Research Article

Dynamic Behaviors of a Class of High-Order Fuzzy Difference Equations

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The purpose of this paper is to give the conditions for the existence and uniqueness of positive solutions and the asymptotic stability of equilibrium points for the following high-order fuzzy difference equation:

\[ x_{n+1} = \frac{A}{x_n} + \frac{1}{x_{n-1}}, \quad n = 0, 1, \ldots, \]

where \( A > 0 \).

Papaschinopoulos and Schinas [7] researched the following difference equations:

\[ x_{n+1} = A + \frac{y_n}{x_n-p}, \]
\[ y_{n+1} = A + \frac{x_n}{y_{n-q}}, \quad n = 0, 1, \ldots, \]  

where \( A, x_{-p}, x_{-p+1}, \ldots, x_0, y_{-q}, y_{-q+1}, \ldots, y_0 \) are the positive numbers and \( p \) and \( q \) are the positive integers.

In 2014, He et al. [8] studied the periodicity of the positive solutions for the following fuzzy max-difference equation:

\[ x_{n+1} = \max \left\{ \frac{A_n}{x_{n-m}}, x_{n-k} \right\}, \quad n = 0, 1, \ldots, \]  

where \( k, m \in \mathbb{N}^* \), \( A_n \) is a periodic sequence of fuzzy numbers, and initial values \( x_0, x_{-1}, \ldots, x_{-d} \) are the positive fuzzy numbers with \( d = \{k, m\} \).
Zhang et al. [9] investigated the boundedness, persistence, and asymptotic behavior of a positive fuzzy solution of the following third-order fuzzy difference equation using a generalization of division for fuzzy numbers:

\[ x_{n+1} = A + \frac{x_{n-1}}{x_{n-2}}, \quad n = 0, 1, 2, \ldots \]  
(4)

where \( A, x_0, x_1, x_2 \) are the positive fuzzy numbers.

These bright spots in the above papers deserve our learning. Moreover, in 2017, Khastan [10] discussed the following fuzzy difference equation:

\[ x_{n+1} - q = w x_n, \quad n = 0, 1, \ldots \]  
(5)

where \( \{ x_n \} \) is a sequence of the positive fuzzy numbers and \( x_0, q, w \) are the positive fuzzy numbers. In this paper, the generalization of division for the fuzzy number is used to investigate the existence, uniqueness, and global behavior of the solution.

Wang and Wang [11] analyzed the following nonlinear difference equation:

\[ x_{n+1} = \frac{ax_{n-1}x_{n-k}}{bx_{n-2} + cx_{n-t}}, \quad n = 0, 1, \ldots \]  
(6)

where the initial conditions \( x_0, x_1, \ldots, x_j \) are the positive real numbers, \( l, k, s, t \) are the nonnegative integers, \( r = \max(l, k, s, t) \), and \( a, b, c \) are the positive constants. Further, in 2017, the author in [12] investigated the asymptotic behavior of the equilibrium points for the following fuzzy difference equation:

\[ x_{n+1} = \frac{Ax_{n-1}x_{n-2}}{D + Bx_{n-3} + Cx_{n-4}}, \quad n = 0, 1, 2, \ldots \]  
(7)

where \( \{ x_n \} \) is a sequence of the positive fuzzy numbers and the parameters \( A, B, C, D \) and initial conditions \( x_0, x_1, x_2, x_3, x_4, x_5 \) are the positive fuzzy numbers. Besides, some interesting results can be found in [13–18] and the references therein.

Based on the above valuable theoretical results, this paper studies the following high-order fuzzy difference equation:

\[ x_{n+1} = \frac{Ax_{n-1}x_{n-2}}{B + \sum_{i=3}^{k} C_i x_{n-i}}, \quad n = 0, 1, 2, \ldots \]  
(8)

where \( x_n \) is a sequence of the positive fuzzy numbers and the parameters \( A, B, C_3, C_4, \ldots, C_k \) and initial conditions \( x_0, x_1, x_2, x_3, \ldots, x_i \) are the positive fuzzy numbers. The purpose of this paper is to study the asymptotic behavior of the equilibrium point of the fuzzy difference equation. The main method is to convert the fuzzy difference equation into a rational difference equation according to the fuzzy number theory, and then the properties of the solutions of the fuzzy difference equations are obtained by studying the corresponding constant difference equations. In addition, the theoretical results are verified by numerical examples.

**Remark 1.** It is well known that difference equations look simple in form, but the properties of their solutions are very complex, especially the dependence on parameters and initial values. The main contribution and innovation of this paper are as follows: (1) based on the practical application, fuzzy parameters and initial values are introduced to the known models, and the new model can better describe the objective natural phenomenon. Obviously, the model in reference [12] is a special case of the model in this paper. (2) To study the new model, some new analytical methods and techniques that is different from those mentioned in the references are obtained. (3) In this paper, the research contents are more rich than the related references. Firstly, the existence and uniqueness of positive fuzzy solutions are proved. Secondly, the nonzero equilibrium points of the corresponding ordinary difference equations which are unstable are obtained by using the linearization method. Finally, it was found that the zero trivial solution of the fuzzy difference equation (8) is asymptotically stable when the parameters of the system are positive trivial fuzzy numbers.

(4) The sufficient conditions obtained herein are new, general, and easily verifiable, which provide flexibility for the application and analysis of the high-order fuzzy difference equation.

### 2. Preliminaries and Notations

For the convenience of readers, the definitions and preliminary results related to the theoretical proof of the paper are given, see [19–23].

**Definition 1.** For a set \( B, \overline{B} \) is denoted as the closure of \( B \) and a function \( A: R \rightarrow [0, 1] \) is a fuzzy number if the following conclusions are true:

(i) \( A \) is normal, i.e., there exists \( x \in R \) such that \( A(x) = 1 \);

(ii) \( A \) is a fuzzy convex set, i.e.,

\[ A(tx_1 + (1 - t)x_2) \geq \min \{ A(x_1), A(x_2) \}, \quad \forall t \in [0, 1], x_1, x_2 \in R; \]

(iii) \( A \) is upper semicontinuous on \( R \);

(iv) The support of \( A \), i.e.,

\[ \text{supp } A = \bigcup_{\alpha \in (0, 1]} [A]_\alpha = \{ x \in R : A(x) > 0 \}, \]

where the \( \alpha \)-cuts of \( A \) are closed intervals, defined as \( [A]_\alpha = \{ x \in R : A(x) \geq \alpha \} \), and if supp \( A \subset (0, \infty) \), then the fuzzy number \( A \) is obviously positive.

