A Shrinking Projection Algorithm with Errors for Costerro Bounded Linear Mappings

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The purpose of this paper is to introduce and analyze the shrinking projection algorithm with errors for a finite set of costerro bounded linear mappings in the setting of uniformly convex smooth Banach spaces. Here, under finite dimensional or compactness restriction or the error term being zero, the strong limit point of the sequence stated in the iterative scheme for these mappings in uniformly convex smooth Banach spaces was studied. This paper extends Ezearn and Prempeh’s result for nonexpansive mappings in real Hilbert spaces.

1. Introduction

Fixed-point theory is a fascinating subject, with a lot of applications in various fields of mathematics and engineering. In a number of situations, one may need to find a common fixed point of a family of mappings. In practice, a modification may be needed to turn the problem into a fixed-point problem (see, for instance, Picard [1] and Lindelöf [2]). For more information on the fixed-point problem and its applications to certain types of linear and nonlinear problems, interested readers should be referred to Tang and Chang [3] (equilibrium problems), Solodov and Svaiter [4] (proximal point algorithm), Takahashi [5, 6] (convex optimization and minimization problems), and Blum and Oettli [7] (variational inequalities).

In practice, finding an exact closed form of a solution to a fixed-point problem is almost a difficult task. For this reason, it has been of particular importance in the development of feasible iterative schemes or methods for approximating fixed points of certain maps, most notably, nonexpansive type of mappings. For instance, Halpern [8], Mann [9], and Ishikawa [10] studied and developed an iterative scheme to approximate the fixed points of nonexpansive mappings in Hilbert spaces under certain conditions. In their scheme, strong convergence is always guaranteed for all closed convex subsets of a Hilbert space. Haugazeau [11] initially proposed the projection method which was later developed by Solodov and Svaiter [4]. A type of projection method which is of relevance and central to this paper is called the Shrinking Projection Method with Errors, which was developed by Takahashi et al. [12] and used by Yasunori [13]. Strong convergence result is always guaranteed for all closed convex subsets of a Hilbert space under certain conditions.

In [14], Ezearn and Prempeh improved the boundedness requirement of Yasunori’s result [13] regarding a shrinking projection algorithm for common fixed points of nonexpansive mappings in a real Hilbert space. In their results, they showed that the boundedness requirement in Yasunori’s results could be removed. That is to say that the convergence of the iterative sequence in the scheme presented in Yasunori’s paper, that is, the error term $\epsilon_i = 0$ is independent of the boundedness of the closed convex subset in a real Hilbert space. With the boundedness removed, Ezearn and Prempeh further provided a better estimate for the convergence result of the iterative sequence in their algorithm especially in finite dimensional and further showed that when the closed convex set is compact, their estimates do not involve the diameter of the subset.

In this paper, it is shown that the strong limit point of the iterative sequence $\{x_n\}_{n \geq 1}$ presented in Iterative Scheme 1
always exists in a finite-dimensional space. And, it also shown that when the space is not finite dimensional, the strong limit point of \( \{ x_n \} \) is guaranteed when the closed convex subset is compact. Finally, the strong limit point of \( \{ x_n \} \) also exists when the error term \( (\varepsilon_n) \) is zero regardless of the compactness of the closed convex subset and the dimension of the space.

**Definition 1** (normalised duality mapping, see Lunner [15]). Let \( \mathcal{X} \) be a Banach space with the norm \( \| \cdot \| \) and let \( \mathcal{X}^* \) be the dual space of \( \mathcal{X} \). Denote \( \langle \cdot, \cdot \rangle \) as the duality product. The normalised duality mapping \( J \) from \( \mathcal{X} \) to \( \mathcal{X}^* \) is defined by

\[
Jx := \{ f \in \mathcal{X}^*: \| f \| = \langle x, f \rangle = f(x) \},
\]

for all \( x \in \mathcal{X} \). The Hahn Banach theorem guarantees that \( Jx \neq \emptyset \) for every \( x \in \mathcal{X} \). For the purposes of this paper, the interest mostly lies on the case when \( Jx \) is single valued for all \( x \in \mathcal{X} \), which is equivalent to the statement that \( \mathcal{X} \) is a smooth Banach space.

Throughout this paper, \( \mathcal{R} \) denotes the real part of a complex number and \( F(T) \) is used to denote the set of fixed points of the mapping \( T \) (that is, \( F(T) = \{ x \in \mathcal{E}: Tx = x \} \)). The mappings studied in this paper are defined in the following.

