{T},$$
(15)

$$\mathcal{P}_{KJ}(\xi,\eta) = \left[\mathcal{P}_{11}(\xi,\eta), \cdots, \mathcal{P}_{1J+1}(\xi,\eta), \mathcal{P}_{21}(\xi,\eta), \cdots, \mathcal{P}_{2J+1} \\ \cdot (\xi,\eta), \cdots, \mathcal{P}_{K+11}(\xi,\eta), \cdots, \mathcal{P}_{K+1J+1}(\xi,\eta)\right]^{T}.$$
(16)

We may also rephrase $\mathscr{P}_{K}(\xi), \mathscr{P}_{J}(\eta)$ in the following way:

$$\mathscr{P}_{K}(\xi) = \mathscr{Q}_{\xi}\mathscr{T}(\xi), \qquad (17)$$

$$\mathscr{P}_{J}(\eta) = \mathscr{Q}_{\eta} \mathscr{T}(\eta), \tag{18}$$

$$\mathcal{T}(\boldsymbol{\xi}) = \begin{bmatrix} 1, \boldsymbol{\xi}, \dots, \boldsymbol{\xi}^K \end{bmatrix}^T, \mathcal{T}(\boldsymbol{\eta}) = \begin{bmatrix} 1, \boldsymbol{\eta}, \dots, \boldsymbol{\eta}^I \end{bmatrix}^T,$$
(19)

where

$$\mathcal{Q}_{\xi} = \begin{pmatrix} a_{0,0} & 0 & 0 & 0 & \cdots & 0 \\ 0 & a_{1,1} & 0 & 0 & \cdots & 0 \\ a_{2,0} & 0 & a_{2,2} & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{K,1} & 0 & a_{K,3} & \cdots & 0 & a_{K,K} \end{pmatrix},$$

$$\mathcal{Q}_{\eta} = \begin{pmatrix} a_{0,0} & 0 & 0 & 0 & \cdots & 0 \\ 0 & a_{1,1} & 0 & 0 & \cdots & 0 \\ a_{2,0} & 0 & a_{2,2} & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{J,1} & 0 & a_{J,3} & \cdots & 0 & a_{J,J} \end{pmatrix},$$
(20)

with

$$(a_{i,j}) = \begin{cases} \left(\begin{array}{c} i - \left\lfloor \frac{i-j}{2} \right\rfloor \\ \left\lfloor \frac{i-j}{2} \right\rfloor \end{array} \right) 2^{i-2 \left\lfloor \frac{i+j}{2} \right\rfloor}, & \text{if } i \ge j, i, j = odd \text{ or } i, j = even \\ 0, & otherwise. \end{cases}$$

$$(21)$$

3. Analysis of the Numerical Method

Here, we find several operational matrices with the help of Pell polynomials, which are useful in developing the suggested technique.

To begin, we estimate the fractional operator as follows:

$$\begin{split} & \overset{C}{}_{0} \mathscr{D}_{\eta}^{\alpha} \mathscr{V}(\xi,\eta) \approx \overset{C}{}_{0} \mathscr{D}_{\eta}^{\alpha} \mathscr{V}_{KJ}(\xi,\eta) \\ & = \overset{C}{}_{0} \mathscr{D}_{\eta}^{\alpha} \mathscr{P}_{K}(\xi)^{T} \mathscr{W} \mathscr{P}_{J}(\eta) = \mathscr{P}_{K}(\xi)^{T} \mathscr{W} \begin{pmatrix} ^{C}_{0} \mathscr{D}_{\eta}^{\alpha} \mathscr{P}_{J}(\eta) \end{pmatrix} \\ & = \mathscr{P}_{K}(\xi)^{T} \mathscr{W} \begin{pmatrix} ^{C}_{0} \mathscr{D}_{\eta}^{\alpha} \mathscr{Q}_{\eta} \mathscr{T}(\eta) \end{pmatrix}, \end{split}$$
(22)

$$=\mathscr{P}_{K}(\xi)^{T}\mathscr{W}\mathscr{Q}_{\eta}\binom{C}{0}\mathscr{D}_{\eta}^{\alpha}T(\eta)\Big).$$
(23)

Thanks to using relation (9), we obtain

$${}_{0}^{C}\mathcal{D}_{\eta}^{\alpha}\mathcal{V}_{KJ}(\xi,\eta) = \mathcal{P}_{K}(\xi)^{T}\mathcal{W}\mathcal{Q}_{\eta}\left[0,\frac{\Gamma(2)}{\Gamma(2-\alpha)}\eta^{1-\alpha},\frac{\Gamma(3)}{\Gamma(3-\alpha)}\eta^{2-\alpha},\cdots,\frac{\Gamma(J+1)}{\Gamma(J+1-\alpha)}\eta^{J-\alpha}\right]^{T},$$
(24)

$$=\mathscr{P}_{K}(\xi)^{T}\mathscr{W}\mathscr{Q}_{\eta}\begin{pmatrix} 0 & 0 & 0 & \cdots & 0 \\ 0 & \frac{\Gamma(2)}{\Gamma(2-\alpha)}\eta^{-\alpha} & 0 & \cdots & 0 \\ 0 & 0 & \frac{\Gamma(3)}{\Gamma(3-\alpha)}\eta^{-\alpha} & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & \frac{\Gamma(J+1)}{\Gamma(J+1-\alpha)}\eta^{-\alpha} \end{pmatrix}\begin{pmatrix} 1 \\ \eta \\ \eta^{2} \\ \vdots \\ \eta^{J} \end{pmatrix},$$
(25)
$$=\mathscr{P}_{K}(\xi)^{T}\mathscr{W}\mathscr{Q}_{\eta}\mathscr{M}_{\alpha}\mathscr{Q}_{\eta}^{-1}\mathscr{P}_{J}(\eta),$$
(26)

where

$$\mathcal{M}_{\alpha} = \operatorname{diag}\left(0, \frac{\Gamma(2)}{\Gamma(2-\alpha)} \eta^{-\alpha}, \frac{\Gamma(3)}{\Gamma(3-\alpha)} \eta^{-\alpha}, \cdots, \frac{\Gamma(J+1)}{\Gamma(J+1-\alpha)} \eta^{-\alpha}\right).$$
(27)

$${}_{0}^{C}\mathcal{D}_{\eta}^{\alpha}\mathcal{V}(\xi,\eta) \approx \mathcal{P}_{K}(\xi)^{T}\mathcal{W}\mathcal{Q}_{\eta}\mathcal{M}_{\alpha}\mathcal{Q}_{\eta}^{-1}\mathcal{P}_{J}(\eta).$$
(28)

Next, we approximate the nonlinear and integro–differential terms in equation (1). First, we compute $\mathcal{P}_{K}{}'(\xi)$ and $\mathcal{P}_{K}{}''(\xi)$.

$$\mathcal{P}'_{K}(\xi) = \mathcal{Q}_{\xi}\mathcal{T}'(\xi) = \mathcal{Q}_{\xi} \begin{pmatrix} 0 \\ 1 \\ 2\xi \\ \vdots \\ K\xi^{K-1} \end{pmatrix}$$

$$= \mathcal{Q}_{\xi} \begin{pmatrix} 0 & 0 & 0 & 0 & \cdots & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & \cdots & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & \cdots & 0 & 0 & 0 \\ 0 & 0 & 3 & 0 & \cdots & 0 & 0 & 0 \\ \vdots & \vdots \\ 0 & 0 & 0 & 0 & \cdots & 0 & N & 0 \end{pmatrix} \begin{pmatrix} 1 \\ \xi \\ \xi^{2} \\ \vdots \\ \xi^{K} \end{pmatrix}, \quad (29)$$

$$= \mathcal{Q}_{\xi} \mathcal{D}' \mathcal{T}(\xi) = \mathcal{Q}_{\xi} \mathcal{D}' \mathcal{Q}_{\xi}^{-1} \mathcal{P}_{K}(\xi), \quad (30)$$

where

$$\mathcal{D}' = \begin{pmatrix} 0 & 0 & 0 & 0 & \cdots & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & \cdots & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & \cdots & 0 & 0 & 0 \\ 0 & 0 & 3 & 0 & \cdots & 0 & 0 & 0 \\ \vdots & \vdots \\ 0 & 0 & 0 & 0 & \cdots & 0 & N & 0 \end{pmatrix}.$$
 (31)

ſ

Similarly, we obtain

$$\mathscr{P}_{K}^{\prime \prime}(\xi) = \mathscr{Q}_{\xi} \mathscr{T}^{\prime \prime}(\xi) = \mathscr{Q}_{\xi} \mathscr{D}^{\prime \prime} \mathscr{Q}_{\xi}^{-1} \mathscr{P}_{K}(\xi), \qquad (32)$$

where $\mathcal{D}'' = (d_{i,j})_{1 \le i,j \le K+1}$.

$$(d_{i,j}) = \begin{pmatrix} (i-1)(i-2), i \ge 3 &, j = i-2, \\ 0, & \text{otherwise.} \end{cases}$$
 (33)

If we use (30), we get

$$\mathcal{V}(\xi,\eta)\mathcal{V}_{\xi}(\xi,\eta) \approx \mathcal{V}_{KJ}(\xi,\eta)\mathcal{V}_{KJx}(\xi,\eta)$$