**Definition 2.** Let \( A \) and \( B \) be the fuzzy numbers which satisfy \( [A]_\alpha = [A_{l, R}, A_{r, R}] \) and \( [B]_\alpha = [B_{l, R}, B_{r, R}] \), then the following metric is denoted:

\[ D(A, B) = \sup \max \left\{ \left| A_{l, R} - B_{l, R} \right|, \left| A_{r, R} - B_{r, R} \right| \right\}; \]

where \( \sup \) is taken for all \( \alpha \in [0, 1] \). Then, \( (R, D) \) is a complete metric space. For the convenience of application in the future, \( 0 \in R \) is defined as
\[ \hat{0}(x) = \begin{cases} 1, & x = 0, \\ 0, & x \neq 0. \end{cases} \] 

(11)

Thus, \( \hat{0}_a = [0,0], \) \( 0 < a \leq 1. \)

**Definition 3.** Persistence (resp., boundedness) of fuzzy numbers is defined if there exists a positive real number \( M \) (resp.\( N \)), such that the following conclusions are true:

\[ \text{supp } x_n \subseteq [M, \infty) \) (resp.\( \text{supp } x_n \subseteq (0, N)] \), \( n = 1, 2, \ldots, \)

where \( \{x_n\} \) is a sequence of the positive fuzzy numbers.

Further, \( \{x_n\} \) is bounded and persistent if there exist positive real numbers \( M, N, \) such that \( \text{supp } x_n \subseteq [M, N], n = 1, 2, \ldots. \)

**Lemma 1.** Let \( I_x, I_y \) be some intervals of real numbers and let \( f: I^{\infty_1}_x \times I^{\infty_1}_y \rightarrow I_x, g: I^{\infty_1}_x \times I^{\infty_1}_y \rightarrow I_y \) be continuously differentiable functions. Then, for every set of initial conditions \((x_0, y_0) \in I_x \times I_y, (i = -k, -k + 1, \ldots, 0, j = -l, \ -l + 1, \ldots, 0), \) the following system of difference equations:

\[
\begin{align*}
x_{n+1} &= f(x_n, x_{n-1}, \ldots, x_{n-k}, y_n, y_{n-1}, \ldots, y_{n-l}), \\
y_{n+1} &= g(x_n, x_{n-1}, \ldots, x_{n-k}, y_n, y_{n-1}, \ldots, y_{n-l}),
\end{align*}
\]

(12)

has a unique solution \( \{x_0, y_0\} \) for \( n \geq 0 \) is the solution of difference system (12), or equivalently, \( (x, y) \) is a fixed point of the vector map \( f, g. \)

**Definition 4.** A point \((x, y) \in I_x \times I_y \) is called an equilibrium point of system (12) if \( x = f(x, x, \ldots, x, y, y, \ldots, y), \) \((y, y, \ldots, y) = g(x, x, \ldots, x, y, y, \ldots, y), \) that is, \( (x_n, y_n) = (x, y) \) for \( n \geq 0 \) is the solution of difference system (12), or equivalently, \( (x, y) \) is an equilibrium point of the difference map \( f, g. \)

**Definition 5.** Suppose that \((x, y) \) is an equilibrium point of system (12), then the following is obtained:

(i) \((x, y) \) is called locally stable if for every \( \varepsilon > 0, \) there exists \( \delta > 0 \) such that for any initial conditions \((x_i, y_i) \in I_x \times I_y, (i = -k, -k + 1, \ldots, 0, j = -l, \ldots, 0), \) with \( \sum_{i=-k}^{0} |x_i - x| < \delta, \sum_{j=-l}^{0} |y_j - y| < \delta, \) there is \( s \) for any \( n > 0; \)

(ii) \((x, y) \) is called an attractor if \( \lim_{n \to \infty} x_n = x, \) \( \lim_{n \to \infty} y_n = y, \) for any initial conditions \((x_i, y_i) \in I_x \times I_y, (i = -k, -k + 1, \ldots, 0, j = -l, \ldots, 0); \)

(iii) \((x, y) \) is called asymptotically stable if it is stable and an attractor;

(iv) \((x, y) \) is called unstable if it is not locally stable.

**Definition 6.** Let \((x, y) \) be an equilibrium point of the vector maps \( F = (f, f, \ldots, f, g, g, \ldots, g) \) and \( G = (g, g, \ldots, g, f, f, \ldots, f) \) where \( f \) and \( g \) are continuously differentiable functions at \((x, y) \). The linearized system of (12) about the equilibrium point \((x, y) \) is \( X_{n+1} = F(X_n) = F_j \) \( X_n, \) where \( F_j \) is the Jacobian matrix of system (12) about \((x, y) \) and \( X_n = (x_{n-1}, \ldots, x_{n-k}, y_{n-1}, \ldots, y_{n-l})^T. \)

**Definition 7.** Let \( p, q, s, t \) be four nonnegative integers such that \( p + q = n \) and \( s + t = m. \) Split \( x = (x_1, x_2, \ldots, x_n) \) into \( x = ([x]_p, [x]_q) \) and \( y = (y_1, y_2, \ldots, y_m) \) into \( y = ([y]_1, \ldots, [y]_m), \) where \([x]_a \) denotes a vector with \( a \)-components of \( x. \) The function \( f(x_1, x_2, \ldots, x_n, y_1, y_2, \ldots, y_m) \) possesses a mixed monotone property in subsets \( I^{\infty_1}_x \times I^{\infty_1}_y \) of \( \mathbb{R}^n \times \mathbb{R}^m \) if \( f([x]_p, [x]_q, [y]_1, [y]_2, \ldots, [y]_m) \) is monotone nondecreasing in each component of \([x]_p, [y]_1, [y]_2, \ldots, [y]_m \) for \((x, y) \in I^{\infty_1}_x \times I^{\infty_1}_y. \) In particular, if \( q = 0, p = 0, \) then it is said to be monotone nondecreasing in \( I^{\infty_1}_x \times I^{\infty_1}_y. \)

**Lemma 2.** Assume that \( X(n+1) = F(X(n)), n = 0, 1, \ldots \) is a system of difference equations and \( \mathbb{X} \) is the equilibrium point of this system, i.e., \( F(\mathbb{X}) = \mathbb{X}, \) then the following is obtained:

(i) If all eigenvalues of the Jacobian \( J_F \) about \( \mathbb{X} \) lie inside the open unit disk \( |\lambda| < 1, \) then \( \mathbb{X} \) is locally asymptotically stable;

(ii) If one of the eigenvalues of the Jacobian \( J_F \) matrix about \( \mathbb{X} \) has a norm greater than one, then \( \mathbb{X} \) is unstable.

