

Research Article

Some Formulas for New Quadruple Hypergeometric Functions

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In this paper, we aim to introduce six new quadruple hypergeometric functions. Then, we investigate certain formulas and representations for these functions such as symbolic formulas, differential formulas, and integral representations.

1. Introduction

Hypergeometric functions of several variables play an important role in diverse areas of science and engineering. The developments in applied mathematics, mathematical physics, chemistry, combinatorics, statistics, numerical analysis, and other areas have led to increasing interest in the study of multiple hypergeometric functions. Many authors have studied a number of formulas involving hypergeometric functions (see, e.g., [1–6]).

In [7], Exton presented twenty-one complete hypergeometric functions in four variables denoted by symbols K_1, K_2, \dots, K_{21} . In [8], Sharma and Parihar defined eighty-three complete quadruple hypergeometric functions, namely, $F_1^{(4)}, F_2^{(4)}, \dots, F_{83}^{(4)}$. Bin-Saad and Younis [9] gave thirty new quadruple hypergeometric functions given by $X_1^{(4)}, X_2^{(4)}, \dots, X_{30}^{(4)}$. In [10], the authors discovered the existence of twenty additional complete hypergeometric functions in four variables $X_{31}^{(4)}, X_{32}^{(4)}, \dots, X_{50}^{(4)}$. Each quadruple hypergeometric function in [7–10] is of the form

$$X^{(4)}(.) = \sum_{m,n,p,q=0}^{\infty} \Omega(m, n, p, q) \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!} \frac{u^q}{q!}, \quad (1)$$

where $\Omega(m, n, p, q)$ is a certain sequence of complex parameters, and there are twelve parameters in each series of $X^{(4)}(.)$ (eight a 's and four c 's). The 1st, 2nd, 3rd, and 4th parameters in $X^{(4)}(.)$ are connected with integers m, n, p , and q , respectively. Each repeated parameter in the series $X^{(4)}(.)$ points out a term with double parameters in $\Omega(m, n, p, q)$. For example, $X^{(4)}(a_1, a_1, a_2, a_2, a_3, a_3, a_4, a_5)$ means that $(a_1)_{m+n}(a_2)_{p+q}(a_3)_{m+n}(a_4)_p(a_5)_q$ includes the term. Similarly, $X^{(4)}(a_1, a_1, a_1, a_2, a_1, a_1, a_2, a_3)$ points out the term $(a_1)_{2m+2n+p}(a_2)_{p+q}(a_3)_q$ and $X^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4)$ shows the existence of the term $(a_1)_{2m+n}(a_2)_{n+p}(a_3)_{p+q}(a_4)_q$. Thus, it is possible to form various combinations of indices. There seems to be no way of independently establishing the number of distinct Gaussian hypergeometric series for any given integer $n \geq 2$ without explicitly stating all such series. Thus, in every situation with $n = 4$, one ought to begin by actually constructing the set just as in the case $n = 3$ (see [11]).

By using the conventions and notations above, we now introduce further quadruple hypergeometric functions as follows:

$$\begin{aligned}
X_{85}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_3, c_1; x, y, z, u) &= \sum_{m,n,p,q=0}^{\infty} \frac{(a_1)_{2m+n}(a_2)_{n+p}(a_3)_{p+q}(a_4)_q}{(c_1)_{m+q}(c_2)_n(c_3)_p} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!} \frac{u^q}{q!}, \\
X_{86}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_3, c_1; x, y, z, u) &= \sum_{m,n,p,q=0}^{\infty} \frac{(a_1)_{2m+n}(a_2)_{n+p}(a_3)_{p+q}(a_4)_q}{(c_1)_{n+q}(c_2)_m(c_3)_p} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!} \frac{u^q}{q!}, \\
X_{87}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_2, c_1; x, y, z, u) &= \sum_{m,n,p,q=0}^{\infty} \frac{(a_1)_{2m+n}(a_2)_{n+p}(a_3)_{p+q}(a_4)_q}{(c_1)_{m+p}(c_2)_{n+q}} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!} \frac{u^q}{q!}, \\
X_{88}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_2, c_1, c_1; x, y, z, u) &= \sum_{m,n,p,q=0}^{\infty} \frac{(a_1)_{2m+n}(a_2)_{n+p}(a_3)_{p+q}(a_4)_q}{(c_1)_{m+q}(c_2)_{n+p}} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!} \frac{u^q}{q!}, \\
X_{89}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_1, c_1; x, y, z, u) &= \sum_{m,n,p,q=0}^{\infty} \frac{(a_1)_{2m+n}(a_2)_{n+p}(a_3)_{p+q}(a_4)_q}{(c_1)_{m+p+q}(c_2)_n} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!} \frac{u^q}{q!}, \\
X_{90}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c, c, c, c; x, y, z, u) &= \sum_{m,n,p,q=0}^{\infty} \frac{(a_1)_{2m+n}(a_2)_{n+p}(a_3)_{p+q}(a_4)_q}{(c)_{m+n+p+q}} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!} \frac{u^q}{q!},
\end{aligned} \tag{2}$$