= $\mathcal{P}_{K}(\xi)^{T}\mathcal{W}\mathcal{P}_{J}(\eta)\mathcal{P}_{K}(\xi)^{T}\mathcal{Q}_{\xi}^{-T}\mathcal{D}'^{T}\mathcal{Q}_{\xi}^{T}\mathcal{W}\mathcal{P}_{J}(\eta).$ (34)

For integro-differential term, using (32), we have

$$\int_{0}^{\eta} (\eta - s)^{\beta - 1} \mathscr{V}_{\xi\xi}(\xi, s) \mathrm{d}s \approx \int_{0}^{\eta} (\eta - s)^{\beta - 1} \mathscr{P}_{K}'(\xi)^{T} \mathscr{W} \mathscr{P}_{J}(s) \mathrm{d}s$$

$$= \int_{0}^{\eta} (\eta - s)^{\beta - 1} \left(\mathscr{Q}_{\xi} \mathscr{D}' \mathscr{Q}_{\xi}^{-1} \mathscr{P}_{K}(\xi) \right)^{T} \mathscr{W} \mathscr{P}_{J}(s) \mathrm{d}s,$$
(35)

$$=\mathscr{P}_{K}(\xi)^{T}\mathscr{Q}_{\xi}^{-T}\mathscr{D}^{\prime}{'}^{T}\mathscr{Q}_{\xi}^{T}\mathscr{W}\int_{0}^{\eta}(\eta-s)^{\beta-1}\mathscr{Q}_{\eta}\mathscr{T}(s)\mathrm{d}s,\qquad(36)$$

-

$$=\mathscr{P}_{K}(\xi)^{T}\mathscr{Q}_{\xi}^{-T}\mathscr{D}^{\prime}{'}^{T}\mathscr{Q}_{\xi}^{T}\mathscr{W}\mathscr{Q}_{\eta}\int_{0}^{\eta}\frac{\left[1,s,\cdots,s^{J}\right]^{T}}{\left(\eta-s\right)^{1-\beta}}\mathrm{d}s.$$
(37)

On the other hand, the following relationship is valid:

$$\int_{0}^{\eta} \frac{\xi^{k}}{(\eta - \xi)^{1 - \beta}} d\xi = \frac{\Gamma(k + 1)\Gamma(\beta)}{\Gamma(k + \beta + 1)} \eta^{k + \beta}, 0 < \beta < 1, k = 0, 1, 2, \cdots.$$
(38)

So, by substituting (38) into (37), we have

$$= \mathscr{P}_{K}(\xi)^{T} \mathscr{Q}_{\xi}^{-T} \mathscr{D}'^{T} \mathscr{Q}_{\xi}^{T} \mathscr{P}_{Q}^{T} \mathscr{Q}_{\xi}^{T} \mathscr{P}_{Q}^{T} \mathscr{Q}_{\xi}^{T} \mathscr{P}_{Q}^{T} \mathscr{Q}_{\xi}^{T} \mathscr{P}_{Q}^{T} \mathscr{Q}_{\xi}^{T} \mathscr{P}_{\xi}^{T} \mathscr{P}_{\xi}^{T} \mathscr{Q}_{\xi}^{T} \mathscr{P}_{\xi}^{T} \mathscr{P}_{Q}^{T} \mathscr{Q}_{\xi}^{T} \mathscr{P}_{\xi}^{T} \mathscr{P}_{Q}^{T} \mathscr{Q}_{\xi}^{T} \mathscr{P}_{\xi}^{T} \mathscr{P}_{\xi} \mathscr{P}_{\xi} \mathscr{P}_{\xi} \mathscr{P}^{T} \mathscr{P}_{\xi} \mathscr{P}_{\xi} \mathscr{P}_{\xi} \mathscr{P}_{\xi} \mathscr{P}_{\xi} \mathscr{P}_{\xi} \mathscr{P}^{T} \mathscr{P}_{\xi} \mathscr{$$

where

$$\mathcal{S} = \operatorname{diag}\left(\frac{\Gamma(\beta)}{\Gamma(\beta+1)}, \frac{\Gamma(2)\Gamma(\beta)}{\Gamma(\beta+2)}, \cdots, \frac{\Gamma(J+1)\Gamma(1-\beta)}{\Gamma(\beta+J+1)}\right),\tag{42}$$

$$\mathcal{T}^{\beta}(\eta) = \left[\eta^{\beta}, \eta^{\beta+1}, \cdots, \eta^{\beta+J}\right].$$
(43)

Hence, using relations (28), (34), and (41), as a result, we get

$$\begin{pmatrix}
\mathscr{R}_{1}(\xi,\eta) = \mathscr{P}_{K}(\xi)^{T} \mathscr{W} \mathscr{Q}_{\eta} \mathscr{M}_{\alpha} \mathscr{Q}_{\eta}^{-1} \mathscr{P}_{J}(\eta) + \mathscr{P}_{K}(\xi)^{T} \mathscr{W} \mathscr{P}_{J}(\eta) \mathscr{P}_{K}(\xi)^{T} \mathscr{Q}_{\xi}^{-T} \mathscr{D}' T \mathscr{Q}_{\xi}^{T} \mathscr{W} \mathscr{P}_{J}(\eta) - \\
\mathscr{P}_{K}(\xi)^{T} \mathscr{Q}_{\xi}^{-T} \mathscr{D}'^{T} \mathscr{Q}_{\xi}^{T} \mathscr{W} \mathscr{Q}_{\eta} \mathscr{S} \mathscr{T}^{\beta}(\eta) - \mathscr{G}(\xi,\eta) \approx 0, \\
\mathscr{R}_{2}(\xi) = \mathscr{P}_{K}(\xi)^{T} \mathscr{W} \mathscr{P}_{J}(0) - \Psi(\xi) \approx 0, \\
\mathscr{R}_{3}(\eta) = \mathscr{P}_{K}(0)^{T} \mathscr{W} \mathscr{P}_{J}(\eta) - \mathfrak{O}_{1}(\eta) \approx 0, \\
\mathscr{R}_{4}(\eta) = \mathscr{P}_{K}(L)^{T} \mathscr{W} \mathscr{P}_{J}(\eta) - \mathfrak{O}_{2}(\eta) \approx 0.
\end{cases}$$
(44)

Now, from relation (44), we create the nonlinear system below.

$$\begin{cases} \mathscr{R}_1\left(\xi_i,\eta_j\right) \approx 0 & 0 \leq i \leq K-2, 0 \leq j \leq J-1, \\ \mathscr{R}_2(\xi_i) \approx 0 & i = 0, 1, \cdots, K, \mathscr{R}_4\left(\eta_j\right) \approx 0 \\ \mathscr{R}_3\left(\eta_j\right) \approx 0 & j = 0, 1, \cdots, J-1, j = 0, 1, \cdots, J-1, \end{cases}$$

$$\tag{45}$$

where $\xi_i = (2i+1)/2K + 2$ and $\eta_j = (2j+1)/2J + 2$.

By solving this system, the unknown matrix \mathcal{W} can be determined. It is worth noting that we have used the fsolve command in Matlab.

4. Convergence

Here, we prove that the numerical scheme for solving (1)–(3) is convergent, and we follow references [43, 44]. We assume that

$$G = \operatorname{span}\{\mathscr{P}_1(\xi), \mathscr{P}_2(\xi), \cdots, \mathscr{P}_{K+1}(\xi)\},$$
(46)

$$Q = \operatorname{span} \left\{ \mathscr{P}_1(\eta), \mathscr{P}_2(\eta), \cdots, \mathscr{P}_{J+1}(\eta) \right\}, \tag{47}$$

$$G_{x} = \operatorname{span}\left\{\mathscr{P}_{1}'(\xi), \mathscr{P}_{2}'(\xi), \cdots, \mathscr{P}_{K+1}'(\xi)\right\},$$
(48)

$$G_{xx} = \operatorname{span}\left\{\mathscr{P}_{1}^{\prime\prime}(\xi), \mathscr{P}_{2}^{\prime\prime}(\xi), \cdots, \mathscr{P}_{K+1}^{\prime\prime}(\xi)\right\}.$$
(49)

$$\left\| \mathscr{V}(\xi,\eta) - \mathscr{V}_{KJ}(\xi,\eta) \right\|_{2} \le \frac{H_{1}LT(L+T)^{K+J+1}}{(K+J+1)!}, \qquad (50)$$

$$\left\| \mathscr{V}_{\xi}(\xi,\eta) - \mathscr{V}_{KJ\xi}(\xi,\eta) \right\|_{2} \le \frac{H_{2}LT(L+T)^{K+J+1}}{(K+J+1)!},$$
 (51)

$$\left\| \mathscr{V}_{\xi\xi}(\xi,\eta) - \mathscr{V}_{KJ\xi\xi}(\xi,\eta) \right\|_{2} \le \frac{H_{3}LT(L+T)^{K+J+1}}{(K+J+1)!}, \qquad (52)$$

Theorem 4. Let $\mathcal{V}(\xi, \eta) \in C^{K+J+3}([0, L] \times [0, T])$ and $\mathcal{V}_{KJ}(\xi, \eta)$, $\mathcal{V}_{KJ\xi}(\xi, \eta)$, and $\mathcal{V}_{KJ\xi\xi}(\xi, \eta)$ be the best approximations of $\mathcal{V}(\xi, \eta)$, $\mathcal{V}_{\xi}(\xi, \eta)$, and $\mathcal{V}_{\xi\xi}(\xi, \eta)$ in the spaces $G \times Q$, $G_{\xi} \times Q$, and $G_{\xi\xi} \times Q$, respectively. The following inequalities are true.

