Research Article

Omega Index of Line and Total Graphs

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A derived graph is a graph obtained from a given graph according to some predetermined rules. Two of the most frequently used derived graphs are the line graph and the total graph. Calculating some properties of a derived graph helps to calculate the same properties of the original graph. For this reason, the relations between a graph and its derived graphs are always welcomed. A recently introduced graph index which also acts as a graph invariant called omega is used to obtain such relations for line and total graphs. As an illustrative exercise, omega values and the number of faces of the line and total graphs of some frequently used graph classes are calculated.

1. Introduction

Let G be a simple graph with $V(G) = \{v_1, v_2, \dots, v_n\}$ and $E(G) = \{e_1, e_2, \dots, e_m\}$ as the vertex and edge sets. n and m are called the order and size of G , respectively, and are the most important graph parameters. If $e = uv \in E(G)$, we say that u and v are adjacent and e is incident to u and v . The number of edges incident to a vertex v is called the degree of v and denoted by $d_G v$, or by dv if there is no confusion. A vertex of degree 1 is named as the pendant vertex. The set of degrees,

$$\{1^{(a_1)}, 2^{(a_2)}, \dots, \Delta^{(a_\Delta)}\}, \quad (1)$$

of all vertices where Δ is the biggest vertex degree in G , is called the degree sequence of the graph.

A graph which is connected and has no cycles is called a tree. A graph is called acyclic, unicyclic, bicyclic, tricyclic, etc. according to the number of cycles it has as 0, 1, 2, 3, etc. As usual, the path, cycle, star, complete, complete bipartite, and tadpole graphs are denoted by P_n , C_n , S_n , K_n , $K_{r,s}$, and $T_{r,s}$, respectively. For other graph theoretical notions used in this paper, see, e.g., [1–3].

Given a graph G , the line graph $L(G)$ of G is the graph whose vertex set is $E(G)$ with two vertices of $L(G)$ being

adjacent iff corresponding edges in G are adjacent. For some applications of the line graph, see, e.g., [4, 5]. Similarly, the total graph $T(G)$ of G is the graph whose vertex set is $V(G) \cup E(G)$ with two vertices of $T(G)$ being adjacent iff the corresponding elements of G are either adjacent or incident. Line graphs and total graphs are two examples of derived graphs. Minimal doubly resolving sets and strong metric dimension of the layer sun graph and the line graph of this graph are calculated in [4]. The classical meanness property of some graphs based on line graphs was considered in [5]. For some recent applications of the total graphs, see, e.g., [6–8].

According to definitions, the degree sequences of the line and total graphs are

$$\begin{aligned} DS(L(G)) &= \{d_G u + d_G v - 2 : uv \in E(G)\} = \{d_G e : e \in E(G)\}, \\ DS(T(G)) &= \{d_{T(G)} v : v \in V(G)\} \cup \{d_{T(G)} e : e \in E(G)\}. \end{aligned} \quad (2)$$

2. Omega Index and Fundamentals

In this paper, we study the line and total graphs in relation with omega index and the number of faces known as the

cyclomatic number. Omega index is an additive quantity defined for a given degree sequence (1) or for a graph with

$$\Omega(G) = \sum_{i=1}^{\Delta} a_i (d_i - 2). \quad (3)$$

It is shown that $\Omega(G) = 2(m - n)$ and therefore it is always an even number. It is shown that the omega characteristic gives us very powerful information about cyclicity and connectedness of all the realizations of a given degree sequence (see, e.g., [9]). In brief, it is shown that all realizations of a degree sequence D with $\Omega(D) \leq -4$ must be disconnected; each connected realization of a degree sequence D with $\Omega(D) = -2$ must be a tree; each connected realization of a degree sequence D with $\Omega(D) = 0$ must be a unicyclic graph; each connected realization of a degree sequence D with $\Omega(D) = 2$ must be a bicyclic graph, etc. Also, the number of faces of a graph or all the realizations of a given degree sequence is formulated as

$$r(G) = \frac{\Omega(G)}{2} + c(G), \quad (4)$$

where $c(G)$ is the number of components of G . For more properties of the omega index, see [10, 11]. The effect of edge and vertex deletion on the omega index is studied in [9]. Next, we obtain the number of pendant vertices of a caterpillar tree which consists of a main path so that all vertices are having maximum distance 1 from the path.