for

$$\left(|x| < \frac{1}{4}, |y| < 1, |z| < 1, |u| < 1\right). \tag{3}$$

Here, $(a)_m$ is the Pochhammer symbol defined (for $a, m \in \mathbb{C}$), in terms of the familiar Gamma function Γ , by (see, e.g., [11], p. 2 and p. 5)

$$\begin{aligned}
(a)_m &:= \frac{\Gamma(a+m)}{\Gamma(a)}, \quad (a+m \in \mathbb{C} \setminus \mathbb{Z}_0^-) \\
&= \begin{cases} 1, & (m = 0), \\ a(a+1)\dots(a+m-1), & (m = n \in \mathbb{N}), \end{cases}
\end{aligned} \tag{4}$$

where $\mathbb{C}, \mathbb{Z}_0^-$, and \mathbb{N} denote the sets of complex numbers, nonpositive integers, and positive integers, respectively.

We recall the Gauss hypergeometric function [12] which is defined by

$${}_2F_1(a, b; c; x) = \sum_{n=0}^{\infty} \frac{(a)_n(b)_n}{(c)_n} \frac{x^n}{n!}, \quad (|x| < 1). \tag{5}$$

Appell's double hypergeometric function F_2 is defined as follows [13]:

$$F_2(a, b, c; d, e; x, y) = \sum_{m,n=0}^{\infty} \frac{(a)_{m+n}(b)_m(c)_n}{(d)_m(e)_n} \frac{x^m}{m!} \frac{y^n}{n!}. \tag{6}$$

In [14], Exton established twenty distinct triple hypergeometric functions, which are denoted by X_1, X_2, \dots, X_{20} . We introduce the definitions of five of these functions in the following:

$$\begin{aligned}
X_{15}(a_1, a_2, a_3; c_2, c_1; x, y, z) &= \sum_{m,n,p=0}^{\infty} \frac{(a_1)_{2m+n}(a_2)_{n+p}(a_3)_p}{(c_1)_{n+p}(c_2)_m} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!}, \\
X_{16}(a_1, a_2, a_3; c_1, c_2; x, y, z) &= \sum_{m,n,p=0}^{\infty} \frac{(a_1)_{2m+n}(a_2)_{n+p}(a_3)_p}{(c_1)_{m+p}(c_2)_n} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!}, \\
X_{17}(a_1, a_2, a_3; c_1, c_2, c_3; x, y, z) &= \sum_{m,n,p=0}^{\infty} \frac{(a_1)_{2m+n}(a_2)_{n+p}(a_3)_p}{(c_1)_m(c_2)_n(c_3)_p} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!}, \\
X_{18}(a_1, a_2, a_3, a_4; c; x, y, z) &= \sum_{m,n,p=0}^{\infty} \frac{(a_1)_{2m+n}(a_2)_n(a_3)_p(a_4)_p}{(c)_{m+n+p}} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!}, \\
X_{20}(a_1, a_2, a_3, a_4; c_1, c_2; x, y, z) &= \sum_{m,n,p=0}^{\infty} \frac{(a_1)_{2m+n}(a_2)_n(a_3)_p(a_4)_p}{(c_1)_{m+p}(c_2)_n} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!}.
\end{aligned} \tag{7}$$

The Lauricella functions of three variables F_M, F_N, F_p, F_S , and F_T are defined in [11, 15]:

$$\begin{aligned} F_M(a_1, a_2, a_2, b_1, b_2, b_1; c_1, c_2, c_2; x, y, z) &= \sum_{m,n,p=0}^{\infty} \frac{(a_1)_m (a_2)_{n+p} (b_1)_{m+p} (b_2)_n}{(c_1)_m (c_2)_{n+p}} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!}, \\ F_N(a_1, a_2, a_3, b_1, b_2, b_1; c_1, c_2, c_2; x, y, z) &= \sum_{m,n,p=0}^{\infty} \frac{(a_1)_m (a_2)_n (a_3)_p (b_1)_{m+p} (b_2)_n}{(c_1)_m (c_2)_{n+p}} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!}, \\ F_p(a_1, a_2, a_1, b_1, b_1, b_2; c_1, c_2, c_2; x, y, z) &= \sum_{m,n,p=0}^{\infty} \frac{(a_1)_{m+p} (a_2)_n (b_1)_{m+n} (b_2)_p}{(c_1)_m (c_2)_{n+p}} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!}, \\ F_S(a_1, a_2, a_2, b_1, b_2, b_3; c, c, c; x, y, z) &= \sum_{m,n,p=0}^{\infty} \frac{(a_1)_m (a_2)_{n+p} (b_1)_m (b_2)_n (b_3)_p}{(c)_{m+n+p}} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!}, \\ F_T(a_1, a_2, a_2, b_1, b_2, b_1; c, c, c; x, y, z) &= \sum_{m,n,p=0}^{\infty} \frac{(a_1)_m (a_2)_{n+p} (b_1)_{m+p} (b_2)_n}{(c)_{m+n+p}} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!}. \end{aligned} \quad (8)$$

The structure of this paper is as follows. In Sections 2 to 5, we obtain several symbolic formulas, differentiation formulas, operator formulas, and integral representations for the hypergeometric functions of four variables $X_{85}^{(4)}, X_{86}^{(4)}, \dots, X_{90}^{(4)}$.

2. Symbolic Formulas

First of all, we recall the following symbolic operators (see [16]):

$$D_{\delta}^m \delta^s = \frac{\Gamma(s+1)}{\Gamma(s-m+1)} \delta^{s-m}, \quad (9)$$

$$D_{\delta}^{-m} \delta^s = \frac{\Gamma(s+1)}{\Gamma(s+m+1)} \delta^{s+m}, \quad (10)$$

for

$$m \in \mathbb{N} \cup \{0\}, \quad s \in \mathbb{C} - \{-1, -2, \dots\}, \quad (11)$$

where D_{δ} and D_{δ}^{-1} are the derivative and integral operator, respectively.

Now, we find the following formulas.

Theorem 1. *The following results hold true:*

$$\begin{aligned} &\left[1 - \left(D_{\alpha_1} D_{\alpha_2} \beta^{-1} D_{\beta}^{-1} \gamma^{-1} D_{\gamma}^{-1} \alpha_1 \alpha_2 \right) u \right]^{-a} X_{17}(a_1, a_2, a_3; c_1, c_2; \beta x, y, \alpha_1 z) \\ &\times \left(\alpha_1^{a_3-1} \alpha_2^{a_4-1} \beta^{c_1-1} \gamma^{a-1} \right) = \alpha_1^{a_3-1} \alpha_2^{a_4-1} \beta^{c_1-1} \gamma^{a-1} X_{85}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4 c_1, c_2, c_3, c_1; \beta x, y, \alpha_1 z, u), \end{aligned} \quad (12)$$

$$\begin{aligned} &\left[1 - \left(D_{\alpha_1} D_{\alpha_2} \beta^{-1} D_{\beta}^{-1} \gamma^{-1} D_{\gamma}^{-1} \alpha_1 \alpha_2 \right) z \right]^{-a} X_{20}(a_1, a_2, a_3, a_4; c_1, c_2; x, \alpha_1 y, \alpha_2 u) \\ &\times \left(\alpha_1^{a_2-1} \alpha_2^{a_3-1} \beta^{c_3-1} \gamma^{a-1} \right) = \alpha_1^{a_2-1} \alpha_2^{a_3-1} \beta^{c_3-1} \gamma^{a-1} X_{85}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_3, c_1; x, \alpha_1 y, z, \alpha_2 u). \end{aligned} \quad (13)$$

Proof. To prove the result in equality (12) asserted in Theorem 1, let \emptyset denote the left-hand side of equality (12).