where
$$H_i = \max_{k=0,\dots,J+K+i} |\mathcal{V}^k(\xi,\eta)|.$$

 $\mathcal{V}(\xi,\eta) = \mathcal{V}(0,0) + \mathcal{V}_{\xi}(0,0)\xi + \mathcal{V}_{\eta}(0,0)\eta + \frac{1}{2!}$
 $\cdot \left(\mathcal{V}_{\xi\xi}(0,0)\xi^2 + 2\mathcal{V}_{\xi\eta}(0,0)\xi\eta + \mathcal{V}_{\eta\eta}(0,0)\eta^2\right) + \cdots,$
(53)

$$+ \frac{1}{n!} \sum_{i+j=J+K} \binom{n}{j} \mathscr{V}_{\xi^{i} \eta^{j}}(0,0) \xi^{i} \eta^{j} + R_{J+K,(0,0)}(\xi,\eta)$$

$$= P_{J+K,(0,0)}(\xi,\eta) + R_{J+K,(0,0)}(\xi,\eta),$$
(54)

where

$$R_{J+K,(0,0)}(\xi,\eta) = \frac{1}{(J+K)!} \sum_{i+j=J+K+1} \binom{J+K+1}{j} \xi^{i} \eta^{j} \\ \cdot \int_{0}^{1} \mathscr{V}_{\xi^{i} \eta^{j}}(m\xi,m\eta) (1-m)^{J+K} dm.$$
(55)

Proof. Using Taylor expansion, we have [45].

According to the best approximation theorem

$$\begin{split} \left\| \mathcal{V}(\xi,\eta) - \mathcal{V}_{JK}(\xi,\eta) \right\|_{2} &\leq \left\| \left| \mathcal{V}(\xi,\eta) - P_{J+K,(0,0)}(\xi,\eta) \right| \right\|_{2}, \end{split}$$
(56)
$$&= \left\| \frac{1}{(J+K)!} \sum_{i+j=J+K+1} \binom{J+K+1}{j} \xi^{i} \eta^{j} \int_{0}^{1} \mathcal{V}_{\xi^{i} \eta^{j}}(m\xi,m\eta)(1-m)^{K+K} dm \right\|_{2}, \end{split}$$

$$(57)$$

$$= \left(\int_{0}^{T} \int_{0}^{L} \left(\frac{1}{(J+K)!} \sum_{i+j=J+K+1} {J+K+1 \choose j} \xi^{i} \eta^{j} \right)^{1/2} \cdot \int_{0}^{1} \mathscr{V}_{\xi^{i} \eta^{j}} (m\xi, m\eta) (1-m)^{J+K} dm \right)^{2} d\xi d\eta \right)^{1/2}$$

$$\leq \left(\int_{0}^{T} \int_{0}^{L} \left(\frac{H_{1}}{(J+K+1)!} \sum_{i+j=J+K+1} {J+K+1 \choose j} \xi^{i} \eta^{j} \right)^{2} d\xi d\eta \right)^{1/2}$$

$$= \frac{H_{1}}{(J+K+1)!} \left(\int_{0}^{T} \int_{0}^{L} (\xi+\eta)^{2K+2J+2} d\xi d\eta \right)^{1/2}$$

$$\leq \frac{H_{1}LT(L+T)^{J+K+1}}{(J+K+1)!}.$$
(58)

Similarly, other inequalities can also be proved.

Theorem 5. Let $\mathcal{V}_{KJ}(\xi, \eta)$ is the exact solution and $\tilde{\mathcal{V}}_{KJ}(\xi, \eta) = \tilde{\mathcal{V}}^T P_{KJ}(\xi, \eta)$ is the approximation solution of equations (45). Then, one has

$$\begin{aligned} \left\| \mathscr{V}_{NM}(\xi,\eta) - \widetilde{\mathscr{V}}_{NM}(\xi,\eta) \right\|_{2} &\leq \left\| \mathscr{V} - \widetilde{\mathscr{V}} \right\|_{2} \\ &\cdot \sqrt{LT \sum_{r=0}^{K} \sum_{s=0}^{J} \left(\sum_{k=0}^{\lfloor \frac{s}{2} \rfloor} \binom{r-k}{k} (2L)^{r-2k} \right)^{2} \left(\sum_{k=0}^{\lfloor \frac{s}{2} \rfloor} \binom{s-k}{k} (2T)^{s-2k} \right)^{2}}. \end{aligned}$$

$$\tag{59}$$

Proof. We have

$$\begin{split} \left\| \mathscr{V}_{KJ}(\xi,\eta) - \tilde{\mathscr{V}}_{KJ}(\xi,\eta) \right\|_{2}^{2} \\ &= \int_{0}^{T} \int_{0}^{L} \left\| \mathscr{V}_{KJ}(\xi,\eta) - \tilde{\mathscr{V}}_{KJ}(\xi,\eta) \right\|_{2}^{2} d\xi d\eta = \int_{0}^{T} \int_{0}^{L} \\ &= \left| \sum_{r=0}^{K} \sum_{s=0}^{J} \left(\bar{\nu}_{r+1,s+1} - \tilde{\bar{\nu}}_{r+1,s+1} \right) \mathscr{P}_{r+1}(\xi) \mathscr{P}_{s+1}(\eta) \right|^{2} d\xi d\eta, \end{split}$$

$$\tag{60}$$

$$\leq \int_{0}^{T} \int_{0}^{L} \left(\sum_{r=0}^{K} \sum_{s=0}^{J} \left| \overline{\nu}_{r+1,s+1} - \widetilde{\overline{\nu}}_{r+1,s+1} \right|^{2} \right) \\ \cdot \left(\sum_{r=0}^{K} \sum_{s=0}^{J} \left| \mathscr{P}_{r+1}(\xi) \mathscr{P}_{s+1}(\eta) \right|^{2} \right) d\xi d\eta,$$

$$(61)$$

$$= \sum_{r=0}^{K} \sum_{s=0}^{J} \left| \bar{v}_{r+1,s+1} - \widetilde{v}_{r+1,s+1} \right|^{2} \sum_{r=0}^{K} \sum_{s=0}^{J} \int_{0}^{T} \int_{0}^{L}$$
(62)

$$\cdot \left| \mathscr{P}_{r+1}(\xi) \mathscr{P}_{s+1}(\eta) \right|^{2} d\xi d\eta,$$

$$= \left\| \mathscr{V} - \widetilde{\mathscr{V}} \right\|_{2}^{2} \sum_{r=0}^{K} \sum_{s=0}^{J} \int_{0}^{T} \int_{0}^{L} \left| \sum_{k=0}^{\lfloor \frac{r}{2} \rfloor} {r-k \choose k} 2^{r-2k} \xi^{r-2k} \right|^{2}$$

$$\cdot \left| \sum_{k=0}^{\lfloor \frac{s}{2} \rfloor} {s-k \choose k} 2^{s-2k} \eta^{s-2k} \right|^{2} d\xi d\eta$$

$$\leq \left\| \mathscr{V} - \widetilde{\mathscr{V}} \right\|_{2}^{2} \sum_{r=0}^{K} \sum_{s=0}^{J} \int_{0}^{T} \int_{0}^{L} \left| \sum_{k=0}^{\lfloor \frac{s}{2} \rfloor} {r-k \choose k} 2^{r-2k} L^{r-2k} \right|^{2}$$

$$\cdot \left\| \sum_{k=0}^{\lfloor \frac{s}{2} \rfloor} {s-k \choose k} 2^{d-2k} T^{s-2k} \right|^{2} d\xi d\eta$$

$$= \left\| \mathscr{V} - \widetilde{\mathscr{V}} \right\|_{2}^{2} LT \sum_{r=0}^{K} \sum_{s=0}^{J} \left| \sum_{k=0}^{\lfloor \frac{r}{2} \rfloor} {r-k \choose k} 2^{r-2k} L^{r-2k} \right|^{2}$$

$$\cdot \left\| \sum_{k=0}^{\lfloor \frac{s}{2} \rfloor} {s-k \choose k} 2^{s-2k} T^{s-2k} \right|^{2} .$$

So that

$$\begin{aligned} \left\| \mathscr{V}_{KJ}(\xi,\eta) - \widetilde{\mathscr{V}}_{KJ}(\xi,\eta) \right\|_{2} &\leq \left\| \mathscr{V} - \widetilde{\mathscr{V}} \right\|_{2} \\ &\cdot \sqrt{LT \sum_{r=0}^{K} \sum_{s=0}^{J} \left(\sum_{k=0}^{\left\lfloor \frac{s}{2} \right\rfloor} {r-k \choose k} (2L)^{r-2k} \right)^{2} \left(\sum_{k=0}^{\left\lfloor \frac{s}{2} \right\rfloor} {s-k \choose k} (2T)^{s-2k} \right)^{2}}. \end{aligned}$$

$$\tag{64}$$

Now, we prove that the presented numerical method is convergent. $\hfill \Box$

Theorem 6. Let $S_{KJ}(\xi, \eta)$ be the perturbation term and $\mathscr{V}_{KJ}(\xi, \eta)$ be the approximate solution to the main problem derived using the proposed approach. Then, the perturbation term tends to zero as $K, J \longrightarrow \infty$.