**Lemma 3.** Assume that \( X(n+1) = F(X(n)), n = 0, 1, \ldots \) is a system of difference equations and \( \mathbb{X} \) is the equilibrium point of this system, and the characteristic polynomial of this system about the equilibrium point \( \mathbb{X} \) is \( P(\lambda) = a_0 \lambda^n + a_1 \lambda^{n-1} + \cdots + a_{n-1} \lambda + a_n = 0, \) with the real coefficients and \( a_0 > 0. \) Then, all roots of the polynomial \( P(\lambda) \) lie inside the open unit disk \( |\lambda| < 1 \) if and only if

\[
\Delta_k > 0, \quad \text{for } k = 1, 2, \ldots, n,
\]

(13)

where \( \Delta_k \) is the principal minor of order \( k \) of the \( n \times n \) matrix:

\[
\Delta_n = \begin{bmatrix}
a_0 & a_1 & a_3 & \cdots & 0 \\
0 & a_2 & a_4 & \cdots & 0 \\
\vdots & \vdots & \ddots & \ddots & \vdots \\
0 & 0 & 0 & \cdots & a_n
\end{bmatrix}
\]

(14)

**3. Main Results and Their Proofs**

The following lemmas are applied to study the existence and uniqueness of a positive solution of the fuzzy difference equation (8).

**Lemma 4** (see [24]). Let \( f \) be a continuous function from \( \mathbb{R}^n \times \mathbb{R}^m \) into \( \mathbb{R}^n \) and \( A, B, C \) be the fuzzy numbers, then

\[
[f(A, B, C)]_a = f([A]_a, [B]_a, [C]_a), \quad a \in (0, 1].
\]

(15)

**Lemma 5** (see [19, 25]). Let us denote \( u \in R_f \) such that

\[
[u]_a = [u_{t,a}, u_{s,a}], \quad a \in (0, 1],
\]

then \( u_{t,a} \) and \( u_{s,a} \) can be seen as functions on \( a \in (0, 1] \) which satisfy the following conclusions:

(i) \( u_{t,a} \) is nondecreasing and left continuous;

(ii) \( u_{s,a} \) is nonincreasing and left continuous;

(iii) \( u_{t,a} \leq u_{s,a}. \)
Conversely, for any functions \(a(\alpha)\) and \(b(\alpha)\) defined on \((0, 1)\) which satisfy the above (i)–(iii), there exists a unique \(u \in R_f\) such that \(u(\alpha) = [a(\alpha), b(\alpha)]\) for any \(\alpha \in (0, 1)\).

**Theorem 1.** Consider equation (8), where \(A, B, C, (i = 3, 4, \ldots, k)\) are the ordinary difference equations, and then for any positive fuzzy numbers \(x_0, x_{-1}, x_{-2}, x_{-3} (i = 3, 4, \ldots, k)\), there exists a unique positive solution \([x_n]\) of (8) with the initial conditions \(x_0, x_{-1}, x_{-2}, x_{-3} (i = 3, 4, \ldots, k)\).

**Proof.** Assume that there exists a sequence \([x_n]\) that is the positive solution of (8) with the positive parameters and initial conditions \(A, B, C, x_0, x_{-1}, x_{-2}, x_{-3} (i = 3, 4, \ldots, k)\). Consider the \(\alpha\) in \((0, 1)\),

\[
[A]_\alpha = [A_{\alpha}, A_{\alpha}], \quad [B]_\alpha = [B_{\alpha}, B_{\alpha}], \quad [C]_\alpha = [C_{\alpha}, C_{\alpha}],
\]

\[
\alpha = 3, 4, \ldots, k,
\]

\[
[x_n]_\alpha = [L_{n\alpha}, R_{n\alpha}], \quad n = -k, -k + 1, \ldots, 0.
\]

Hence, for \(\alpha \in (0, 1), n = -k, -k + 1, \ldots, 0\), according to the above result, it follows that

\[
L_{n+1\alpha} = \frac{A_{\alpha}L_{n\alpha} - A_{\alpha}L_{n-1\alpha}}{B_{\alpha} + \sum_{i=3}^{k} C_{i\alpha}R_{n-i\alpha}}, \quad R_{n+1\alpha} = \frac{A_{\alpha}R_{n\alpha} - A_{\alpha}R_{n-1\alpha}}{B_{\alpha} + \sum_{i=3}^{k} C_{i\alpha}R_{n-i\alpha}}.
\]

And then, for any initial conditions \((L_{j\alpha}, R_{j\alpha}), j = -k, -k + 1, \ldots, 0, \alpha \in (0, 1)\), it is evident from Lemma 1 that there exists a unique solution \((L_{n\alpha}, R_{n\alpha})\) of the ordinary difference equations (18).