Then, employing the series representation of x_{17} and by using (9) and (10), we have

$$\begin{aligned} \emptyset &= \sum_{m,n,p,q=0}^{\infty} \frac{(a_1)_{2m+n} (a_2)_{n+p} (a_3)_p (a)_q \beta^{-q} \gamma^{-q}}{(c_1)_m (c_2)_n (c_3)_p m! n! p! q!} x^m y^n z^p u^q \times D_{\alpha_1}^q D_{\alpha_2}^q D_{\beta}^{-q} D_{\gamma}^{-q} \left(\alpha_1^{a_3+p+q-1} \alpha_2^{a_4+q-1} \beta^{c+m+q-1} \gamma^{a-1} \right) \\ &= \alpha_1^{a_3-1} \alpha_2^{a_4-1} \beta^{c_1-1} \gamma^{a-1} \sum_{m,n,p,q=0}^{\infty} \frac{(a_1)_{2m+n} (a_2)_{n+p} (a_3)_p (a_4)_q (\beta x)^m}{(c_1)_{m+q} (c_2)_n (c_3)_p} \frac{(y)^n}{m!} \frac{(\alpha_1 z)^p}{n!} \frac{u^q}{p!} \frac{q!}{q!} \end{aligned}$$

$$= \alpha_1^{a_3-1} \alpha_2^{a_4-1} \beta^{c_1-1} \gamma^{a-1} X_{85}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_3, c_1; x, y, z, u), \quad (14)$$

which completes the proof. Similarly, one can prove formulas (13) and (20). \square

Theorem 2. *The following results hold true:*

$$\begin{aligned} & [1 - (D_\alpha^2 \beta^{-1} D_\beta^{-1} \gamma^{-1} D_\gamma^{-1} \alpha^2) x]^{-a} F_P(a_3, a_3, a_1, a_2, a_2, a_4; c_3, c_1, c_1; z, \alpha y, u) \\ & \times (\alpha^{a_1-1} \beta^{c_2-1} \gamma^{a-1}) = \alpha^{a_1-1} \beta^{c_2-1} \gamma^{a-1} X_{86}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_2, c_1, c_3, c_1; x, \alpha y, z, u), \\ & [1 - (D_{\alpha_1} D_{\alpha_2} \beta^{-1} D_\beta^{-1} \gamma^{-1} D_\gamma^{-1} \alpha_1 \alpha_2) y]_2^{-a} F_1\left(\frac{a_1}{2}, \frac{a_1+1}{2}; c_2; 4\alpha_1^2 x\right) \\ & \times F_2(a_3, a_2, a_4; c_3, c_1; \alpha_2 z, \beta u) (\alpha_1^{a_1-1} \alpha_2^{a_2-1} \beta^{c_1-1} \gamma^{a-1}) = \alpha_1^{a_1-1} \alpha_2^{a_2-1} \beta^{c_1-1} \gamma^{a-1} \\ & X_{86}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_2, c_1, c_3, c_1; \alpha_1^2 x, y, \alpha_2 z, \beta u). \end{aligned} \quad (15)$$

Theorem 3. *The following results hold true:*

$$\begin{aligned} & [1 - (D_{\alpha_1} D_{\alpha_2} \beta^{-1} D_\beta^{-1} \gamma^{-1} D_\gamma^{-1} \alpha_1 \alpha_2) u]^{-a} X_{16}(a_1, a_2, a_3; c_1, c_2; x, \beta y, \alpha_1 z) \\ & \times (\alpha_1^{a_3-1} \alpha_2^{a_4-1} \beta^{c_2-1} \gamma^{a-1}) = \alpha_1^{a_3-1} \alpha_2^{a_4-1} \beta^{c_2-1} \gamma^{a-1} X_{87}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_2; x, \beta y, \alpha_1 z, u), \\ & [1 - (D_{\alpha_1} D_{\alpha_2} \beta^{-1} D_\beta^{-1} \gamma^{-1} D_\gamma^{-1} \alpha_1 \alpha_2) y]^{-a} F_N\left(a_4, \frac{a_1}{2}, a_2, a_3, a_3, \frac{a_1+1}{2}; c_2, c_1, c_1; \beta u, 4\alpha_1^2 x, \alpha_2 z\right) \\ & \times (\alpha_1^{a_1-1} \alpha_2^{a_2-1} \beta^{c_2-1} \gamma^{a-1}) = \alpha_1^{a_1-1} \alpha_2^{a_2-1} \beta^{c_2-1} \gamma^{a-1} X_{87}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_2; \alpha_1^2 x, y, \alpha_2 z, \beta u). \end{aligned} \quad (16)$$