Proof. Thanks to (9), we deduce that

$$\begin{aligned} \mathscr{V}(\xi,\eta) &= \Psi(\xi) - {}_{0}^{RL} \mathscr{I}_{\eta}^{\alpha} \mathscr{V}(\xi,\eta) \mathscr{V}_{\xi}(\xi,\eta) \\ &+ {}_{0}^{RL} \mathscr{I}_{\eta}^{\alpha} \int_{0}^{\eta} (\eta - s)^{\beta - 1} \mathscr{V}_{\xi\xi}(\xi,s) ds + {}_{0}^{RL} \mathscr{I}_{\eta}^{\alpha} \mathscr{G}(\xi,\eta). \end{aligned}$$

$$(65)$$

Assume that $\mathcal{V}_{NM}(\xi,\eta)$ is an approximate solution of the above equation. It means that

(ξ_i, η_i)	$\alpha = 0.5, K = 11$	$\alpha = 0.5, K = 11$	$\alpha = 0.5, K = 9$	$\alpha = 0.5, K = 9$
	$\beta = 0.1, J = 4$	$\beta = 0.3, J = 4$	$\beta = 0.7, J = 4$	$\beta = 0.9, J = 4$
(0.1,0.1)	5.2665 <i>e</i> – 11	7.5026 <i>e</i> – 11	9.4157 <i>e</i> – 10	1.5935e – 09
(0.2,0.2)	8.8713 <i>e</i> – 10	7.0142e - 10	1.7084e - 09	4.5505e - 09
(0.3,0.3)	4.6062e - 09	3.6713 <i>e</i> – 09	5.8173 <i>e</i> – 08	1.3764 <i>e</i> - 09
(0.4,0.4)	1.4766e - 08	1.2353 <i>e</i> – 08	3.6620 <i>e</i> - 07	1.2902e - 07
(0.5,0.5)	3.6426 <i>e</i> – 08	3.1853 <i>e</i> – 08	1.2736 <i>e</i> – 06	6.7104e - 07
(0.6,0.6)	7.6243e - 08	6.9345e - 08	3.4065e - 06	2.2596e – 06
(0.7,0.7)	1.4258e - 07	1.3432e - 07	7.7630e - 06	6.0393 <i>e</i> – 06
(0.8,0.8)	2.4555e - 07	2.3833e - 07	1.5689 <i>e</i> – 05	1.3673 <i>e</i> – 05
(0.9,0.9)	3.8165 <i>e</i> – 07	3.7801e - 07	2.5814e - 05	2.4145e - 05
(1,1)	7.3344 <i>e</i> – 15	1.1944 <i>e</i> – 16	1.6793 <i>e</i> – 15	2.1690 <i>e</i> – 14

TABLE 1: Numerical reports in Example 1.

$$\mathcal{V}_{KJ}(\xi,\eta) = \Psi(\xi) - {}_{\eta}^{RL} \mathcal{J}_{\eta}^{\alpha} \mathcal{V}_{KJ}(\xi,\eta) \mathcal{V}_{KJ\xi}(\xi,\eta) + {}_{0}^{RL} \mathcal{J}_{\eta}^{\alpha} \int_{0}^{\eta} (\eta - s)^{\beta - 1} \mathcal{V}_{KJ\xi\xi}(\xi,s) ds \qquad (66) + {}_{0}^{RL} \mathcal{J}_{\eta}^{\alpha} \mathcal{G}(\xi,\eta) + S_{KJ}(\xi,\eta),$$

where S_{KJ} is the perturbation term. From equations (65) and (66), we have



FIGURE 1: Pictorial results in Example 1 with $\alpha = 0.5$, $\beta = 0.1$, and N = 11, M = 4.

	J = 4, K = 6	J = 4, K = 7	J = 4, K = 8	J = 4, K = 9	J = 4, K = 10
	$\ e\ _{\infty}$				
	1.7427e - 03	1.7093e - 03	3.7497e - 05	3.7046e - 05	5.5452 <i>e</i> – 07
CPU	0.7787s	1.3037s	1.4066s	1.5607s	1.9541s

(ξ_i, η_i)	$\alpha = 0.5$	$\alpha = 0.7$	$\alpha = 0.9$	$\alpha = 1$
	$\beta = 0.5$	$\beta = 0.5$	$\beta = 0.5$	$\beta = 0.5$
(0,0)	1.3878 <i>e</i> – 17	1.3878 <i>e</i> – 17	1.3878 <i>e</i> – 17	6.9389 <i>e</i> – 17
(0.1,0.1)	2.9677 <i>e</i> – 15	2.4715e – 15	2.1732e – 15	2.4820 <i>e</i> – 15
(0.2,0.2)	1.3601 <i>e</i> – 14	1.0819e - 14	8.4386 <i>e</i> – 15	8.1749 <i>e</i> – 15
(0.3,0.3)	4.2369 <i>e</i> – 14	3.3196 <i>e</i> – 14	2.4869 <i>e</i> – 14	2.1178 <i>e</i> – 14
(0.4, 0.4)	1.0748 <i>e</i> – 13	8.5140e - 14	6.4282e - 14	5.2874e - 14
(0.5,0.5)	2.2699 <i>e</i> – 13	1.8235e – 13	1.4061 <i>e</i> – 13	1.1730 <i>e</i> – 13
(0.6,0.6)	4.0491e - 13	3.2892 <i>e</i> – 13	2.5840e - 13	2.2102 <i>e</i> – 13
(0.7,0.7)	6.1083 <i>e</i> – 13	5.0086 <i>e</i> – 13	3.9917 <i>e</i> – 13	3.4946 <i>e</i> – 13
(0.8,0.8)	7.5499 <i>e</i> – 13	6.2282 <i>e</i> – 13	5.0181 <i>e</i> – 13	4.4802 <i>e</i> – 13
(0.9,0.9)	6.5503 <i>e</i> – 13	5.4298e – 13	4.4097e - 13	4.0014e - 13
(1,1)	7.5493 <i>e</i> – 16	3.3867 <i>e</i> – 16	1.0991 <i>e</i> – 15	1.0437 <i>e</i> – 15

TABLE 4: Norm of errors for $\alpha = \beta = 0.5$ and CPU time in Example 2.

	J = 3, K = 3	J = 3, K = 4	J = 3, K = 5	J = 3, K = 6	J = 3, K = 7
	$\ e\ _{\infty}$				
	1.9604 <i>e</i> – 12	4.9638 <i>e</i> – 12	8.0466 <i>e</i> – 11	1.3686 <i>e</i> – 13	1.4568 <i>e</i> – 12
CPU	0.7492s	0.9354s	1.1262s	1.2330s	1.2589s



FIGURE 2: Pictorial results in Example 2 for $\alpha = 0.5$, $\beta = 0.5$ and N = M = 3.

where $\mathscr{C}_{KJ}(\xi,\eta) = \mathscr{V}(\xi,\eta) - \mathscr{V}_{KJ}(\xi,\eta)$. So that

$$\begin{split} \left\| S_{KJ}(\xi,\eta) \right\|_{2} &\leq \left\| \begin{matrix} RL \\ 0 \end{matrix} \mathcal{S}_{\eta}^{\alpha} \mathcal{V}_{KJ}(\xi,\eta) \mathcal{C}_{KJ\xi}(\xi,\eta) + \mathcal{V}_{KJ\xi}(\xi,\eta) \mathcal{C}_{NM}(\xi,\eta) \\ &+ \mathcal{C}_{KJ\xi}(\xi,\eta) \mathcal{C}_{NM}(\xi,\eta) \right\|_{2} + \left\| \mathcal{C}_{KJ}(\xi,\eta) \right\|_{2} \\ &+ \left\| \begin{matrix} RL \\ 0 \end{matrix} \mathcal{J}_{\eta}^{\alpha} \int_{0}^{\eta} (\eta - s)^{\beta - 1} \mathcal{C}_{NM\xi\xi}(\xi,\eta) ds \right\|_{2} \\ &= \|I_{1}\|_{2} + \|\mathcal{C}_{NM}(\xi,\eta)\|_{2} + \|I_{2}\|. \end{split}$$

$$(68)$$

Now, we compute $||I_1||_2$ and $||I_2||_2$.