Conversely, it is proved that the positive solution \([x_n]\) of equation (8) is determined by \((L_{n\alpha}, R_{n\alpha})\) with initial conditions \((L_{j\alpha}, R_{j\alpha}), j = -k, -k + 1, \ldots, 0, \alpha \in (0, 1)\) and satisfies the following condition:

\[
[x_n]_\alpha = [L_{n\alpha}, R_{n\alpha}], \quad \alpha \in (0, 1), n = -k, -k + 1, \ldots
\]

For any \(\alpha_1, \alpha_2 \in (0, 1), \alpha_1 < \alpha_2\), according to Lemma 5, the following is obtained:

\[
0 < A_{\alpha_1} \leq A_{\alpha_2} \leq A_{\alpha_1}, \quad 0 < C_{i\alpha_1} \leq C_{i\alpha_2} \leq C_{i\alpha_1}, \quad i = 3, 4, \ldots, k,
\]

\[
0 < B_{\alpha_1} \leq B_{\alpha_2} \leq B_{\alpha_1}, \quad 0 < L_{j\alpha_1} \leq L_{j\alpha_2} \leq R_{j\alpha_1} \leq R_{j\alpha_2}, \quad j = -k, -k + 1, \ldots, 0,
\]

where \(A, B, C, x_j (i = 3, 4, \ldots, k, j = -k, -k + 1, \ldots, 0)\) are the positive fuzzy numbers.

Next, from the mathematical induction, it is proved that the following conclusion is true, that is,

\[
0 < L_{n\alpha_1} \leq L_{n\alpha_2} \leq R_{n\alpha_2} \leq R_{n\alpha_1}, \quad n = 1, 2, \ldots
\]

According to (20), (21) is true for \(n = -k, -k + 1, \ldots, 0\). Suppose that (21) is true for any \(n \leq m, m \in \{1, 2, \ldots\}\), then from (18)–(21), it follows that for \(n = m + 1\),

\[
L_{m+1\alpha_1} = \frac{A_{\alpha_1}L_{m\alpha_1} - A_{\alpha_1}L_{m-1\alpha_1}}{B_{\alpha_1} + \sum_{i=3}^{k} C_{i\alpha_1}R_{m-i\alpha_1}} \leq \frac{A_{\alpha_1}L_{m-1\alpha_1} - A_{\alpha_1}L_{m-2\alpha_1}}{B_{\alpha_1} + \sum_{i=3}^{k} C_{i\alpha_1}R_{m-i\alpha_1}} = L_{m+1\alpha_1},
\]

\[
R_{m+1\alpha_1} \leq \frac{A_{\alpha_1}R_{m\alpha_1} - A_{\alpha_1}R_{m-1\alpha_1}}{B_{\alpha_1} + \sum_{i=3}^{k} C_{i\alpha_1}R_{m-i\alpha_1}} = R_{m+1\alpha_1},
\]
Hence, (21) is true.
Furthermore, from (18), it follows that
\[
L_{1,a} = \frac{A_{1,a} L_{-1,a} L_{-2,a}}{B_{r,a} + \sum_{i=3}^{k} c_{i,r,a} R_{-i,a}}, \quad R_{1,a} = \frac{A_{r,a} R_{-1,a} R_{-2,a}}{B_{i,a} + \sum_{i=3}^{k} c_{i,d,a} L_{-i,a}}, \quad \alpha \in (0, 1].
\]
(23)

Then, in view of \(A, B, C_i, x_i (i = 3, 4, \ldots, k, j = -k, -k + 1, \ldots, 0)\) which are the positive fuzzy numbers, it is known that \(A_{1,a}, A_{r,a}, B_{r,a}, B_{i,a}, C_{d,a}, C_{i,a}, L_{-k,a}, R_{-k,a}, L_{-k+1,a}, R_{-k+1,a}, \alpha, \ldots, L_{0,a}, R_{0,a} (i = 3, 4, \ldots, k)\) are left continuous from Lemma 5. So, \(L_{1,a}\) and \(R_{1,a}\) are also left continuous from (23). Moreover, \(L_{n,a} R_{n,a} n = 1, 2, \ldots\) are left continuous using mathematical induction.

\[
\left[L_{1,a}, R_{1,a}\right] \subset \left[\frac{M_1 M_{-1} M_{-2}}{N_2 + \sum_{i=3}^{k} \sum_{j=3}^{k} N_i N_j}, \frac{N_1 N_{-1} N_{-2}}{M_2 + \sum_{i=3}^{k} \sum_{j=3}^{k} M_i M_j}\right], \quad \alpha \in (0, 1],
\]
(25)
from which the following is obtained:

\[
\bigcup_{\alpha \in (0, 1]} \left[L_{1,a}, R_{1,a}\right] \subset \left[\frac{M_1 M_{-1} M_{-2}}{N_2 + \sum_{i=3}^{k} \sum_{j=3}^{k} N_i N_j}, \frac{N_1 N_{-1} N_{-2}}{M_2 + \sum_{i=3}^{k} \sum_{j=3}^{k} M_i M_j}\right], \quad \alpha \in (0, 1].
\]
(26)

Since (21) and (24) and \(L_{n,a}, R_{n,a}\) are left continuous, from Lemma 5, a sequence of positive fuzzy numbers \(\{x_n\}\) is determined \([L_{n,a}, R_{n,a}]\) such that (8) holds.

Furthermore, it is proven that \(\{x_n\}\) is the solution of (6) with initial conditions \(x_0, x_{-1}, x_{-2}, x_{-i} (i = 3, 4, \ldots, k)\). Since for all \(\alpha \in (0, 1]\),

\[
\left[x_{n+1}\right] = \left[L_{n+1,a}, R_{n+1,a}\right] = \left[\frac{A_{1,a} L_{-1,a} L_{-2,a}}{B_{r,a} + \sum_{i=3}^{k} c_{i,r,a} R_{-i,a}}, \frac{A_{r,a} R_{-1,a} R_{-2,a}}{B_{i,a} + \sum_{i=3}^{k} c_{i,d,a} L_{-i,a}}\right] = \left[\frac{AX_{n-1} x_{-2}}{B + \sum_{i=3}^{k} c_{i} x_{n-1} x_{-i}}\right],
\]
(28)
and from the above result, it is obtained that the sequence \(\{x_n\}\) is a unique solution of (6) with initial conditions \(x_0, x_{-1}, x_{-2}, x_{-i} (i = 3, 4, \ldots, k)\), so the proof is completed.