**Definition 2** (costerro bounded linear mappings). Let \( \mathcal{X} \) be a strictly convex smooth reflexive space and \( \mathcal{E} \) a closed convex subset of \( \mathcal{X} \). A mapping \( T: \mathcal{E} \to \mathcal{X} \) is said to be a costerro bounded linear mapping if

\[
\| Tx \| \leq \| x \|,
\]

such that whenever \( z \in F(T) \), then

\[
\mathcal{R} \langle z, JT x - Jx \rangle \geq 0, \quad \forall x, z \in \mathcal{E}.
\]

An immediate example of such mappings is the scaling operator given by

\[
T(x) = ax,
\]

where the scaling factor \( a \) lies in the closed unit disk.

In order to state the iterative scheme, the following function is defined.

**Definition 3** (generalised projection functional, see Alber [16]). Let \( \mathcal{X} \) be a smooth Banach space and let \( \mathcal{X}^* \) be the dual space of \( \mathcal{X} \). The generalised projection functional \( \phi(\cdot, \cdot): \mathcal{X} \times \mathcal{X} \to \mathcal{R} \) is defined by

\[
\phi(y, x) = \| y \|^2 - 2\mathcal{R} \langle y, Jx \rangle + \| x \|^2,
\]

for all \( x, y \in \mathcal{X} \), where \( J \) is the normalised duality mapping from \( \mathcal{X} \) to \( \mathcal{X}^* \). It is obvious from the definition that the generalised projection functional \( \phi(\cdot, \cdot) \) satisfies the following inequality:

\[
(\| y \| - \| x \|)^2 \leq \phi(y, x) \leq (\| y \| + \| x \|)^2,
\]

for all \( x, y \in \mathcal{X} \).

Note that the generalised projection functional \( \phi(\cdot, \cdot) \) is continuous.

The next function which is stated in the iterative scheme is established via the following theorem.

**Theorem 1** (generalised projection, see Li [17]). Let \( \mathcal{X} \) be a uniformly convex smooth Banach space and let \( \mathcal{E} \neq \emptyset \) be a closed convex subset of \( \mathcal{X} \). Then, for every \( x \in \mathcal{X} \), there exists a unique \( y \in \mathcal{E} \) such that

\[
\Lambda(x, C) = \phi(y, x) = \inf_{z \in \mathcal{E}} \phi(z, x).
\]

The unique point \( y \) satisfying equation (7) is the called the generalised projection of \( x \) on \( \mathcal{E} \). That is, the projection operator \( \Pi_\mathcal{E}: \mathcal{X} \to \mathcal{E} \) is defined by setting

\[
\Pi_\mathcal{E} x = y,
\]

where \( y \) is the only point in \( \mathcal{E} \) satisfying equation (7).

**Remark 1.** In Theorem 1, note that if \( \mathcal{X} \) is a Hilbert space, then \( \phi(y, x) = \| y - x \|^2 \). Hence, the (generalised) projection \( \Pi_\mathcal{E} \) defined in equation (8) coincides with the metric projection onto \( \mathcal{E} \) in the Hilbert space setting. The converse is not necessarily true in a general Banach space.

The iterative scheme is stated as follows.

Iterative Scheme 1. Let \( \mathcal{X} \) be a uniformly convex smooth Banach space and let \( \mathcal{E} \neq \emptyset \) (not necessarily bounded) be a closed convex subset of \( \mathcal{X} \). Let \( \{ T_k \}_{k=1}^m \) be finite set of costerro bounded linear mappings from \( \mathcal{E} \) to \( \mathcal{X} \) with \( F = \cap_{k=1}^m F(T_k) \neq \emptyset \). Let \( \{ \alpha_{nk} \}_{n,k=1}^m \) and \( \{ \varepsilon_n \}_{n=1}^\infty \) be nonnegative real sequences satisfying the following conditions:

(i) \( \{ \alpha_{nk} \}_{n,k=1}^m \subset [0, 1] \)

(ii) \( \sum_{k=1}^m \alpha_{nk} = 1 \)

(iii) \( \alpha_k = \lim \inf_{n \to \infty} \alpha_{nk} > 0 \)

(iv) \( \varepsilon_0 = \lim \sup_{n \to \infty} \varepsilon_n < \infty \)

for all \( 1 \leq k \leq m \) and \( n \geq 1 \).