Similarly

$$\begin{split} \|I_{2}\|_{2}^{2} &= \frac{1}{\Gamma(\alpha)^{2}} \int_{0}^{T} \int_{0}^{L} \left| \int_{0}^{\eta} \int_{0}^{\tau} (\eta - \tau)^{\alpha - 1} (\tau - s)^{\beta - 1} \mathscr{C}_{KJ\xi\xi}(\xi, s) ds d\tau \right|^{2} d\xi d\eta \\ &\leq \frac{1}{\Gamma(\alpha)^{2}} \int_{0}^{T} \int_{0}^{L} \left(\int_{0}^{\eta} \int_{0}^{\tau} (\eta - \tau)^{\alpha - 1} (\tau - s)^{\beta - 1} \left| e_{KJ\xi\xi}(\xi, s) \right| ds d\tau \right)^{2} d\xi d\eta \\ &\leq \frac{1}{\Gamma(\alpha)^{2}} \int_{0}^{T} \int_{0}^{L} \left(\int_{0}^{\eta} \int_{0}^{\tau} (\eta - \tau)^{2\alpha - 2} (\tau - s)^{2\beta - 2} ds d\tau \right) \\ &\cdot \left(\int_{0}^{\eta} \int_{0}^{\tau} \left| \mathscr{C}_{KJ\xi\xi}(\xi, s) \right|^{2} ds d\tau \right) d\xi d\eta \leq \frac{T}{\Gamma(\alpha)^{2}} \int_{0}^{T} \int_{0}^{L} ds d\xi d\eta \\ &\leq \frac{T}{\Gamma(\alpha)^{2}} \int_{0}^{T} \int_{0}^{L} \left(T^{2\beta - 1} \times t^{2\alpha - 1} \right) \int_{0}^{T} |\mathscr{C}_{KJ}(\xi, \eta)|^{2} ds d\xi d\eta \\ &= \frac{T^{2\beta}}{\Gamma(\alpha)^{2}} \left(\int_{0}^{T} \eta^{2\alpha - 1} d\eta \right) \left(\int_{0}^{T} \int_{0}^{L} |\mathscr{C}_{KJ\xi\xi}(\xi, s)|^{2} d\xi ds \right) \\ &= \frac{T^{2\beta + 2\alpha}}{\Gamma(\alpha)^{2}(2\alpha)} \left\| \mathscr{C}_{KJ\xi\xi}(\xi, \eta) \right\|_{2}^{2}. \end{split}$$

Therefore, we conclude

$$\begin{split} \left\| S_{KJ}(\xi,\eta) \right\|_{2} &\leq \sqrt{\frac{T^{2\alpha}}{\Gamma(\alpha)^{2}(2\alpha)}} \left\| \mathscr{V}_{KJ}(\xi,\eta) \mathscr{E}_{KJ\xi}(\xi,\eta) + \mathscr{E}_{KJ\xi}(\xi,\eta) \right\|_{2} \\ &+ \mathscr{V}_{KJ\xi}(\xi,\eta) \mathscr{E}_{KJ}(\xi,\eta) + \mathscr{E}_{KJ\xi}(\xi,\eta) \mathscr{E}_{KJ}(\xi,\eta) \right\|_{2} \\ &+ \left\| \mathscr{E}_{KJ}(\xi,\eta) \right\|_{2} + \sqrt{\frac{T^{2\beta+2\alpha}}{\Gamma(\alpha)^{2}(2\alpha)}} \left\| \mathscr{E}_{KJ\xi\xi}(\xi,\eta) \right\|_{2} \\ &\leq C_{1} \left\| \mathscr{V}_{KJ}(\xi,\eta) \right\|_{2} \left\| \mathscr{E}_{KJ\xi}(\xi,\eta) \right\|_{2} \\ &+ C_{1} \left\| \mathscr{V}_{KJ\xi}(\xi,\eta) \right\|_{2} \left\| \mathscr{E}_{KJ}(\xi,\eta) \right\|_{2} \\ &+ C_{1} \left\| \mathscr{E}_{KJ\xi}(\xi,\eta) \right\|_{2} \left\| \mathscr{E}_{KJ}(\xi,\eta) \right\|_{2} \\ &+ C_{2} \left\| \mathscr{E}_{KJ\xi\xi}(\xi,\eta) \right\|_{2} \\ &+ C_{2} \left\| \mathscr{E}_{KJ\xi\xi}(\xi,\eta) \right\|_{2} \leq \frac{C_{1}H_{2}LT(L+T)^{n+1}}{(n+1)!} \left\| \mathscr{V}_{KJ}(\xi,\eta) \right\|_{2} \\ &+ \frac{C_{1}H_{1}LT(L+T)^{n+1}}{(n+1)!} \left\| \mathscr{V}_{KJx}(\xi,\eta) \right\|_{2} \\ &+ \frac{C_{1}H_{1}H_{2}L^{2}T^{2}(L+T)^{2n+2}}{(n+1)^{2}} + \frac{H_{1}LT(L+T)^{n+1}}{(n+1)} \\ &+ \frac{C_{2}H_{3}LT(L+T)^{n+1}}{(n+1)}, \end{split}$$
(71)

where n = K + J. Now $S_{KJ}(\xi, \eta) \longrightarrow 0$ as $K, J \longrightarrow \infty$.

Finally, we provide a theorem about the convergence of the series of Pell polynomials. We follow Atta et al. [38, 40], Abd-Elhameed and Youssri [43, 44], and Youssri [46]. According to [47, 48], a square-integrable function $\mathscr{V}(\xi)$ on [0, 1] has the following Pell expansion

$$\mathscr{V}(\xi) = \sum_{m=0}^{\infty} \bar{\nu}_{m+1} \mathscr{P}_{m+1}(\xi), \qquad (72)$$

where

$$\bar{v}_{m} = m \sum_{s=0}^{\infty} \frac{(-1)^{s} b_{2s+m-1}}{2^{2s+m-1} (s+m)} {2s+m-1 \choose s}, b_{s} = \frac{\mathcal{V}^{s}(0)}{s!}.$$

$$_{KJ\xi}(\eta,\eta) \mathscr{C}_{KJ}(\xi,\eta) \Big\|_{2}^{2}.$$
(73)

$$\|I_1\|_2^2 \leq \frac{T^{2\alpha}}{\Gamma(\alpha)^2(2\alpha)} \|\mathscr{V}_{KJ}(\xi,\eta)\mathscr{C}_{KJ\xi}(\xi,\eta) + \mathscr{V}_{KJ\xi}(\xi,\eta)\mathscr{C}_{KJ}(\xi,\eta) + \mathscr{C}_{KJ\xi}(\eta,\eta) + \mathscr$$

Lemma 7 (see [46]). Let $I_u(z)$ denote the modified Bessel function of order u of the first kind. The following identity

TABLE 5: Numerical results in Example 3.

(ξ_i, η_i)	$\alpha = 0.1$	$\alpha = 0.4$	$\alpha = 0.6$	$\alpha = 0.8$
	$\beta = 0.1$	$\beta = 0.4$	$\beta = 0.6$	$\beta = 0.8$
(0,0)	4.7184e - 14	3.4972 <i>e</i> – 15	5.5511e – 15	3.9191 <i>e</i> – 14
(0.1,0.1)	3.0197e - 14	1.8513 <i>e</i> – 17	9.9751 <i>e</i> – 13	5.3904 <i>e</i> – 14
(0.2,0.2)	9.1656 <i>e</i> – 14	1.8249 <i>e</i> – 15	3.8079e - 12	1.1759 <i>e</i> – 12
(0.3,0.3)	1.9482 <i>e</i> – 13	2.8203e - 15	8.9047e - 12	3.4628 <i>e</i> – 12
(0.4, 0.4)	4.2674 <i>e</i> – 13	7.0777 <i>e</i> – 15	1.8213 <i>e</i> – 11	6.6157 <i>e</i> – 12
(0.5,0.5)	9.4080 <i>e</i> – 13	1.0436e - 14	3.9364 <i>e</i> – 11	1.0878e - 11
(0.6,0.6)	1.9982 <i>e</i> – 12	3.2196 <i>e</i> – 14	8.7362 <i>e</i> – 11	1.6063 <i>e</i> – 11
(0.7,0.7)	3.9228 <i>e</i> – 12	4.3965 <i>e</i> – 14	1.7459e - 10	1.9690 <i>e</i> – 11
(0.8,0.8)	6.4684e - 12	8.2379e - 14	2.8359e - 10	1.6850e - 10
(0.9,0.9)	7.9272 <i>e</i> – 12	6.1506 <i>e</i> – 14	3.2058e - 10	5.0651 <i>e</i> – 12
(1,1)	5.7618 <i>e</i> – 12	8.9421 <i>e</i> – 14	5.1744 <i>e</i> – 11	3.9714 <i>e</i> – 12









FIGURE 3: Pictorial results in Example 3 for J = 4, K = 5: (a) ($\alpha = 0.1, \beta = 0.1$), (b) ($\alpha = 0.4, \beta = 0.4$), (c) ($\alpha = 0.6, \beta = 0.6$), and (d) ($\alpha = 0.8, \beta = 0.8$).

holds:

$$\sum_{s=0}^{\infty} \frac{z^s}{s!(s+m+1)!} = t^{-m+1/2} I_{m+1} \left(2\sqrt{z} \right).$$
(74)

Lemma 8 (see [46]). The modified Bessel function of the first kind $I_u z$ satisfies the following inequality:

$$|I_u(z)| \le \frac{z^u \cos h(z)}{2^u \Gamma(u+1)}.$$
 (75)

TABLE 6: Norm of errors for $\alpha = \beta = 0.5$ and CPU time in Example 3.

	I = 5 V = 4	I = F V = F	I = F V = 6	I = 5 $V = 7$	I_E_V_9
	J = 5, K = 4	J = 5, K = 5	J = 5, K = 6	J = 5, K = 7	$J = 5, K = \delta$
	$\ e\ _{\infty}$				
	1.7474e - 13	4.6830e - 10	5.1812e - 10	2.2715e - 09	3.7225e - 08
CPU	0.6941s	1.4075s	1.4990s	1.7516s	2.1537s

TABLE 7: Numerical reports in Example 4.