Theorem 4. *The following results hold true:*

$$\begin{aligned} & [1 - (D_{\alpha_1} D_{\alpha_2} \beta^{-1} D_\beta^{-1} \gamma^{-1} D_\gamma^{-1} \alpha_1 \alpha_2) u]^{-a} X_{15}(a_1, a_2, a_3; c_1, c_2; \beta x, y, \alpha_1 z) \\ & \times (\alpha_1^{a_3-1} \alpha_2^{a_4-1} \beta^{c_1-1} \gamma^{a-1}) = \alpha_1^{a_3-1} \alpha_2^{a_4-1} \beta^{c_1-1} \gamma^{a-1} X_{88}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_1; \beta x, y, \alpha_1 z, u), \\ & [1 - (D_\alpha^2 \beta^{-1} D_\beta^{-1} \gamma^{-1} D_\gamma^{-1} \alpha^2) x]^{-a} F_M(a_4, a_2, a_2, a_3, a_3, a_1; c_1, c_2, c_2; \beta u, \alpha y, z) \\ & \times (\alpha^{a_1-1} \beta^{c_1-1} \gamma^{a-1}) = \alpha^{a_1-1} \beta^{c_1-1} \gamma^{a-1} X_{88}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_1; x, \alpha y, z, \beta u). \end{aligned} \quad (17)$$

Theorem 5. *The following results hold true:*

$$\begin{aligned} & [1 - (D_{\alpha_1} D_{\alpha_2} \beta^{-1} D_\beta^{-1} \gamma^{-1} D_\gamma^{-1} \alpha_1 \alpha_2) u]^{-a} X_{16}(a_1, a_2, a_3; c_1, c_2; \beta x, y, \alpha_1 \beta z) \\ & \times (\alpha_1^{a_3-1} \alpha_2^{a_4-1} \beta^{c_1-1} \gamma^{a-1}) = \alpha_1^{a_3-1} \alpha_2^{a_4-1} \beta^{c_1-1} \gamma^{a-1} X_{89}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_1; \beta x, y, \alpha_1 \beta z, u), \\ & [1 - (D_{\alpha_1} D_{\alpha_2} \beta^{-1} D_\beta^{-1} \gamma^{-1} D_\gamma^{-1} \alpha_1 \alpha_2) y]^{-a} F_S\left(\frac{a_1}{2}, a_3, a_3, \frac{a_1+1}{2}, a_2, a_4; c_1, c_1, c_1; 4\alpha_1 x, \alpha_2 z, u\right) \\ & \times (\alpha_1^{a_1-1} \alpha_2^{a_2-1} \beta^{c_2-1} \gamma^{a-1}) = \alpha_1^{a_1-1} \alpha_2^{a_2-1} \beta^{c_2-1} \gamma^{a-1} X_{89}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_1; \alpha_1 x, y, \alpha_2 z, u). \end{aligned} \quad (18)$$

Theorem 6. *The following results hold true:*

$$\begin{aligned} & \left[1 - \left(D_{\alpha_1} D_{\alpha_2} \beta^{-1} D_{\beta}^{-1} \gamma^{-1} D_{\gamma}^{-1} \alpha_1 \alpha_2 \right) z \right]^{-a} X_{18}(a_1, a_2, a_3, a_4; c; \beta x, \alpha_1 \beta y, \alpha_2 \beta u) \\ & \times \left(\alpha_1^{a_2-1} \alpha_2^{a_3-1} \beta^{c-1} \gamma^{a-1} \right) = \alpha_1^{a_2-1} \alpha_2^{a_3-1} \beta^{c-1} \gamma^{a-1} X_{90}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c, c, c; \beta x, \alpha_1 \beta y, z, \alpha_2 \beta u), \end{aligned} \quad (19)$$

$$\begin{aligned} & \left[1 - \left(D_{\alpha}^2 \beta^{-1} D_{\beta}^{-1} \gamma^{-1} D_{\gamma}^{-1} \alpha^2 \right) x \right]^{-a} F_T(a_4, a_2, a_2, a_3, a_1, a_3; c, c, c; \beta u, \alpha \beta y, \beta z) \\ & \times \left(\alpha^{a_1-1} \beta^{c-1} \gamma^{a-1} \right) = \alpha^{a_1-1} \beta^{c-1} \gamma^{a-1} X_{90}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c, c, c; x, \alpha \beta y, \beta z, \beta u). \end{aligned} \quad (20)$$

3. Differentiation Formulas

The results of this section can be derived from formula (9) by a direct evaluation.