In the following result, the asymptotic behavior of the equilibrium point of (6) is further investigated. From the above proof process, it is known that if \(x_n\) is the unique positive solution of (6) with the initial values \(x_0, x_{-1}, x_{-2}, x_{-i} (i = 3, 4, \ldots, k)\), then the following is obtained:

\[
\left[x_n\right] = \left[L_{n,a}, R_{n,a}\right], \alpha \in (0, 1], \quad n = 0, 1, \ldots
\]
(31)
Hence, it is known that \((L_{n,a}, R_{n,a})\) satisfies the family of system (18). The following corresponding ordinary parametric systems to study the asymptotic behavior of equation (8) are constructed:

\[
y_{n+1} = \frac{a_1y_{n-1}y_{n-2}}{b_1 + \sum_{i=3}^{k} c_{i1}z_{n-i}}, \\
z_{n+1} = \frac{a_2z_{n-1}z_{n-2}}{b_2 + \sum_{i=3}^{k} c_{2i}y_{n-i}},
\]

(32)

where the parameters \(a_1, a_2, b_1, b_2, c_{i1}, c_{2i} (i = 3, 4, \ldots, k)\) and initial conditions \(y_0, y_{-1}, y_{-2}, z_0, z_{-1}, z_{-2}, z_{-3}, \ldots, z_{-i} (i = 3, 4, \ldots, k)\) are the positive real constants. Clearly, system (32) has a unique solution \((y, z)\) for any initial conditions from Lemma 1.

Now, it is easily obtained that system (32) has the following three equilibrium points:

\[
\mathbf{X}_1 = (\mathbf{y}_1, \mathbf{z}_1) = (0, 0), \\
\mathbf{X}_2 = (\mathbf{y}_2, \mathbf{z}_2) = \left(0, \frac{b_1}{a_2}\right), \\
\mathbf{X}_3 = (\mathbf{y}_3, \mathbf{z}_3) = \left(b_1, 0\right).
\]

(33)

if \(a_1a_2 > \sum_{i=3}^{k} c_{i1} \sum_{j=3}^{k} c_{2i}\), and system (32) has the fourth positive equilibrium point \(\mathbf{X}_4\):

\[
\mathbf{X}_4 = (\mathbf{y}_4, \mathbf{z}_4) = \left(\frac{a_2b_1 + b_2 \sum_{i=3}^{k} c_{i1} \sum_{j=3}^{k} c_{2i}}{a_1a_2 - \sum_{i=3}^{k} c_{i1} \sum_{j=3}^{k} c_{2i}}, \frac{a_1b_2 + b_1 \sum_{i=3}^{k} c_{2i}}{a_1a_2 - \sum_{i=3}^{k} c_{i1} \sum_{j=3}^{k} c_{2i}}\right).
\]

(34)

Next, the asymptotic behavior of these four equilibrium points in detail is analyzed.

**Theorem 2.** The equilibrium point \(\mathbf{X}_1 = (0, 0)\) is locally asymptotically stable.

**Proof.** Let \(F: (R^*)^k \rightarrow R^+, \ G: (R^*)^k \rightarrow R^+\) be multivariate functions defined by

\[
F(y_{n-1}, y_{n-2}, z_{n-3}, \ldots, z_{n-k}) = \frac{a_1y_{n-1}y_{n-2}}{b_1 + \sum_{i=3}^{k} c_{i1}z_{n-i}}, \\
G(z_{n-1}, z_{n-2}, y_{n-3}, \ldots, y_{n-k}) = \frac{a_2z_{n-1}z_{n-2}}{b_2 + \sum_{i=3}^{k} c_{2i}y_{n-i}},
\]

(35)

\[
F_{y_{n-1}} = \frac{a_1y_{n-2}}{b_1 + \sum_{i=3}^{k} c_{i1}z_{n-i}}, \\
F_{y_{n-2}} = \frac{a_1y_{n-1}}{b_1 + \sum_{i=3}^{k} c_{i1}z_{n-i}}, \\
F_{z_{n-1}} = \frac{-a_1c_{i1}y_{n-1}y_{n-2}}{(b_1 + \sum_{i=3}^{k} c_{i1}z_{n-i})^2}, \\
F_{z_{n-2}} = \frac{a_2z_{n-1}z_{n-2}}{b_2 + \sum_{i=3}^{k} c_{2i}y_{n-i}}, \\
G_{z_{n-1}} = \frac{a_3z_{n-2}}{b_2 + \sum_{i=3}^{k} c_{2i}y_{n-i}}, \\
G_{z_{n-2}} = \frac{a_3z_{n-1}}{b_2 + \sum_{i=3}^{k} c_{2i}y_{n-i}}, \\
G_{y_{n-1}} = \frac{-a_3z_{n-1}z_{n-2}}{(b_2 + \sum_{i=3}^{k} c_{2i}y_{n-i})^2},
\]

(36)

thus, it holds that

\[
\Phi_{n+1} = \begin{bmatrix} y_n \\ y_{n-1} \\ \vdots \\ y_{n-k} \\ z_n \\ z_{n-1} \\ \vdots \\ z_{n-k} \end{bmatrix}, \\
D_1 = \begin{bmatrix} 0 & 0 & \cdots & 0 & 0 & \cdots & 0 & 0 \\ 1 & 0 & \cdots & 0 & 0 & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 & 0 & \cdots & 0 & 0 \\ 0 & 0 & \cdots & 0 & 0 & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & 0 & 0 & \cdots & 1 & 0 \end{bmatrix}, \]

(38)

and the corresponding characteristic polynomial of \(D_1(0, 0)\) is as follows:

\[
f(\lambda) = \lambda^{2(k+1)} = 0.
\]

(39)

Obviously, all eigenvalues of \(D_1(0, 0)\) about \((0, 0)\) lie in an open unit disk \(|\lambda| < 1\); hence, from Lemma 2, the
equilibrium point $\overline{X}_1$ is locally asymptotically stable, and then the proof ends. □