(ξ_i, η_i)	J = 4	J = 4	J = 4	<i>J</i> = 4
	<i>K</i> = 6	<i>K</i> = 7	<i>K</i> = 8	<i>K</i> = 9
(0,0)	3.9549e - 20	1.9230 <i>e</i> – 22	6.7320e - 20	1.1194 <i>e</i> – 18
(0.1,0.1)	1.0519e - 10	5.3038e - 12	4.6608 <i>e</i> – 13	2.8112 <i>e</i> – 12
(0.2,0.2)	2.7128e - 09	1.4373e - 10	7.5190 <i>e</i> – 12	8.1029 <i>e</i> – 12
(0.3,0.3)	2.6072e - 08	1.4112e - 09	6.8470e - 11	1.6060 <i>e</i> – 11
(0.4, 0.4)	1.0383e - 07	5.6159 <i>e</i> – 09	2.7027e - 10	3.5035e – 11
(0.5,0.5)	2.8045e - 07	1.5208e - 08	7.3186 <i>e</i> – 10	8.5052 <i>e</i> – 11
(0.6,0.6)	6.1575e - 07	3.3347e - 08	1.6119 <i>e</i> – 09	1.9935 <i>e</i> – 10
(0.7,0.7)	1.2047e - 06	6.5140e - 08	3.1553 <i>e</i> – 09	4.1556 <i>e</i> – 10
(0.8,0.8)	2.1149e - 06	1.1777e - 07	5.7928 <i>e</i> – 09	7.3660 <i>e</i> – 10
(0.9,0.9)	2.8168e - 06	1.7066e - 07	8.9641 <i>e</i> - 09	9.7501 <i>e</i> – 10
(1,1)	1.3234e - 14	2.6645 <i>e</i> – 15	1.0658e - 14	3.5527 <i>e</i> – 15

TABLE 8: Norm of errors for $\alpha = \beta = 0.5$ and CPU time in Example 4.

	J = 4, K = 5	J = 4, K = 6	J = 4, K = 7	J = 4, K = 8	J = 4, K = 9
	$\ e\ _{\infty}$				
	5.4599e - 05	3.6853e - 06	2.2397e - 07	1.1841e - 08	1.2327e - 09
CPU	0.6648s	1.3185s	1.2689s	1.3789s	1.5100s

J	Κ	$\left\ e \right\ _2$
4	5	3.0728e - 05
4	6	2.0621e - 06
4	7	1.1742e - 07
4	8	6.0069 <i>e</i> - 09
4	9	7.7425e - 10

Theorem 9. Suppose $\mathcal{V}(x) \in L^2[0, 1]$, $\mathcal{V}^{(i)}(0) \leq L^i, i \geq 0$, where L is a positive constant and $\mathcal{V}(x) = \sum_{m=0}^{\infty} \bar{v}_{m+1} \mathcal{P}_{m+1}(x)$. Then

$$|\bar{\nu}_{m+1}| \le \frac{L^m \cos hL}{2^m m!},\tag{76}$$

and the approximate solution series converges absolutely. Also, if $E_K(\xi) = \sum_{m=K+1}^{\infty} \overline{v}_{m+1} \mathscr{P}_{m+1}(\xi)$, the following

error estimation is satisfied

$$|E_{K}(\xi)| \le \frac{\cos h(L)e^{L/2} \left(\frac{L}{2}\right)^{K+1}}{(K+1)!}.$$
(77)

Proof. From (73), Lemma (7), and Lemma (8), we have

$$\begin{split} |\bar{v}_{m+1}| &= (m+1) \left| \sum_{s=0}^{\infty} \frac{(-1)^{s} \mathcal{V}^{(2s+m)}(0)}{2^{2s+m} (s+m+1)(2s+m)} \binom{2s+m}{s} \right| \\ &= (m+1) \left| \sum_{s=0}^{\infty} \frac{(-1)^{s} \mathcal{V}^{(2s+m)}(0)}{2^{2s+m} (s+m+1)s(s+m)} \right| = (m+1) \left| \sum_{s=0}^{\infty} \frac{(-1)^{s} \mathcal{V}^{(2s+m)}(0)}{2^{2s+m} s(s+m+1)} \right| \\ &\leq (m+1) \sum_{s=0}^{\infty} \frac{L^{2s+m}}{2^{2s+m} s(s+m+1)} = (s+1) \times \left(\frac{L}{2} \right)^{m} \sum_{s=0}^{\infty} \frac{(L^{2}/2^{2})^{s}}{s(s+m+1)} \\ &\leq (m+1) \times \left(\frac{L}{2} \right)^{m} \times \left(\frac{L^{2}}{2^{2}} \right)^{-m+1/2} \times I_{m+1} \left(\frac{2L}{2} \right) = \frac{2(m+1)}{L} I_{m+1}(L) \\ &\leq \frac{2(m+1)}{L} \times \frac{L^{m+1} \cos hL}{2^{m+1} \Gamma(m+2)} = \frac{L^{k} \cos hL}{2^{m} m}. \end{split}$$

$$(78)$$



FIGURE 4: Pictorial results in Example 4 for $\alpha = 0.5$, $\beta = 0.5$ and K = 9, J = 4.

TABLE 10: Norm of errors for $\alpha = 0.5$, $\beta = 0.5$ in Example 5.

		$\alpha = \beta = 0.3$	$\alpha = \beta = 0.5$	$\alpha = \beta = 0.7$	$\alpha = \beta = 0.9$
J	K	$\ e\ _2$	$\ e\ _2$	$\ e\ _2$	$\ e\ _2$
3	5	7.2576e-0 5	7.1011e-05	7.1448e-05	6.0514 <i>e</i> - 05
3	6	1.5363e-05	1.5000e - 05	1.4978e-0 5	1.3806 <i>e</i> – 05
3	7	3.8656e - 07	3.7824e-07	3.7609e - 07	3.4637 <i>e</i> - 07
3	8	5.1965e-08	5.0757e - 08	5.0432e - 08	3.9225 <i>e</i> - 08
3	9	1.1091e - 09	2.4799e - 09	1.6532e - 08	6.7070 <i>e</i> – 08

As a result, the first portion of the theorem is established. $\hfill \Box$

We now go on to the second section.

$$|\bar{\nu}_{m+1}\mathscr{P}_{m+1}(\xi)| \le \frac{L^m \cos hL}{2^m m} \mathscr{P}_{m+1}(1),$$
 (79)

additionally

$$\sum_{m=0}^{\infty} \frac{L^m}{2^m m} \mathscr{P}_{m+1}(1) = \sum_{m=0}^{\infty} \frac{L^m}{2^m m} \times \frac{\left(1+\sqrt{2}\right)^{m+1} - \left(1-\sqrt{2}\right)^{m+1}}{2\sqrt{2}}$$
$$= \sum_{m=0}^{\infty} \frac{\left(1+\sqrt{2}\right)}{2\sqrt{2}} \frac{\left(L\left(1+\sqrt{2}\right)/2\right)^m}{m}$$
$$- \sum_{m=0}^{\infty} \frac{\left(1-\sqrt{2}\right)}{2\sqrt{2}} \frac{\left(L\left(1-\sqrt{2}\right)/2\right)^m}{m!}$$
$$= \frac{\left(1+\sqrt{2}\right)}{2\sqrt{2}} e^{L(1+\sqrt{2})/2} - \frac{\left(1-\sqrt{2}\right)}{2\sqrt{2}} e^{L(1-\sqrt{2})/2}.$$
(80)

As a result, we can conclude that the series is absolutely convergent using the comparison test.

For the third part, we have

$$E_{K}(\xi)| \le \cos h(L) \sum_{m=K+1}^{\infty} \frac{L^{m}}{2^{m}m} = \cos h(L) \sum_{m=K+1}^{\infty} \frac{(L/2)^{m}}{m}$$
$$= \cos h(L) \frac{\gamma(K+1, (L/2))}{\Gamma(K+1)} e^{L/2},$$
(81)

where $\gamma(K + 1, L/2)$ is the lower incomplete gamma function [49], then

$$|E_{K}(\xi)| \le \cos h(L) \frac{e^{L/2}}{\Gamma(K+1)} \int_{0}^{L/2} \eta^{K} e^{-\eta} d\eta \le \frac{\cos h(L) e^{L/2} \left(\frac{L}{2}\right)^{k+1}}{\Gamma(K+1)}.$$
(82)

5. Numerical Experiments

Five test problems are offered in this part to demonstrate the correctness and validity of the presented method. On a Windows 10 (64 bit) Intel(R) Core(TM) i7-7500U CPU operating at 2.70 GHz with 8.0 GB of RAM, all computations are done with Matlab R2020b software. In all examples, we use the L_{∞} error norm and L_2 error norm

$$\|e\|_{\infty} = \max_{\substack{0 \le r \le K \\ 0 \le s \le J}} |\mathcal{V}(\xi_r, \eta_s) - \mathcal{V}_{KJ}(\xi_r, \eta_s)|, \|e\|_2 = \left(h \sum_{s=0}^n (e_s^m)^2\right)^{1/2},$$
(83)

Example 1. Consider the following nonlinear time–fractional partial integro–differential equation on $[0, 1] \times [0, 1]$ with the exact solution $\mathcal{V}(\xi, \eta) = \eta^3 \sin(\pi\xi)$

$${}^{C}_{0}\mathcal{D}^{\alpha}_{\eta}\mathcal{V}(\xi,\eta) + \mathcal{V}(\xi,\eta)\mathcal{V}_{\xi}(\xi,\eta) = \int_{0}^{\eta} (\eta-s)^{\beta-1}\mathcal{V}_{\xi\xi}(\xi,s)ds + \mathcal{G}(\xi,\eta),$$

$$(84)$$

	J = 3, K = 5	J = 3, K = 6	J = 3, K = 7	J = 3, K = 8	J = 3, K = 9
	$\ e\ _{\infty}$	$\ e\ _{\infty}$	$\ e\ _{\infty}$	$\ e\ _{\infty}$	$\ e\ _{\infty}$
	1.1228e - 04	2.3945e - 05	6.0186 <i>e</i> – 07	8.0155e - 08	4.0315e - 09
CPU	0.5944s	1.0808s	1.1061s	1.1594s	1.2277s

TABLE 11: Norm of errors for $\alpha = \beta = 0.5$ and CPU time in Example 5.