Then, for any arbitrary \( u \in \mathcal{X} \) with the assumptions \( x_1 \in \mathcal{E}_1 : = \mathcal{E} \) and \( \phi(x_1, u) < \varepsilon_1^2 \), the sequence \( \{ x_n \}_{n=1}^\infty \) is defined iteratively by the following scheme:

\[
\delta_n = \left\{ z \in \mathcal{E}: \sum_{k=1}^m \alpha_{nk} \phi(z, T_k x_n) \leq \phi(z, x_n) \right\},
\]

\[
\mathcal{E}_{n+1} = \delta_n \cap \mathcal{E}_n, x_{n+1} \in \mathcal{E}_{n+1},
\]

\[
\phi(x_{n+1}, u) \leq \Lambda(u, \mathcal{E}_{n+1}) + \varepsilon_{n+1},
\]

for all \( n \geq 1 \).

### 2. Preliminaries

The inequality \( \mathcal{R} \langle z, JT x - Jx \rangle \geq 0 \) in Definition 2 can be written equivalently in terms of norms. This is achieved via the elementary lemma by Ezearn in [18]. The proof is given here for the sake of completeness.
Corollary 1. The inequality \( \langle z, JTx - Jx \rangle \geq 0 \) is equivalent to
\[
\|Tx\|^2 + \|x\|^2 \leq \|Tx\| \|Tx + ax\| + \|x\| \|x - ax\|,
\]
for all \( \alpha \geq 0 \).

Proof. By considering Lemma 1 for the case when \( m = 2 \), the inequality
\[
\langle z, Jx_1 - Jx_2 \rangle = \langle z, Jx_1 + J(-x) \rangle \geq 0,
\]
is equivalent to the following condition:
\[
\sum_{k=1}^{2} \|x_k\|^2 \leq \sum_{k=1}^{2} \|x_k\| \|x_k + \alpha y\|,
\]
\[
\|x_1\|^2 + \|x_2\|^2 \leq \|x_1\| \|x_1 + \alpha y\| + \|x_2\| \|x_2 + \alpha y\|.
\]

Now, replacing \( x_1 \) with \( Tx, y \) with \( z \), and \( x_2 \) with \( -x \), the corollary is proved.

Below, a nontrivial example of costerro bounded linear mappings is given which is referred to as Ezeern nonexpansive mapping. Ezeern, in his thesis [18], has defined certain closely related mappings (named type III variational nonexpansive mappings).

Corollary 2 (Ezeern nonexpansive mapping). Let \( \mathcal{C} \) be a closed convex subset of a strictly convex smooth reflexive space \( \mathcal{X} \). Then, the following is a nontrivial example of a costerro bounded linear mapping:
\[
\left( \|Tx\|^2 + \|Ty\|^2 \right) \leq \|Tx\| \|Tx + Ty\| + \|x\| \|x - Ty\|,
\]
for all \( x, y \in \mathcal{C} \) and all \( \alpha \geq 0 \).

Proof. For \( \alpha = 0 \), equation (19) reduces to the following:
\[
\|Tx\|^2 + \|Ty\|^2 \leq \|Tx\| \|Ty\| + \|x\| \|x - Ty\|,
\]
\[
\|Ty\|^2 \leq \|y\|^2,
\]
which satisfies the first part of Definition 2. To show the second part of Definition 2, if \( y \in F(T) \), then equation (19) reduces to the fixed point set of \( T \), then equation (19) reduces to the following evaluation:
\[
\left( \|Tx\|^2 + \|Ty\|^2 \right) \leq \|Tx\| \|Tx + Ty\| + \|x\| \|x - Ty\|,
\]
\[
\|Tx\|^2 + \|Ty\|^2 \leq \|Tx\| \|Tx + Ty\| + \|x\| \|x - Ty\|,
\]
which by Corollary 1 is equivalent to \( \langle y, JTx - Jx \rangle \geq 0 \). Hence proved.

Lemma 2 (see, for instance, Ezeern [18]). Let \( \{\mathcal{C}_n\}_{n=1}^\infty \) be a sequence of nonempty closed convex subsets of a uniformly convex smooth Banach space \( \mathcal{X} \) such that \( \mathcal{C}_{m+1} \subseteq \mathcal{C}_m \). Suppose that further that \( \mathcal{C}_\infty = \bigcap_{n=1}^\infty \mathcal{C}_n \) is nonempty. Then, the sequence of generalized projections \( \{\Pi_{\mathcal{C}_n}x\}_{n=1}^\infty \) converges strongly to \( \Pi_{\mathcal{C}_\infty}x \) for any \( x \in \mathcal{X} \).