**Theorem 3.** The equilibrium point $\overline{X}_2$ is unstable.

**Proof.** From (36), the linearized systems of (32) about the equilibrium point $\overline{X}_2$ is as follows:

$$\varphi_{n+1} = D_2 \varphi_n,$$  
\hspace{1cm} (40)

where

$$\varphi_n = \begin{bmatrix} y_n \\ y_{n-1} \\ y_{n-2} \\ \vdots \\ y_{n-k} \\ z_n \\ z_{n-1} \\ \vdots \\ z_{n-k} \end{bmatrix},$$

$$D_2 = \begin{bmatrix} 0 & 0 & 0 & 0 & \cdots & 0 & 0 & 0 & 0 & \cdots & 0 & 0 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 0 & 0 & \cdots & 0 & 1 & 0 & 0 & \cdots & 0 & 0 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 0 & \frac{c_{23}}{a_2} & \cdots & \frac{c_{2k}}{a_2} & 0 & 1 & 1 & \cdots & 0 & 0 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 0 & 0 & \cdots & 0 & 0 & 0 & 1 & \cdots & 0 & 0 & 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \cdots & 0 & 0 & 0 & 0 & \cdots & 0 & 0 & 0 & 0 & \cdots & 1 & 0 \end{bmatrix},$$

and the characteristic polynomial of (40) is given by

$$f(\lambda) = \lambda^{2k-1}(\lambda^3 - \lambda - 1) = 0.$$  
\hspace{1cm} (42)

It is obvious that there exists $|\lambda| > 1$ so that $\lambda^{2k-1}(\lambda^3 - \lambda - 1) = 0$. Thus, a root of the characteristic equation (42) lies outside the unit disk. According to Lemma 2, the equilibrium point $\overline{X}_2$ of (32) is unstable, and the proof is complete. □

**Theorem 4.** The equilibrium point $\overline{X}_3$ is unstable.

**Proof.** From (36), the linearized systems of (32) about the equilibrium point $\overline{X}_3$ is provided by

$$\varphi_{n+1} = D_3 \varphi_n,$$  
\hspace{1cm} (43)

where

$$\varphi_n = \begin{bmatrix} y_{n-k} \\ y_{n-2} \\ \vdots \\ y_n \\ z_n \\ z_{n-1} \\ \vdots \\ z_{n-k} \end{bmatrix},$$

$$D_3 = \begin{bmatrix} 0 & 1 & 0 & \cdots & 0 & 0 & \cdots & 0 & \frac{c_{13}}{a_1} & \cdots & \frac{c_{1k-1}}{a_1} & \frac{c_{1k}}{a_1} \\ 0 & 0 & 0 & \cdots & 1 & 0 & 0 & \cdots & 0 & 0 & \cdots & 0 & 0 & \cdots & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 0 & 0 & 0 & 0 & 1 & \cdots & 0 & 0 & \cdots & 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 0 & 0 & 0 & 0 & \cdots & 1 & 0 & 0 & \cdots & 0 & 0 & \cdots & 0 \end{bmatrix},$$

and the characteristic polynomial of (43) is given by

$$f(\lambda) = \lambda^{2k-1}(\lambda^3 - \lambda - 1) = 0,$$  
\hspace{1cm} (45)

which is the same as with (42); therefore, the equilibrium point $\overline{X}_3$ of (32) is unstable, and the proof is complete. □
Theorem 5. If \( a_1a_2 > \sum_{i=3}^{k} c_{1i} \sum_{j=3}^{k} c_{2i} \), then the equilibrium point \( \bar{X}_4 \) is unstable.

Proof. From (36), the linearized systems of (32) about the equilibrium point \( \bar{X}_4 \) is provided by

\[
\varphi_n = \begin{bmatrix}
  y_n \\
  y_{n-1} \\
  y_{n-2} \\
  \vdots \\
  y_{n-k} \\
  z_n \\
  z_{n-1} \\
  \vdots \\
  z_{n-k}
\end{bmatrix}
\]

where

\[
\varphi_{n+1} = D_4 \varphi_n, \tag{46}
\]

and

\[
D_4 = \begin{bmatrix}
  0 & 1 & 1 & 0 & \cdots & 0 & 0 & 0 \frac{c_{13}}{a_1} \cdots \frac{c_{1k-1}}{a_1} & \frac{c_{1k}}{a_1} \\
  1 & 0 & 0 & 0 & \cdots & 0 & 0 & 0 & 0 \\
  0 & 1 & 0 & 0 & \cdots & 0 & 0 & 0 & 0 \\
  \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots \\
  0 & 0 & 0 & 0 & \cdots & 1 & 0 & 0 & 0 \\
  0 & 0 & 0 & \frac{c_{23}}{a_2} \cdots \frac{c_{2k}}{a_2} & 0 & 1 & 1 & \cdots & 0 \\
  0 & 0 & 0 & \cdots & 0 & 0 & 1 & 0 & \cdots & 0 \\
  \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \vdots \\
  0 & 0 & 0 & \cdots & 0 & 0 & 0 & 0 & \cdots & 1 \\
  0 & 0 & 0 & \cdots & 0 & 0 & 0 & 0 & \cdots & 1 \end{bmatrix}
\]

and the characteristic polynomial of (46) is given by

\[
f(\lambda) = \lambda^{2k+2} - 2\lambda^{2k} - 2\lambda^{2k-1} + \lambda^{2k-2} + 2\lambda^{2k-3} + \lambda^{2k-4} - \frac{1}{a_1a_2} \sum_{i=3}^{2k-3} \sum_{j=3}^{2k-3} c_{1i}c_{2j} \lambda^{2k-i-j} = 0. \tag{48}
\]
According to Lemma 3, the following is obtained:

\[
\Delta_1 = (a_1) = 0;
\]
\[
\Delta_2 = \begin{pmatrix} 0 & -2 \\ 1 & -2 \end{pmatrix} = 2 > 0;
\]
\[
\Delta_3 = \begin{pmatrix} 0 & -2 & 2 \\ 1 & -2 & 1 \\ 0 & 0 & -2 \end{pmatrix} = 4 > 0;
\]
\[
\Delta_4 = \begin{pmatrix} 0 & -2 & 2 & 0 \\ 1 & -2 & 1 & 1 \\ 0 & 0 & -2 & 2 \\ 0 & 0 & -2 & 1 \end{pmatrix} = -4 < 0.
\]

It is obvious that not all \( \Delta_i > 0, i = 1, 2, \ldots, 2k + 2 \). From Lemma 2, the equilibrium point \( X_4 \) is unstable, and then the proof is completed.