FIGURE 5: Pictorial results in Example 5 for $\alpha = 0.5$, $\beta = 0.5$ and K = 9, J = 3.

with conditions (2), (3), and

$$\mathscr{G}(\xi,\eta) = \left(\frac{6\eta^{3-\alpha}}{\Gamma(4-\alpha)} + \frac{6\pi^2\Gamma(\beta)\eta^{3+\beta}}{\Gamma(4+\beta)}\pi\eta^6\cos\left(\pi\xi\right)\right)\sin\left(\pi\xi\right).$$
(85)

We solved this problem numerically using the polynomial spectral scheme provided in this paper. We employed fsolve in Matlab to solve a nonlinear system of equations (45). Table 1 shows the absolute errors for $\alpha = 0.5$ and various β values. We can observe from this table that the recommended strategy is effective. Also, we portrayed the numerical solution and absolute error surfaces in Figure 1. Furthermore, the norm of errors and CPU times is reported in Table 2. Table 1, Table 2, and Figure 1 show that the numerical method provides acceptable results.

Example 2. Consider the following equation

$${}_{0}^{C}\mathcal{D}_{\eta}^{\alpha}\mathcal{V}(\xi,\eta) + \mathcal{V}(\xi,\eta)\mathcal{V}_{\xi}(\xi,\eta) = \int_{0}^{\eta} (\eta-s)^{\beta-1}\mathcal{V}_{\xi\xi}(\xi,s)ds + \mathcal{G}(\xi,\eta),$$
(86)

with conditions (2) and (3). The source term is taken as

$$\mathscr{G}(\xi,\eta) = \frac{2\xi(1-\xi)\eta^{2-\alpha}}{\Gamma(3-\alpha)} + \xi(1-2\xi)(1-\xi)\eta^4 + \frac{4\eta^{\beta+2}}{\beta^3 + 3\beta^2 + 2\beta},$$
(87)

and $\mathscr{V}(\xi, \eta) = \eta^2 \xi (1 - \xi)$.

The absolute errors for equal values of α , β , and K = J = 3 are illustrated in Table 3. This table shows quite revealingly

that the expressed method has good precision. In addition, we can observe from the table that only a small number of basis functions have produced the necessary outcomes. The CPU times and the norm of errors are provided in Table 4. Figure 2 shows a visualization of the approximate solution as well as absolute errors.

Example 3. Consider the following equation on $[0, 1] \times [0, 1]$:

$${}_{0}^{C}\mathcal{D}_{\eta}^{a}\mathcal{V}(\xi,\eta) + \mathcal{V}(\xi,\eta)\mathcal{V}_{\xi}(\xi,\eta) = \int_{0}^{\eta} (\eta-s)^{\beta-1}\mathcal{V}_{\xi\xi}(\xi,s)ds + \mathcal{G}(\xi,\eta),$$
(88)

with conditions (2) and (3). The source term is taken as

$$\mathscr{G}(\xi,\eta) = \frac{600\xi^{3}(1-\xi)\eta^{3-\alpha}}{\Gamma(4-\alpha)} - \frac{24\eta^{4-\alpha}}{\Gamma(5-\alpha)} + 10000\eta^{6}(1-\eta)^{2}(3-4\xi)\xi^{2}\left(\xi^{3}-\xi^{4}\right) - 600\xi(1-2\xi)\left(\frac{6\Gamma(\beta)\eta^{\beta+3}}{\Gamma(4+\beta)} - \frac{24\Gamma(\beta)\eta^{\beta+4}}{\Gamma(5+\beta)}\right).$$
(89)

The exact solution is $\mathcal{V}(\xi, \eta) = 100\xi^3\eta^3(1-\xi)(1-\eta)$.

The numerical results are reported in Table 5. We have chosen K = 4, J = 5, and for equal α and β , the obtained results are fruitful. This table confirms that the presented method has high performance and produces accurate results. For $\alpha = \beta = 0.5$ and different *J* and *K*, the norm of errors and the CPU times are provided in Table 3. The absolute error functions for equal α and β are sketched in Figure 3. These figures show that the numerical and exact solutions are almost identical (Table 6).

Example 4. Consider the following equation:

$${}_{0}^{C}\mathcal{D}_{\eta}^{\alpha}\mathcal{V}(\xi,\eta) + \mathcal{V}(\xi,\eta)\mathcal{V}_{\xi}(\xi,\eta) = \int_{0}^{\eta} (\eta-s)^{\beta-1}\mathcal{V}_{\xi\xi}(\xi,s)ds + \mathcal{G}(\xi,\eta),$$
(90)

with conditions (2), (3), and

$$\mathscr{G}(\xi,\eta) = \frac{6e^{\xi}\eta^{3-\alpha}}{\Gamma(4-\alpha)} + \eta^6 e^{2\xi} - \frac{6e^{\xi}\Gamma(\beta)\eta^{\beta+3}}{\Gamma(4+\beta)}.$$
 (91)

The exact solution is $\mathscr{V}(\xi, \eta) = \eta^3 e^{\xi}$.

The absolute errors for $\alpha = \beta = 0.5$ are presented in Table 7. Table 8 illustrates the norm of errors and CPU times for $\alpha = \beta = 0.5$ with various *J* and *K* values. Table 9 also contains data on L_2 errors. Numerical solutions and pointwise error graphs are demonstrated in Figure 4. This figure shows the behavior of the numerical solution and the error function. Numerical results are in good settlement with theoretical results.

Example 5. Finally, we investigate the following equation on $[0, 1] \times [0, 1]$

$$\int_{0}^{C} \mathcal{D}_{\eta}^{a} \mathcal{V}(\xi,\eta) + \mathcal{V}(\xi,\eta) \mathcal{V}_{\xi}(\xi,\eta) = \int_{0}^{\eta} (\eta-s)^{\beta-1} \mathcal{V}_{\xi\xi}(\xi,s) ds + \mathcal{G}(\xi,\eta),$$
(92)

with conditions (2) and (3). The source term is taken as

$$\mathscr{G}(\xi,\eta) = \frac{2(1-\xi)\cos\xi\eta^{2-\alpha}}{\Gamma(3-\alpha)} + \eta^4(1-\xi)\cos\xi(-\sin\xi-\cos\xi+\xi\sin\xi) - (2\sin\xi+(\xi-1)\cos\xi)\frac{2\Gamma(\beta)\eta^{\beta+2}}{\Gamma(3+\beta)},$$
(93)

and $\mathscr{V}(\xi, \eta) = \eta^2 (1 - \xi) \cos \xi$.

In Table 10, the L_2 error is computed for $\alpha = \beta = 0.5$ and different *N* and *M*. Table 11 also shows the norm of errors and CPU times. Figure 5 shows the numerical solution and absolute error plots. This figure shows that for K = 9 and J = 4, the numerical solution is close to the exact solution. Table 10, Table 11, and Figure 5 affirm the validity and efficacy of the presented method.

6. Conclusions

The purpose of this study was to suggest a collocation approach for solving a nonlinear TFPIDE based on Pell polynomials. In the Caputo sense, the fractional derivative is considered. The equation's solution was expressed as a series of Pell polynomials with two variables. An algebraic system of nonlinear equations is obtained using the numerical technique. We proved that the method is convergent. Five test problems are provided to show that the method is efficacious. In numerical results, a small number of basis Pell polynomials is used to obtain good accuracy. In all examples, the CPU time was about one second. All of the tables and graphs demonstrated that the strategy is effective.

Data Availability

All results have been obtained by conducting the numerical procedure and the ideas can be shared for the researchers.

Conflicts of Interest

The authors declare that they have no conflicts of interest.