Proposition 1 (see Alber [19], Alber and Reich [20], and Kamimura and Takahashi [21]). Let \( \mathcal{X} \) be a real uniformly convex smooth Banach space and \( \mathcal{C} \neq \emptyset \) be a closed convex subset of \( \mathcal{X} \). Then, the following inequality holds:
\[
\phi(y, \Pi_{\mathcal{C}_n}x) + \phi(\Pi_{\mathcal{C}_n}x, x) \leq \phi(y, x),
\]
for all \( y \in \mathcal{C} \) and \( x \in \mathcal{X} \).

Proposition 2 (continuity in duality pairing). Let \( \mathcal{X} \) be a Banach space and let \( \mathcal{X}^* \) be the dual space of \( \mathcal{X} \). Denote \( \langle \cdot, \cdot \rangle \) as the duality product. Now, for \( \{x_n\}_{n=1}^\infty \subset \mathcal{X} \) and \( \{f_n\}_{n=1}^\infty \subset \mathcal{X}^* \), suppose either of the following conditions hold:

(i) \( \{x_n\} \rightharpoonup x \) and \( \{f_n\} \rightarrow f \)
(ii) \( \{x_n\} \rightharpoonup x \) and \( \{f_n\} \rightarrow f \)

Then, \( \limsup_{n \to \infty} \langle x_n, f_n \rangle = \langle x, f \rangle \).
Lemma 3 (weak star-continuity in smooth spaces). Let $X$ be a real smooth Banach space. Then, $J \colon X \to X^*$ is norm-to-weak star continuous, where $J$ is the normalized duality mapping.

Lemma 4 (see Kamimura and Takahashi [21]). Let $X$ be a uniformly convex and smooth Banach space and let $\{x_n\}$ and $\{y_n\}$ be two sequences in $X$ such that either $\{x_n\}$ or $\{y_n\}$ is bounded. If $\lim_{n \to \infty} \phi(x_n, y_n) = 0$, then $\lim_{n \to \infty} \|x_n - y_n\| = 0$.

3. Main Results

The proof of the main result of this paper is given in this section, which is accomplished in Theorem 3. The following corollary and lemmas shall aid in arriving at the conclusion of the main result.

Corollary 3. If the sequence $\{x_n\}_{n \geq 1}$ has a strong limit point, say $x$, then $x \in F = \cap_{k=1}^{\infty} F(T_k)$.

Proof. Without loss of generality, it is assumed that the sequence $\{x_n\}_{n \geq 1} = x_1, x_2, x_3, \ldots$ is the subsequence converging to $x$. Now, for $n \geq 1$, since the sets $\mathcal{C}_n$ form a decreasing sequence of sets, that is, $\mathcal{C}_{n+1} \subseteq \mathcal{C}_n$ then from Iterative Scheme 1, $x_{n+1} \in \mathcal{C}_{n+1} \subseteq \mathcal{C}_n$, where $\{x_{n+1}\}_{n \geq 1} = x_2, x_3, x_4, \ldots$. Hence, it is observed that

$$\sum_{k=1}^{m} \alpha_{n,k} \phi(x_{n+1}, T_k x_n) \leq \phi(x_{n+1}, x_n).$$

(23)

Hence, taking limit as $n \to \infty$ of the above inequality, the following is obtained:

$$\lim_{n \to \infty} \sum_{k=1}^{m} \alpha_{n,k} \phi(x_{n+1}, T_k x_n) \leq \lim_{n \to \infty} \phi(x_{n+1}, x_n).$$

(24)

By Proposition 2 and Lemma 3, $\lim_{n \to \infty} \phi(x_{n+1}, x_n) \to 0$ and as a result, the following is obtained:

$$\lim_{n \to \infty} \sum_{k=1}^{m} \alpha_{n,k} \phi(x_{n+1}, T_k x_n) \leq 0.$$

(25)

Since the generalised functional $\phi(\cdot, \cdot)$ is nonnegative and the limit infimum of $\{\alpha_{n,k}\}$ is nonzero for all $k$, the following is obtained:

$$\lim_{n \to \infty} \phi(x_{n+1}, T_k x_n) = 0,$$

(26)

for all $k \in \{1, \ldots, m\}$.