Theorem 1. *Let G be a caterpillar tree. Let the nonpendant vertices of G be $v_1, v_2, \dots, v_k$ so that v_1 has unique nonpendant neighbor v_2 ; v_k has unique nonpendant neighbor*

v_{k-1} ; and v_i has two nonpendant vertices v_{i-1} and v_{i+1} for $i = 2, 3, \dots, k-1$. The following relation holds:

$$a_1(G) = \sum_{i=1}^k d_G i - 2(k-1), \quad (5)$$

where $d_G i$ is the degree of v_i .

Proof. By counting, v_1 has only one nonpendant neighbor and hence $d_G 1 - 1$ pendant neighbors, v_k has only one nonpendant neighbor and hence $d_G k - 1$ pendant neighbors, and similarly, for $i = 2, 3, \dots, k-1$, the vertex v_i has $d_G i - 2$ pendant neighbors. Therefore,

$$\begin{aligned} a_1(G) &= d_G 1 - 1 + \sum_{i=2}^{k-1} (d_G i - 2) + d_G k - 1 \\ &= \sum_{i=1}^k d_G i - 2(k-1), \end{aligned} \quad (6)$$

thus giving the result. $\square$

Corollary 1. *For any tree T , we have*

$$a_1(T) + k - m(T) = 1. \quad (7)$$

For a caterpillar tree, the degree sequence of its line graph can be stated more deterministically.

Theorem 2. *Let T be a caterpillar tree. Let the degrees of the nonpendant vertices of T be $d_G 1, d_G 2, \dots, d_G k$. The degree sequence of the line graph of T is*

$$DS(L(T)) = \left\{ \begin{aligned} &(d_G 1 - 1)^{(d_G 1 - 1)}, (d_G 2 - 1)^{(d_G 2 - 2)}, \dots, (d_G (k-1) - 1)^{(d_G (k-1) - 2)}, \\ &(d_G k - 1)^{(d_G k - 1)}, (d_G 1 + d_G 2 - 2)^{(1)}, (d_G 2 + d_G 3 - 2)^{(1)}, \dots, \\ &(d_G (k-1) + d_G k - 2)^{(1)} \end{aligned} \right\}. \quad (8)$$

Proof. By Theorem 5 in [11], there exists a complete graph $K_{d_G i}$ in $L(T)$ around each nonpendant vertex $v_i \in V(G)$ of degree $d_T i$ in T . Also, $v_i \sim v_j$ iff $K_{d_T i}$ and $K_{d_T j}$ have a common vertex. Therefore, $K_{d_T 1}$ has $d_T 1 - 1$ vertices of degree $d_T 1 - 1$; $K_{d_T k}$ has $d_T k - 1$ vertices of degree $d_T k - 1$; and each of other complete graphs $K_{d_T i}$ for $i = 2, 3, \dots, k-1$ has $d_T i - 2$ vertices of degree $d_T i - 1$. Also, the intersection vertex of $K_{d_T i}$ and $K_{d_T (i+1)}$ is of degree $d_T i - 1 + d_T (i+1) - 1$ for $i = 2, 3, \dots, k-1$. Hence, the result follows. $\square$

The next result gives the relation between the edge numbers of G and $L(G)$ by means of the first Zagreb index of G :

Lemma 1. *For a given graph G , we have*

$$m(L(G)) = \frac{1}{2} M_1(G) - m(G). \quad (9)$$

Proof. By definition, we have

$$\begin{aligned} m(L(G)) &= \frac{1}{2} \sum_{e \in E(G)} d_e \\ &= \frac{1}{2} \sum_{e=uv \in E(G)} (d_u + d_v - 2) \\ &= \frac{1}{2} \sum_{u \in V(G)} d_u^2 - \sum_{e \in E(G)} 1 \\ &= \frac{1}{2} M_1(G) - m(G). \end{aligned} \quad (10)$$

$\square$

In the following result, we calculate the omega index of the line graph of G when G is k -cyclic by means of triangular numbers $T_n = n(n+1)/2$.

Corollary 2. For a given graph G with k – cycles, we have

$$\Omega(L(G)) = 2 \sum_{i=3}^{\Delta} (a_i T_{i-2} - 1) + k. \quad (11)$$

The following results are about the omega index of the line graph.