References

- H. Dutta, A. Akdemir, and A. Atangana, *Fractional Order* Analysis: Theory, Methods and Applications, John Wiley and Sons Ltd, 2020.
- [2] D. Kumar and J. Singh, *Fractional Calculus in Medical and Health Science*, Taylor & Francis Group, LLC, 2020.
- [3] G. A. Anastassiou, *Generalized Fractional Calculus: New Advancements and Applications*, Springer, 2020.
- [4] J. C. Trigeassou and N. Maamri, Analysis, Modeling and Stability of Fractional Order Differential Systems 2, John Wiley & Sons, 2019.
- [5] R. Caponetto, G. Dongola, I. Fortuna, and I. Petras, *Fractional Order Systems: Modeling and Control Applications*, World Scientific, 2010.
- [6] A. E. Matouk, "Advanced applications of fractional differential operators to science and technology," *IGI Global*, 2020.
- [7] D. Baleanu and A. M. Lopes, Handbook of Fractional Calculus with Applications, Volume 7 Applications in Engineering, Life and Social Sciences, Part A, de Gruyter, 2019.
- [8] X. J. Yang, F. Gao, and Y. Ju, *General Fractional Derivatives* with Applications in Viscoelasticity, Academic Press, 2020.
- [9] E. Shishkina and S. Sitnik, *Transmutations, Singular and Fractional Differential Equations with Applications to Mathematical Physics*, Academic Press, 2020.
- [10] A. Atangana, Fractional Operators with Constant and Variable Order with Application to Geo-Hydrology, Academic Press, 2017.
- [11] D. Valerio and M. D. Ortigueira, *Fractional Signals and Systems*, de Gruyter, 2020.
- [12] M. M. Meerschaert and A. Sikorskii, Stochastic Models for Fractional Calculus, de Gruyter, 2019.
- [13] P. Ostalczyk, D. Sankowski, and J. Nowakowski, On-Integer Order Calculus and Its Applications, Springer, 2019.
- [14] H. Fallahgoul, S. Focardi, and F. Fabozzi, *Fractional Calculus* and Fractional Processes with Applications to Financial Economics: Theory and Application, Academic Press, 2017.
- [15] Z. Z. Sun and G. Gao, Fractional Differential Equations: Finite Difference Methods, Walter de Gruyter GmbH & Co KG, 2020.
- [16] C. Li and F. Zeng, Numerical Methods for Fractional Calculus, Chapman and Hall/CRC, 2019.
- [17] W. M. Abd-Elhameed and Y. H. Youssri, "Sixth-kind Chebyshev spectral approach for solving fractional differential equations," *Int. J. Nonlin. Sci. Num.*, vol. 20, no. 2, pp. 191–203, 2019.

- [18] W. M. Abd-Elhameed, "Novel expressions for the derivatives of sixth kind Chebyshev polynomials: spectral solution of the non-linear one-dimensional Burgers' equation," *Fractal and Fractional*, vol. 5, no. 2, p. 53, 2021.
- [19] W. M. Abd-Elhameed and Y. H. Youssri, "New formulas of the high-order derivatives of fifth-kind Chebyshev polynomials: spectral solution of the convectionâ€'diffusion equation," *Numerical Methods for Partial Differential Equations*, pp. 1– 17, 2021.
- [20] M. Samiee, E. Kharazmi, M. M. Meerschaert, and M. Zayernouri, "A unified Petrov–Galerkin spectral method and fast solver for distributed-order partial differential equations," *Communications on Applied Mathematics and Computation*, vol. 3, no. 1, pp. 61–90, 2021.
- [21] M. Jani, E. Babolian, and D. Bhatta, "A Petrov–Galerkin spectral method for the numerical simulation and analysis of fractional anomalous diffusion," *Mathematical Methods in the Applied Sciences*, vol. 44, no. 2, pp. 2021–2032, 2021.
- [22] B. Guo, X. Pu, and F. Huang, Fractional Partial Differential Equations and Their Numerical Solutions, World Scientific, 2015.
- [23] S. S. Ray, Nonlinear Differential Equations in Physics: Novel Methods for Finding Solutions, Springer, 2020.
- [24] H. Wang, D. Xu, J. Zhou, and J. Guo, "Weak Galerkin finite element method for a class of time fractional generalized Burgers' equation," *Numerical Methods for Partial Differential Equations*, vol. 37, no. 1, pp. 732–749, 2021.
- [25] Y. Zheng and Z. Zhao, "The time discontinuous space-time finite element method for fractional diffusion-wave equation," *Applied Numerical Mathematics*, vol. 150, pp. 105–116, 2020.
- [26] M. Dehghan, J. Manafian, and A. Saadatmandi, "Solving nonlinear fractional partial differential equations using the homotopy analysis method," *International Journal*, vol. 26, no. 2, pp. 448–479, 2010.
- [27] O. Nikan, Z. Avazzadeh, and J. A. T. Machado, "An efficient local meshless approach for solving nonlinear time-fractional fourth-order diffusion model," *Journal of King Saud University-Science*, vol. 33, no. 1, article 101243, 2021.
- [28] F. Safari and P. Azarsa, "Backward substitution method based on Müntz polynomials for solving the nonlinear space fractional partial differential equations," *Mathematical Methods in the Applied Sciences*, vol. 43, no. 2, pp. 847–864, 2020.
- [29] H. C. Yaslan, "Legendre collocation method for the nonlinear space-time fractional partial differential equations," *Iranian Journal of Science and Technology, Transactions A: Science*, vol. 44, no. 1, pp. 239–249, 2020.
- [30] J. Shen, T. Tang, and L. L. Wang, Spectral Methods: Algorithms, Analysis and Applications, Springer Science & Business Media, 2011.
- [31] C. Canuto, M. Y. Hussaini, A. Quarteroni, and T. A. Zang, *Spectral Methods in Fluid Dynamics*, Springer Science & Business Media, 2012.
- [32] P. Agarwal, A. A. El-Sayed, and J. Tariboon, "Vieta-Fibonacci operational matrices for spectral solutions of variable-order fractional integro-differential equations," *Journal of Computational and Applied Mathematics*, vol. 382, article 113063, 2021.
- [33] N. Moshtaghi and A. Saadatmandi, "Polynomial-Sinc collocation method combined with the Legendre-Gauss quadrature rule for numerical solution of distributed order fractional differential equations," *Revista de la Real Academia de Ciencias*

Exactas, FÃ-sicas y Naturales. Serie A. MatemÃ_iticas, vol. 115, no. 2, pp. 1–23, 2021.

- [34] M. Abbaszadeh, M. Dehghan, and Y. Zhou, "Crank-Nicolson/ Galerkin spectral method for solving two-dimensional timespace distributed-order weakly singular integro-partial differential equation," *Journal of Computational and Applied Mathematics*, vol. 374, article 112739, 2020.
- [35] X. Zheng, W. Qiu, and H. Chen, "Three semi-implicit compact finite difference schemes for the nonlinear partial integrodifferential equation arising from viscoelasticity," *International Journal of Modelli ng and Simulation*, vol. 41, no. 3, pp. 234–242, 2021.
- [36] J. M. Sanz-Serna, "A numerical method for a partial integrodifferential equation," *SIAM Journal on Numerical Analysis*, vol. 25, no. 2, pp. 319–327, 1988.
- [37] J. Guo, D. Xu, and W. Qiu, "A finite difference scheme for the nonlinear time-fractional partial integro-differential equation," *The European Physical Journal Plus*, vol. 136, no. 1, pp. 1–30, 2021.
- [38] A. G. Atta, G. M. Moatimid, and Y. H. Youssri, "Generalized Fibonacci operational collocation approach for fractional initial value problems," *International Journal of Applied and Computational Mathematics*, vol. 5, no. 1, pp. 1–11, 2019.
- [39] A. G. Atta, W. M. Abd-Elhameed, G. M. Moatimid, and Y. H. Youssri, "Shifted fifth-kind Chebyshev Galerkin treatment for linear hyperbolic first- order partial differential equations," *Applied Numerical Mathematics*, vol. 167, pp. 237–256, 2021.
- [40] A. G. Atta, G. M. Moatimid, and Y. H. Youssri, "Generalized Fibonacci operational tau algorithm for fractional Bagley-Torvik equation," *Prog. Fract. Differ. Appl*, vol. 6, no. 3, pp. 215–224, 2020.
- [41] M. Taghipour and H. Aminikhah, "Application of Pell collocation method for solving the general form of time-fractional burgers equations," *Mathematical Sciences*, vol. 1-19, 2022.
- [42] A. F. Horadam and J. M. Mahon, "Pell and Pell-Lucas polynomials," *The Fibonacci Quarterly*, vol. 23, no. 1, pp. 7–20, 1985.
- [43] W. M. Abd-Elhameed and Y. H. Youssri, "Spectral tau algorithm for certain coupled system of fractional differential equations via generalized Fibonacci polynomial sequence," *Iranian Journal of Science and Technology, Transactions A: Science*, vol. 43, no. 2, pp. 543–554, 2019.
- [44] W. M. Abd-Elhameed and Y. H. Youssri, "Generalized Lucas polynomial sequence approach for fractional differential equations," *Nonlinear Dynamics*, vol. 89, no. 2, pp. 1341–1355, 2017.
- [45] J. J. Callahan, Advanced Calculus: A Geometric View, Springer Science & Business Media, 2010.
- [46] Y. H. Youssri, "A new operational matrix of Caputo fractional derivatives of Fermat polynomials: an application for solving the Bagley-Torvik equation," *Adv. Difference Equ.*, vol. 2017, no. 1, pp. 1–17, 2017.
- [47] P. F. Byrd, "Expansion of analytic functions in polynomials associated with Fibonacci numbers," *Fibonacci Q.*, vol. 1, article n16, 1963.
- [48] M. Taghipour and H. Aminikhah, "A fast collocation method for solving the weakly singular fractional integro-differential equation," *Computational and Applied Mathematics*, vol. 41, no. 4, p. 142, 2022.
- [49] G. J. O. Jameson, "The incomplete gamma functions," *The Mathematical Gazette*, vol. 100, no. 548, pp. 298–306, 2016.