Lemma 6 (see [12]). Let \( I_x, I_y \) be some intervals of real numbers and assume that \( f: I_x^{k+1} \times I_y^{t+1} \longrightarrow I_x \) and \( g: I_x^{k+1} \times I_y^{t+1} \longrightarrow I_y \) be continuously differentiable functions satisfying a mixed monotone property. If there exists

\[
\begin{align*}
0 \leq \min\{x_{-k}, \ldots, x_0, y_{-t}, \ldots, y_0\} & \leq M_0, \\
0 \leq \min\{x_{-k}, \ldots, x_0, y_{-t}, \ldots, y_0\} & \leq N_0, \\
\end{align*}
\]

such that

\[
\begin{align*}
m_0 & \leq f([m_0]_{p}, [M_0]_{p}, [n_0]_{p}, [N_0]_{p}) \leq f([M_0]_{p}, [m_0]_{p}, [N_0]_{p}, [n_0]_{p}) \leq M_0, \\
n_0 & \leq g([m_0]_{q}, [M_0]_{q}, [n_0]_{q}, [N_0]_{q}) \leq g([M_0]_{q}, [m_0]_{q}, [N_0]_{q}, [n_0]_{q}) \leq N_0,
\end{align*}
\]

then there exist \( (m, M) \in [m_0, M_0]^2 \) and \( (n, N) \in [n_0, N_0]^2 \) satisfying

\[
\begin{align*}
M = f([M]_{p}, [m]_{q}, [N]_{q}, [n]_{q}), m = f([m]_{p}, [M]_{q}, [n]_{q}, [N]_{q}), \\
N = g([M]_{q}, [m]_{q}, [N]_{q}, [n]_{q}), n = g([m]_{q}, [M]_{q}, [n]_{q}, [N]_{q}).
\end{align*}
\]

Moreover, if \( m = M \) and \( n = N \), then equation (12) has a unique equilibrium point \( (x, y) \in [m_0, M_0] \times [n_0, N_0] \) and every solution of (12) converges to \( (x, y) \).

Theorem 6. If \( a_1 = a_2, b_1 = b_2, c_{ij} = c_{ji}, \) then the equilibrium point \( X_4 = (0, 0) \) of system (32) is a global attractor for any conditions \( (y_{-i}, z_{-j}) \in (0, (b_1/2a_1)) \times (0, (b_1/2a_1)), i = -k, -k + 1, \ldots, 0. \)

Proof. In view of \( a_i = a_2, b_1 = b_2, c_{ij} = c_{ji} \), system (32) can be changed to

\[
\begin{align*}
y_{n+1} & = \frac{a_1 y_{n-1} y_{n-2}}{b_1 + \sum_{i=3}^{k} c_{ij} z_{n-i}}, \\
z_{n+1} & = \frac{a_1 z_{n-1} z_{n-2}}{b_1 + \sum_{i=3}^{k} c_{ij} y_{n-i}} \quad (53)
\end{align*}
\]

\( n = 0, 1, \ldots. \)
Let \((f, g)\) be a function defined by
\[
f(y_n, y_{n-1}, \ldots, y_{n-i}, z_{n-1}, \ldots, z_{n-i}) = \frac{a_1 y_{n-1} y_{n-2}}{b_1 + \sum_{i=3}^{k} c_{i1} z_{n-i}},
\]
\[
g(y_n, y_{n-1}, \ldots, y_{n-i}, z_{n-1}, \ldots, z_{n-i}) = \frac{a_2 z_{n-1} z_{n-2}}{b_1 + \sum_{i=3}^{k} c_{i1} y_{n-i}}.
\]
Set
\[
f = \frac{a_1 u v}{b_1 + \sum_{i=3}^{k} c_{i1} w_i},
\]
\[
g = \frac{a_1 u^* v^*}{b_1 + \sum_{i=3}^{k} c_{i1} w_i},
\]
\[
f_u = \frac{a_1 v}{b_1 + \sum_{i=3}^{k} c_{i1} w_i} > 0,
\]
\[
f_v = \frac{a_1 u}{b_1 + \sum_{i=3}^{k} c_{i1} w_i} > 0,
\]
\[
f_{w_i} = \frac{a_1 c_{i1} u v}{(b_1 + \sum_{i=3}^{k} c_{i1} w_i)^2} < 0,
\]
\[
g_{u^*} = \frac{a_1 v^*}{b_1 + \sum_{i=3}^{k} c_{i1} w_i} > 0,
\]
\[
g_{v^*} = \frac{a_1 u^*}{b_1 + \sum_{i=3}^{k} c_{i1} w_i} > 0,
\]
\[
g_{w_{i^*}} = \frac{a_1 c_{i1} u^* v^*}{(b_1 + \sum_{i=3}^{k} c_{i1} w_i)^2} < 0,
\]
which means that \(f\) and \(g\) have a mixed monotone property.

Let
\[
M_0 = N_0 = \max\{y_0, y_{-1}, y_{-2}, \ldots, z_0, z_{-1}, z_{-2}, \ldots\},
\]
\[
i = 3, 4, \ldots, k,
\]
\[
\left[\left(a_1 M_0 - b_1\right)\right] \leq m_0 = n_0 < 0,
\]
then,
\[
m_0 \leq \frac{a_1 m_0^2}{b_1 + N_0 \sum_{i=3}^{k} c_{i1}} \leq \frac{a_1 M_0^2}{b_1 + m_0 \sum_{i=3}^{k} c_{i1}} \leq M_0,
\]
\[
n_0 \leq \frac{a_1 n_0^2}{b_1 + N_0 \sum_{i=3}^{k} c_{i1}} \leq \frac{a_1 N_0^2}{b_1 + m_0 \sum_{i=3}^{k} c_{i1}} \leq N_0.
\]

Thus, \([a_1 (m + M) - b_1] (m - M) = 0\). Moreover, from \(2a_1 M_0 < b_1\), then \(M = m\) and \(N = n\).

Hence, it is obtained that the equilibrium point \((0, 0)\) of system (32) is a global attractor from Lemma 6. The proof is completed.

Moreover, from Definition 5, it is obtained that the equilibrium point \(X_0\) of system (32) is asymptotically stable.