Theorem 3. For a graph G , we have

$$\Omega(L(G)) = M_1(G) - 4m(G). \quad (12)$$

Proof. As $DS(L(G)) = \{d_{e_1}, d_{e_2}, \dots, d_{e_m}\}$ and $d_{e_i} = d_{u_i} + d_{v_i} - 2$, we have

$$\begin{aligned} \Omega(L(G)) &= \sum_{e_i \in E(G)} (d_{e_i} - 2) \\ &= \sum_{u_i, v_i \in E(G)} (d_{u_i} + d_{v_i} - 4) \\ &= \sum_{u \in V(G)} d_u^2 - 4m(G) \\ &= M_1(G) - 4m(G). \end{aligned} \quad (13)$$

□

Corollary 3. For a graph G , we have

$$\Omega(L(G)) = \sum_{i=1}^n d_i (d_i - 2). \quad (14)$$

Proof. By Theorem 3,

$$\begin{aligned} \Omega(L(G)) &= M_1(G) - 4m(G) \\ &= \sum_{i=1}^n d_i^2 - 2 \sum_{i=1}^n d_i, \end{aligned} \quad (15)$$

thus giving the result. □

Corollary 4. For a graph G , we have

$$\Omega(L(G)) = M_1(G) - 2\Omega(G) - 4n(G). \quad (16)$$

Proof. It follows from $\Omega(G) = 2(m(G) - n(G))$. □

Now, we obtain some results on the omega index of the total graphs.

Corollary 5. For a connected k – cyclic graph G , we have

$$\Omega(T(G)) = M_1(G) + 2k - 2. \quad (17)$$

Corollary 6. For a connected k – cyclic graph G , we have

$$\Omega(T(G)) = \Omega(L(G)) + 4m(G) + 2k - 2. \quad (18)$$

Proof. It follows by Corollary 5 and Theorem 3. □

Corollary 7. For any graph G , we have

$$\Omega(T(G)) - \Omega(L(G)) = 3\Omega(G) + 4n(G). \quad (19)$$

Proof. It follows by the definition of omega index. □

This means that for every graph G , $\Omega(T(G)) - \Omega(L(G)) - 3\Omega(G)$ is fixed and is equal to $4n(G)$.

In [11], the number of faces of the line graph of a tree T was given by

$$r(L(T)) = \sum_{i=3}^{\Delta} a_i T_{i-2}, \quad (20)$$

where $T_n = n(n+1)/2$ is the n – th triangular number. In [?], this number for a tricyclic graph G was given by

$$r(L(G)) = 3 + \sum_{i=3}^{\Delta} a_i T_{i-2}. \quad (21)$$

These suggest the following generalization.

Theorem 4. Let G be a simple, connected, and k – cyclic graph with degree sequence (1). The number of faces of the line graph $L(G)$ is

$$r(L(G)) = k + \sum_{i=3}^{\Delta} a_i T_{i-2}. \quad (22)$$

Proof. For acyclic part of G , the formula is given in equation (20). For each t – cycle C in G , $L(G)$ has another t – cycle C' formed by joining the midpoints of the edges of C . Hence, the number of cycles in G must be added to $\sum_{i=3}^{\Delta} a_i T_{i-2}$ giving the result. □

Inverse problems in mathematics are quite important due to their applications. In graph theory, the inverse problem is the one which deals with finding the values of a given topological graph index. Here, we solve a similar problem for the number of faces of the line graph.

Theorem 5. Let G be a connected graph. Then, $r(L(G))$ can take any positive integer value.

Proof. By Theorem 4, we have equation (22) for a simple, connected, k – cyclic graph G . This gives us the following linear equality:

$$r(L(G)) = k + a_3 + 3a_4 + 6a_5 + 10a_6 + \dots + \frac{(\Delta-2)(\Delta-1)}{2} a_{\Delta}. \quad (23)$$

As $a_i \geq 0$ are integers and as a_3 has coefficient 1, $r(L(G))$ can take any positive integer value. □

Some special cases are as follows.

Corollary 8. Let T be a tree with no vertices of degree 3. Then, $r(L(T))$ can take all positive integers except 1, 2, 4, 5, 7, 8, 11, 14, and 17.

Proof. By the equality in Theorem 11 in [12], we have

$$r(L(T)) = 3a_4 + 6a_5 + 10a_6 + \dots + \frac{(\Delta - 2)(\Delta - 1)}{2}a_\Delta. \quad (24)$$

As $a_i \geq 0$ are integers, the result follows. $\square$

Corollary 9. Let T be a tree with no vertices of degree 3 or 4. Then, $r(L(T))$ can take all positive integer values except 1, 2, 3, 4, 5, 7, 8, 9, 11, 13, 14, 17, 19, 23, and 29.