So by Lemma 4,

$$\lim_{n \to \infty} \|x_{n+1} - T_k x_n\| = 0,$$

(27)

for all $k \in \{1, \ldots, m\}$ and that proves the corollary due to the continuity of the norm functional and the mappings $T_k$.

Lemma 5. For all $n \geq 1$, the sets $\mathcal{B}_n$ and $\mathcal{C}_n$ in Iterative Scheme 1 are closed convex sets.

Proof. Because $\mathcal{C}_1 = \mathcal{C}$ is a closed convex set by assumption, it suffices to show that $\mathcal{B}_n$ is a closed convex set for all $n$. To prove the closure aspect of the lemma, if $\{z_j\}_{j=1}^{\infty} \subseteq \mathcal{B}_n$ converges to $z \in \mathcal{C}$, then via the continuity of the generalised functional $\phi(\cdot, \cdot)$, the following is obtained:

$$\sum_{k=1}^{m} \alpha_{n,k} \phi(z, T_k x_n) = \lim_{j \to \infty} \sum_{k=1}^{m} \alpha_{n,k} \phi(z_j, T_k x_n)$$

$$\leq \lim_{j \to \infty} \phi(z_j, x_n) = \phi(z, x_n),$$

(28)

and as a result, $z \in \mathcal{B}_n$.

Finally, to prove convexity, let $u, v \in \mathcal{B}_n$ and $t \in [0, 1]$. First, note that whenever $z \in \mathcal{B}_n$ then the inequality is obtained:

$$\sum_{k=1}^{m} \alpha_{n,k} \phi(z, T_k x_n) \leq \phi(z, x_n),$$

(29)

which can be expanded and observed to be equivalent to

$$\sum_{k=1}^{m} \alpha_{n,k} \left(\|T_k x_n\|^2 - \|x_n\|^2\right) \leq 2R \sum_{k=1}^{m} \alpha_{n,k} \langle z, J T_k x_n - J x_n \rangle.$$

(30)

So by making the substitution $z = u$ and multiplied by $t$ and adding it to $z = v$ multiplied by $(1 - t)$, the following is obtained:

$$\sum_{k=1}^{m} \alpha_{n,k} \left(\|T_k x_n\|^2 - \|x_n\|^2\right)$$

$$= t \sum_{k=1}^{m} \alpha_{n,k} \left(\|T_k x_n\|^2 - \|x_n\|^2\right) + (1 - t) \sum_{k=1}^{m} \alpha_{n,k} \left(\|T_k x_n\|^2 - \|x_n\|^2\right)$$

$$\leq 2R \sum_{k=1}^{m} \alpha_{n,k} \langle u, J T_k x_n - J x_n \rangle + 2(1 - t)R \sum_{k=1}^{m} \alpha_{n,k} \langle v, J T_k x_n - J x_n \rangle$$

$$= 2R \sum_{k=1}^{m} \alpha_{n,k} \langle tu + (1 - t)v, J T_k x_n - J x_n \rangle,$$

from which it is concluded that

$$\sum_{k=1}^{m} \alpha_{n,k} \phi(tu + (1 - t)v, T_k x_n) \leq \phi(tu + (1 - t)v, x_n).$$

(32)

Hence, $\mathcal{B}_n$ is convex.

Now, define $\mathcal{C}_\infty := \bigcap_{n \geq 1} \mathcal{C}_n$.

□

Lemma 6. The set $\mathcal{C}_\infty$ is a closed convex set containing $F$. Hence, the sequence $\{\Pi_{\mathcal{C}_n} x\}_{n \geq 1}$ of generalised projections converges strongly to $\Pi_{\mathcal{C}_\infty} x$ for any arbitrary $x$ in a uniformly convex smooth Banach space $X$.

Proof. By induction, it is observed that the sets $\mathcal{C}_n$ are all closed convex subsets by the help of Lemma 5 and the
Theorem 3

Let $\mathcal{X}$ be a uniformly convex smooth Banach space and suppose any of the following cases hold:

(i) The space $\mathcal{X}$ is finite dimensional.

(ii) The convex set $\mathcal{C}$ is compact.

(iii) $\varepsilon_0 = 0$.