Theorem 7. *The following derivative formulas hold true:*

$$\begin{aligned} & D_{w_1}^{a_1-c} D_{w_2}^{a_2-c'} \left[w_1^{a_1-1} w_2^{a_2-1} X_{85}^{(4)}(c, c, c', a_3, c, c', a_3, a_4; c_1, c_2, c_3, c_1; w_1^2 x, w_1 w_2 y, w_2 z, u) \right] \\ & = \frac{\Gamma(a_1) \Gamma(a_2)}{\Gamma(c) \Gamma(c')} w_1^{c-1} w_2^{c'-1} X_{85}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_3, c_1; w_1^2 x, w_1 w_2 y, w_2 z, u), \\ & D_{w_1}^{a_2-c} D_{w_2}^{a_3-c'} \left[w_1^{a_2-1} w_2^{a_3-1} X_{85}^{(4)}(a_1, a_1, c, c', a_1, c, c', a_4; c_1, c_2, c_3, c_1; x, w_1 y, w_1 w_2 z, w_2 u) \right] \\ & = \frac{\Gamma(a_2) \Gamma(a_3)}{\Gamma(c) \Gamma(c')} w_1^{c-1} w_2^{c'-1} X_{85}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_3, c_1; x, w_1 y, w_1 w_2 z, w_2 u), \\ & D_{w_1}^{a_3-c} D_{w_2}^{a_4-c'} \left[w_1^{a_3-1} w_2^{a_4-1} X_{85}^{(4)}(a_1, a_1, a_2, c, a_1, a_2, c, c'; c_1, c_2, c_3, c_1; x, y, w_1 z, w_1 w_2 u) \right] \\ & = \frac{\Gamma(a_3) \Gamma(a_4)}{\Gamma(c) \Gamma(c')} w_1^{c-1} w_2^{c'-1} X_{85}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_3, c_1; x, y, w_1 z, w_1 w_2 u). \end{aligned} \quad (21)$$

Theorem 8. *The following differentiation formulas hold:*

$$\begin{aligned} & D_x^{a_1-c} \left[x^{a_1-1} X_{86}^{(4)}(c, c, a_2, a_3, c, a_2, a_3, a_4; c_2, c_1, c_3, c_1; x^2, xy, z, u) \right] \\ & = \frac{\Gamma(a_1)}{\Gamma(c)} x^{c-1} X_{86}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_2, c_1, c_3, c_1; x^2, xy, z, u), \\ & D_x^{a_1-c} D_y^{a_2-c'} \left[x^{a_1-1} y^{a_2-1} X_{86}^{(4)}(c, c, c', a_3, c, c', a_3, a_4; c_2, c_1, c_3, c_1; x^2, xy, yz, u) \right] \\ & = \frac{\Gamma(a_1) \Gamma(a_2)}{\Gamma(c) \Gamma(c')} x^{c-1} y^{c'-1} X_{86}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_2, c_1, c_3, c_1; x^2, xy, yz, u), \\ & D_u^{a_4-c} \left[u^{a_4-1} X_{86}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, c; c_2, c_1, c_3, c_1; x, y, z, u) \right] \\ & = \frac{\Gamma(a_4)}{\Gamma(c)} u^{c-1} X_{86}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_2, c_1, c_3, c_1; x, y, z, u). \end{aligned} \quad (22)$$

Theorem 9. *The following derivative formulas hold true:*

$$\begin{aligned}
 & D_w^{a_2-c} D_z^{a_3-c'} \left[w^{a_2-1} z^{a_3-1} X_{87}^{(4)}(a_1, a_1, c, c', a_1, c, c', a_4; c_1, c_2, c_1, c_2; x, w, y, wz, uz) \right] \\
 &= \frac{\Gamma(a_2)\Gamma(a_3)}{\Gamma(c)\Gamma(c')} w^{c-1} z^{c'-1} X_{87}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_2; x, w, y, wz, uz), \\
 & D_w^{a_1-c} D_y^{a_2-c'} D_z^{a_3-c''} \left[w^{a_1-1} y^{a_2-1} z^{a_3-1} X_{87}^{(4)}(c, c, c', c'', c, c', c'', a_4; c_1, c_2, c_1, c_2; w^2 x, w, y, wz, uz) \right] \\
 &= \frac{\Gamma(a_1)\Gamma(a_2)\Gamma(a_3)}{\Gamma(c)\Gamma(c')\Gamma(c'')} w^{c-1} y^{c'-1} z^{c''-1} X_{87}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_2; w^2 x, w, y, wz, uz), \\
 & D_{w_1}^{a_1-c} D_{w_2}^{a_4-c'} \left[w_1^{a_1-1} w_2^{a_4-1} X_{87}^{(4)}(c, c, a_2, a_3, c, a_2, a_3, a_4; c_1, c_2, c_1, c_2; w_1^2 x, w_1 y, z, w_2 u) \right] \\
 &= \frac{\Gamma(a_1)\Gamma(a_4)}{\Gamma(c)\Gamma(c')} w_1^{c-1} w_2^{c'-1} X_{87}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_2; w_1^2 x, w_1 y, z, w_2 u).
 \end{aligned} \tag{23}$$