Proof. Note that

$$r(L(T)) = 6a_5 + 10a_6 + 15a_7 + \dots + \frac{(\Delta - 2)(\Delta - 1)}{2}a_\Delta. \quad (25)$$

After easy observations, we find that the class $10 + 10n$ has all integers ≥ 10 ending with 0; $6 + 10n$ has all integers ≥ 6 ending with 6; $2 \cdot 6 + 10n$ has all integers ≥ 12 ending with 2; $3 \cdot 6 + 10n$ has all integers ≥ 18 ending with 8; $21 + 10n$ has all integers ≥ 21 ending with 1; $21 + 2 \cdot 6 + 10n$ has all integers ≥ 33 ending with 3; $6 \cdot 4 + 10n$ has all integers ≥ 24 ending with 4; $15 + 10n$ has all integers ≥ 15 ending with 5; $15 + 2 \cdot 6 + 10n$ has all integers ≥ 27 ending with 7; and finally, $21 + 3 \cdot 6 + 10n$ has all integers ≥ 39 ending with 9. This implies that only the values given above cannot be attainable by $r(L(G))$. $\square$

Then, we obtain the following result.

Corollary 10. We have

$$\Omega(L(G)) - \Omega(G) = 2 \sum_{\Delta} a_i T_{i-2}. \quad (26)$$

The following variation of this result has useful applications related to cyclicity.

Corollary 11. We have

$$r(L(G)) = \frac{\Omega(G)}{2} + 1 + \sum_{i=3}^{\Delta} a_i T_{i-2}. \quad (27)$$

By Corollary 11, we have the following cases:

- (i) If G is acyclic, then $r(L(G)) = \sum_{i=3}^{\Delta} a_i T_{i-2}$
- (ii) If G is unicyclic, then $r(L(G)) = 1 + \sum_{i=3}^{\Delta} a_i T_{i-2}$
- (iii) If G is bicyclic, then $r(L(G)) = 2 + \sum_{i=3}^{\Delta} a_i T_{i-2}$
- (iv) If G is k -cyclic, then $r(L(G)) = k + \sum_{i=3}^{\Delta} a_i T_{i-2}$

3. Omega and r of the Line Graphs of Some Special Graphs

Now, we consider the omega and r values of some frequently used graph classes. First, we give a new proof of the fact that the line graph of P_n is P_{n-1} .

Lemma 2. We have

$$L(P_n) = P_{n-1}. \quad (28)$$

Proof. Recall that $DS(P_n) = \{1^{(2)}, 2^{(n-2)}\}$. We then have

$$\begin{aligned} DS(L(P_n)) &= \{0^{(0)}, 1^{(0)}, \dots, 1^{(0)}, 0^{(0)}, 1^{(1)}, 2^{(1)}, \dots, 2^{(1)}, 1^{(1)}\} \\ &= \{1^{(2)}, 2^{(n-3)}\} \\ &= DS(P_{n-1}). \end{aligned} \quad (29)$$

$\square$

Hence, $\Omega(L(P_n)) = \Omega(P_{n-1}) = -2$ as path graphs are acyclic. Also, $r(L(P_n)) = 0$.

Secondly, it is obvious that $L(C_n) = C_n$. Therefore, $\Omega(L(C_n)) = \Omega(C_n) = 0$ and $r(L(C_n)) = 1$.

Next, we consider the line graph of the star graph S_n . By the definition of the line graph, $L(S_n) = K_{n-1}$. Hence,

$$\begin{aligned} \Omega(L(S_n)) &= \Omega(K_{n-1}) \\ &= (n-1)(n-4), \\ r(L(S_n)) &= r(K_{n-1}) \\ &= \frac{(n-3)(n-2)}{2}. \end{aligned} \quad (30)$$

For a complete graph K_n , we have $DS(L(K_n)) = \{(2(n-2))^{(n(n-1)/2)}\}$ implying that $\Omega(L(K_n)) = n(n-1)/2 \cdot (2n-6) = n(n-1)(n-3)$ and $r(L(K_n)) = (n-2)(n^2-2n-1)$. In Figure 1, we illustrated the case of K_4 .

For a complete bipartite graph $K_{r,s}$, $L(K_{r,s})$ is a regular graph of degree $r+s-2$. Its degree sequence is $\{(r+s-2)^{(rs)}\}$. Hence, $\Omega(L(K_{r,s})) = rs(r+s-4)$ and $r(L(K_{r,s})) = rs(r+s-4)/2 + 1$.