It is obvious that the fuzzy difference (6) has the trivial solution 0. Next, the stability of the trivial solution is discussed. To do this, first, the following definition is introduced.

**Definition 8.** The trivial solution \(x = 0\) of the fuzzy difference equation (8) is said to be

(i) Stable, if given \(\epsilon > 0\), and there exists \(\delta(\epsilon) > 0\) with \(D(x, 0) < \delta\), \(i = -k, -k + 1, \ldots, 0\), which implies \(D(x, 0) < \epsilon\), for any \(n > 0\), such that for any \(x_i \in D, i = -k, -k + 1, \ldots, 0\), the solution \(x_i \in D, n > 0\);

(ii) Attractive if there is \(\delta > 0\) such that \(D(x, 0) < \delta, i = -k, -k + 1, \ldots, 0\), and one has
\[
\lim_{n \to \infty} D(x, 0) = 0;
\]

(iii) Asymptotically stable if (i) and (ii) hold simultaneously.

**Theorem 7.** If the parameters \(A, B, C\) are the positive trivial fuzzy numbers, i.e., positive real numbers, and the initial conditions are the positive fuzzy numbers with \([x_i]_{0} \in (0, B/2A), i = -k, -k + 1, \ldots, 0\), \(a \in (0, 1)\), then the trivial solution \(x = 0\) of the fuzzy difference equation (8) is asymptotically stable with respect to \(D\) as \(n \to \infty\).

**Proof.** The result follows from Theorem 2 and Theorem 6. \(\square\)

**4. Numerical Simulation**

Numerical examples are given in this section to confirm the results of the previous sections and to support the theoretical discussion. The example gives the asymptotic behavior of the solution of the fuzzy difference system (8). The following fuzzy difference equation is considered.
Example 1. Let \( k = 5 \), and the following fuzzy difference equation is considered:

\[
x_{n+1} = \frac{A x_{n-1} x_{n-2}}{B + \sum_{i=3}^{5} C_i x_{n-i}}, \quad n = 0, 1, 2, \ldots
\]  

(60)

where \( A, B, C_i (i = 3, 4, 5) \) are the positive real numbers. By Theorem 7, \([A]_\alpha = [A, A] = 0.2, [B]_\alpha = [B, B] = 16, [C_3]_\alpha = [C, C] = 2, [C_4]_\alpha = [C, C] = 3, \alpha \in (0, 1)\). In addition, from Theorem 7, the initial conditions \( x_{-5}, x_{-4}, x_{-3}, x_{-2}, x_{-1}, x_0 \) with \([x_i]_\alpha \not\in (0, B/2A), i = -5, -4, \ldots, 0, \alpha \in (0, 1)\), are denoted such that

\[
x_0(x) = \begin{cases}
\frac{1}{2} x - \frac{5}{2} & 5 \leq x \leq 7, \\
\frac{1}{5} x + \frac{12}{5} & 7 \leq x \leq 12,
\end{cases}
\]

\[
x_{-1}(x) = \begin{cases}
\frac{1}{8} x - \frac{3}{8} & 3 \leq x \leq 11, \\
\frac{1}{2} x + \frac{13}{2} & 11 \leq x \leq 13,
\end{cases}
\]

\[
x_{-2}(x) = \begin{cases}
\frac{1}{8} x - \frac{1}{8} & 1 \leq x \leq 9, \\
\frac{1}{4} x + \frac{13}{4} & 9 \leq x \leq 13,
\end{cases}
\]

\[
x_{-3}(x) = \begin{cases}
\frac{1}{6} x - \frac{1}{3} & 2 \leq x \leq 8, \\
\frac{1}{4} x + 3 & 8 \leq x \leq 12,
\end{cases}
\]

\[
x_{-4}(x) = \begin{cases}
\frac{1}{5} x - \frac{4}{5} & 4 \leq x \leq 9, \\
\frac{1}{5} x + \frac{14}{5} & 9 \leq x \leq 14,
\end{cases}
\]

\[
x_{-5}(x) = \begin{cases}
\frac{1}{4} x - \frac{3}{2} & 6 \leq x \leq 10, \\
\frac{1}{6} x + \frac{8}{3} & 10 \leq x \leq 16.
\end{cases}
\]

(61)

From (61), the corresponding triangular fuzzy numbers are obtained:

\[
\begin{array}{l}
\alpha = 1 \\
\alpha = 0.75 \\
\alpha = 0.5 \\
\alpha = 0.25 \\
\alpha = 0.1
\end{array}
\]

\[
\begin{array}{l}
\alpha = 1 \\
\alpha = 0.75 \\
\alpha = 0.5 \\
\alpha = 0.25 \\
\alpha = 0.1
\end{array}
\]

\[
\begin{array}{l}
\alpha = 1 \\
\alpha = 0.75 \\
\alpha = 0.5 \\
\alpha = 0.25 \\
\alpha = 0.1
\end{array}
\]

From (60), the parameters \( A, B, C_i (i = 3, 4, 5) \) and initial values \( x_{-5}, x_{-4}, x_{-3}, x_{-2}, x_{-1}, x_0 \) satisfy the following system of nonlinear difference equation with parameter \( \alpha \):
powerful tool for solving various fuzzy difference equations and can also be applied to other nonlinear differential equations or difference equations in mathematical physics. Numerical simulation results show that this method is effective and simple. Variational iterative method is an effective method to deal with nonlinear structures. MATLAB 2016 software package was used for calculation.

The purpose of this paper was to study the dynamic behavior for a class of nonlinear high-order fuzzy difference equations. Firstly, the existence and uniqueness of positive fuzzy solutions are proved. Secondly, it is obtained that the nonzero equilibrium points of the corresponding ordinary difference equations (32) are unstable by using the linearization method. Finally, it is found that the trivial solution $0$ of fuzzy difference (6) is asymptotically stable when the parameters $A$, $B$, $C_i$ are positive trivial fuzzy numbers. In particular, an illustrate example is given to show the effectiveness of the obtained results. In addition, the sufficient conditions obtained in this paper are very simple and provide some flexibility for the application and analysis of nonlinear fuzzy difference equations.

**Data Availability**

The data used to support the findings of this work are included within this article.

**Conflicts of Interest**

The author declares that there are no conflicts of interest.

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