Theorem 10. *The following derivative formulas hold true:*

$$\begin{aligned}
 & D_y^{a_2-c} \left[y^{a_2-1} X_{88}^{(4)}(a_1, a_1, c, a_3, a_1, c, a_3, a_4; c_1, c_2, c_1, c_2; x, y, wz, u) \right] \\
 &= \frac{\Gamma(a_2)}{\Gamma(c)} y^{c-1} X_{88}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_2; x, y, wz, u), \\
 & D_z^{a_2-c} \left[z^{a_2-1} X_{88}^{(4)}(a_1, a_1, c, a_3, a_1, c, a_3, a_4; c_1, c_2, c_1, c_2; x, wz, z, u) \right] \\
 &= \frac{\Gamma(a_2)}{\Gamma(c)} z^{c-1} X_{88}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_2; x, wz, z, u), \\
 & D_{w_1}^{a_1-c} D_{w_2}^{a_2-c'} D_{w_3}^{a_3-c''} D_{w_4}^{a_4-c'''} \left[w_1^{a_1-1} w_2^{a_2-1} w_3^{a_3-1} w_4^{a_4-1} X_{88}^{(4)}(c, c, c', c'', c, c', c'', c''' ; c_1, c_2, c_1, c_2; w_1^2 x, w_1 w_2 y, w_2 w_3 z, w_3 w_4 u) \right] \\
 &= \frac{\Gamma(a_1)\Gamma(a_2)\Gamma(a_3)\Gamma(a_4)}{\Gamma(c)\Gamma(c')\Gamma(c'')\Gamma(c''')} w_1^{c-1} w_2^{c'-1} w_3^{c''-1} w_4^{c'''-1} \\
 &\quad \times X_{88}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_2; w_1^2 x, w_1 w_2 y, w_2 w_3 z, w_3 w_4 u).
 \end{aligned} \tag{24}$$

Theorem 11. *The following derivative formulas hold true:*

$$\begin{aligned}
 & D_y^{a_1-c} \left[y^{a_1-1} X_{89}^{(4)}(c, c, a_2, a_3, c, a_2, a_3, a_4; c_1, c_2, c_1, c_1; xy^2, y, z, u) \right] \\
 &= \frac{\Gamma(a_1)}{\Gamma(c)} y^{c-1} X_{88}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_1; xy^2, y, z, u), \\
 & D_y^{a_1-c} D_w^{a_2-c'} \left[y^{a_1-1} w^{a_2-1} X_{89}^{(4)}(c, c, c', a_3, c, c', a_3, a_4; c_1, c_2, c_1, c_1; xy^2, w, y, wz, u) \right]
 \end{aligned}$$

$$\begin{aligned}
&= \frac{\Gamma(a_1)\Gamma(a_2)}{\Gamma(c)\Gamma(c')} y^{c'-1} w^{c'-1} X_{89}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_1; xy^2, wy, wz, u), \\
D_x^{a_1-c} D_{w_1}^{a_2-c''} D_z^{a_3-c'''} D_{w_2}^{a_4-c'''} &\left[x^{a_1-1} w_1^{a_2-1} z^{a_3-1} w_2^{a_4-1} X_{89}^{(4)}(c, c, c', c'', c, c', c'', c'''; c_1, c_2, c_1, c_1; x^2, w_1xy, w_1z, w_2uz) \right] \\
&= \frac{\Gamma(a_1)\Gamma(a_2)\Gamma(a_3)\Gamma(a_4)}{\Gamma(c)\Gamma(c')\Gamma(c'')\Gamma(c''')} x^{c-1} w_1^{c'-1} z^{c''-1} w_2^{c'''-1} \times X_{89}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_1; x^2, w_1xy, w_1z, w_2uz).
\end{aligned} \tag{25}$$