Then, $\omega(\{x_n\}_{n \in \mathbb{N}}) \neq \emptyset$ and $\omega(\{x_n\}_{n \in \mathbb{N}}) \subseteq \bigcap_{k=1}^{m} F(T_k)$, where $\omega$ denotes the (strong) limit set of the iterative sequence $\{x_n\}_{n \in \mathbb{N}}$.

By the assumption in Iterative Scheme 1, it is observed that $F \subseteq \mathcal{C}'$ and $x_1$ is given. Now, supposing $F \subseteq \mathcal{C}_m$ for all $m \leq n$ and choosing arbitrary $z \in F$. Then, the following evaluation is obtained:

\[
\sum_{k=1}^{m} \alpha_{n,k} \phi(z, T_k x_n) = \sum_{k=1}^{m} \alpha_{n,k} \left( \|z\|^2 + \|T_k x_n\|^2 - 2R \left\langle z, J T_k x_n \right\rangle \right) 
= \sum_{k=1}^{m} \alpha_{n,k} \|z\|^2 + \sum_{k=1}^{m} \alpha_{n,k} \|T_k x_n\|^2 - 2R \sum_{k=1}^{m} \alpha_{n,k} \left\langle z, J T_k x_n \right\rangle 
\leq \sum_{k=1}^{m} \alpha_{n,k} \|z\|^2 + \sum_{k=1}^{m} \alpha_{n,k} \|x_n\|^2 - 2R \sum_{k=1}^{m} \alpha_{n,k} \left\langle z, J x_n \right\rangle 
= \|z\|^2 + \|x_n\|^2 - 2R \left\langle z, J x_n \right\rangle 
= \phi(z, x_n),
\]

where the fact that the mappings are costerro bounded linear mappings in the third step is used. Hence, it is shown that $z \in \mathcal{C}_{m+1}$. From Lemma 2, it is concluded that $\{\Pi_{\mathcal{C}} x_n\}_{n \in \mathbb{N}}$ converges strongly to $\Pi_{\mathcal{C}} x$.

**Lemma 7.** The sequence $\{x_n\}_{n \in \mathbb{N}}$ satisfies the inequality

\[
(x_n, \Pi_{\mathcal{C}} u) \leq \varepsilon_n^2.
\]

**Proof.** Since $\Lambda(u, \mathcal{C}) = \inf_{z \in \mathcal{C}} \phi(x, u) = \phi(\Pi_{\mathcal{C}} u, u)$, then for every $\varepsilon_n > 0$, $x_n \in \mathcal{C}$ is found such that

\[
\phi(x_n, u) \leq \Lambda(\mathcal{C}, u) + \varepsilon_n^2 = \phi(\Pi_{\mathcal{C}} u, u) + \varepsilon_n^2,
\]

which implies that

\[
\phi(x_n, u) - \phi(\Pi_{\mathcal{C}} u, u) \leq \varepsilon_n^2.
\]

However, Proposition 1 implies that

\[
\phi(x_n, \Pi_{\mathcal{C}} u) \leq \phi(x_n, u) - \phi(\Pi_{\mathcal{C}} u, u),
\]

and so in addition to equation (37), the following inequality is obtained:

\[
\phi(x_n, \Pi_{\mathcal{C}} u) \leq \varepsilon_n^2,
\]

which completes the proof.

The main result of this paper is given by the following theorem.

**Theorem 3 (main result).** Let $\mathcal{X}$ be a uniformly convex smooth Banach space and suppose any of the following cases hold:

(i) The space $\mathcal{X}$ is finite dimensional.

(ii) The convex set $\mathcal{C}$ is compact.

(iii) $\varepsilon_0 = 0$.

Then, $\omega(\{x_n\}_{n \in \mathbb{N}}) \neq \emptyset$ and $\omega(\{x_n\}_{n \in \mathbb{N}}) \subseteq \bigcap_{k=1}^{m} F(T_k)$, where $\omega$ denotes the (strong) limit set of the iterative sequence $\{x_n\}_{n \in \mathbb{N}}$.

**Remark 2.** We also note that for infinite dimensions, we can also say that the sequence $\{x_n\}_{n \in \mathbb{N}}$ has a weak limit point since a uniformly convex smooth Banach is a reflexive space.
Data Availability
No data were used as far as this research is concerned.

Conflicts of Interest
The author declares that there are no conflicts of interest.

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