Finally, consider the tadpole graph $T_{r,s}$. $L(T_{r,s})$ has degree sequence $\{1^{(1)}, 2^{(r+s-4)}, 3^{(3)}\}$. Hence, $\Omega(L(T_{r,s})) = 3 - 1 = 2$, and therefore, $r(L(T_{r,s})) = 2$.

4. Omega and r of the Total Graphs of Some Special Graphs

In this section, we calculate the omega and r values of some frequently used graphs. We first give an important property.

Lemma 3. Let G be a connected graph. Then, $T(G)$ cannot have any pendant vertex.

Proof. Let $v \in V(G)$. Let e be an edge incident to v . As G is connected, there is at least one adjacent vertex say u , to v . In

FIGURE 1: Line graph of K_4 .

the total graph $T(G)$, the vertex v will be adjacent to u and e implying the result. $\square$

The proof alternatively follows from the fact that $DS(T(G))$ consists of integers in the form of either $2d_i$ or $e_j + 2$, where $d_i, e_j \geq 1$.

Next, we give the relation between omega of G and omega of $T(G)$.

Theorem 6. For a connected graph G , we have

$$\Omega(T(G)) = \Omega(G) + M_1(G). \quad (31)$$

Proof. Recall that $DS(T(G))$ consists of a_i times $2d_i$ for every $v_i \in V(G)$ and $de_j + 2$'s for every $e_j = u_jv_j \in E(G)$. As $de_j = du_j + dv_j - 2$, we can deduce that $DS(T(G))$ consists of a_i times $2d_i$ for every $v_i \in V(G)$ and $du_j + dv_j$'s for every $e_j = u_jv_j \in E(G)$. Hence,

$$\begin{aligned} \Omega(T(G)) &= \sum_{v_i \in V(G)} a_i(2d_i - 2) + \sum_{e_j = u_jv_j \in E(G)} (du_j + dv_j - 2) \\ &= 2m(G) + \Omega(G) + \sum_{v \in V(G)} d_v^2 - 2m(G) \\ &= \Omega(G) + M_1(G). \end{aligned} \quad (32)$$

$\square$

Corollary 11. For a connected graph G , we have

$$\Omega(T(G)) = \Omega(G) + \Omega(L(G)) + 4m(G). \quad (33)$$

Proof. As in Theorem 6, we can write

$$\begin{aligned} \Omega(T(G)) &= \sum_{v_i \in V(G)} a_i(2d_i - 2) + \sum_{e_j \in E(G)} de_j \\ &= 2m(G) + \Omega(G) + \Omega(L(G)) + 2m(G) \\ &= \Omega(G) + \Omega(L(G)) + 4m(G). \end{aligned} \quad (34)$$

$\square$

Corollary 12. If G is an acyclic graph, then

$$\Omega(T(G)) = M_1(G) - 2, \quad (35)$$

and if G is a unicyclic graph, then

$$\Omega(T(G)) = M_1(G). \quad (36)$$

Finally, we give the following result for the omega indices of the total graphs of some frequently used graph classes:

Theorem 7. The omega index of the total graphs of some well-known graph classes is as follows:

$$\begin{aligned} \Omega(T(P_n)) &= 4n - 8, \\ \Omega(T(C_n)) &= 4n, \\ \Omega(T(S_n)) &= (n+1)(n-2), \\ \Omega(T(K_n)) &= n(n+1)(n-2), \\ \Omega(T(K_{r,s})) &= (r+s)(rs-2) + 2rs, \\ \Omega(T(T_{r,s})) &= 4(r+s) + 2. \end{aligned} \quad (37)$$

5. Conclusion

Derived graphs are graphs obtained from a given graph according to some rules. In this paper, two of the most frequently used derived graphs, the line and total graphs, are studied. Calculating some properties of a derived graph helps to calculate the same properties of the original graph. Here, by means of omega index and several results in recent papers, new relations for line and total graphs are obtained. Also, omega values and the number of faces of the line and total graphs of some frequently used graph classes are calculated. In the future works, similar ideas can be applied to establish several relations for other derived graphs.

Data Availability

No data were used to support this study.

Conflicts of Interest

The authors declare that they have no conflicts of interest.

Authors' Contributions

All authors contributed equally to this paper.

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