Theorem 12. *The following derivative formulas hold true:*

$$\begin{aligned}
D_z^{a_2-c'} D_u^{a_3-c''} &\left[z^{a_2-1} u^{a_3-1} X_{90}^{(4)}(a_1, a_1, c', c'', a_1, c', c'', a_4; c, c, c, c; x, yz, uz, u) \right] \\
&= \frac{\Gamma(a_2)\Gamma(a_3)}{\Gamma(c)\Gamma(c')} z^{c'-1} u^{c''-1} X_{90}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c, c, c, c; x, yz, uz, u), \\
D_y^{a_2-c'} D_w^{a_3-c''} D_u^{a_4-c'''} &\left[y^{a_2-1} w^{a_3-1} u^{a_4-1} X_{90}^{(4)}(a_1, a_1, c', c'', a_1, c', c'', c'''; c, c, c, c; x, y, wyz, wu) \right] \\
&= \frac{\Gamma(a_2)\Gamma(a_3)\Gamma(a_4)}{\Gamma(c')\Gamma(c'')\Gamma(c''')} y^{c'-1} w^{c''-1} u^{c'''-1} X_{90}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c, c, c, c; x, y, wyz, wu),
\end{aligned} \tag{26}$$

$$\begin{aligned}
D_{w_1}^{a_1-c'} D_z^{a_3-c''} D_{w_2}^{a_4-c'''} &\left[w_1^{a_1-1} z^{a_3-1} w_2^{a_4-1} X_{90}^{(4)}(c', c', a_2, c'', c', a_2, c'', c'''; c, c, c, c; w_1^2x, w_1y, z, w_2uz) \right] \\
&= \frac{\Gamma(a_1)\Gamma(a_3)\Gamma(a_4)}{\Gamma(c')\Gamma(c'')\Gamma(c''')} w_2^{c-1} z^{c''-1} w_2^{c'''-1} X_{90}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c, c, c, c; w_1^2x, w_1y, z, w_2uz).
\end{aligned}$$

4. Integral Representations

In this section, we give integral representations of Laplace type for our new hypergeometric functions of four variables.

Theorem 13. *Each of the following integral representations holds true:*

$$X_{85}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_3, c_1; x, y, z, u) = \frac{1}{\Gamma(a_1)\Gamma(a_3)} \int_0^\infty \int_0^\infty \times e^{-(s+t)} s^{a_1-1} t^{a_3-1} \Phi_3(a_4; c_1; tu, s^2x) \Psi_2(a_4; c_2, c_3; sy, tz) ds dt \quad (\text{Re}(a_1) > 0, \text{Re}(a_3) > 0), \tag{27}$$

$$\begin{aligned}
X_{86}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_2, c_1, c_3, c_1; x, y, z, u) &= \frac{1}{\Gamma(a_1)\Gamma(a_2)\Gamma(a_3)} \\
&\cdot \int_0^\infty \int_0^\infty \int_0^\infty \times e^{-(s+t+v)} s^{a_1-1} t^{a_2-1} v^{a_3-1} \Phi_3(a_4; c_1; vu, sty) {}_0F_1(-; c_2; s^2x) {}_0F_1(-; c_3; tvz) ds dt dv \\
&\cdot (\text{Re}(a_1) > 0, \text{Re}(a_2) > 0, \text{Re}(a_3) > 0),
\end{aligned} \tag{28}$$

$$\begin{aligned}
X_{87}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_2; x, y, z, u) &= \frac{1}{\Gamma(a_1)\Gamma(a_2)\Gamma(a_3)} \\
&\cdot \int_0^\infty \int_0^\infty \int_0^\infty \times e^{-(s+t+v)} s^{a_1-1} t^{a_2-1} v^{a_3-1} {}_0F_1(-; c_1; s^2x + tvz) \Phi_3(a_4; c_2; vu, sty) ds dt dv \\
&\cdot (\text{Re}(a_1) > 0, \text{Re}(a_2) > 0, \text{Re}(a_3) > 0),
\end{aligned} \tag{29}$$

$$\begin{aligned} X_{88}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_3, c_1; x, y, z, u) &= \frac{1}{\Gamma(a_1)\Gamma(a_3)} \\ &\cdot \int_0^\infty \int_0^\infty \times e^{-(s+t)} s^{a_1-1} t^{a_3-1} \Phi_3(a_4; c_1; tu, s^2x) {}_1F_1(a_2; c_2; sy + tz) ds dt (\operatorname{Re}(a_1) > 0, \operatorname{Re}(a_3) > 0), \end{aligned} \quad (30)$$

$$\begin{aligned} X_{89}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_3, c_1; x, y, z, u) &= \frac{1}{\Gamma(a_1)\Gamma(a_2)\Gamma(a_4)} \\ &\cdot \int_0^\infty \int_0^\infty \int_0^\infty \times e^{-(s+t+v)} s^{a_1-1} t^{a_2-1} v^{a_4-1} \Phi_3(a_3; c_1; tz + vu, s^2x) {}_0F_1(-; c_2; sty) ds dt dv (\operatorname{Re}(a_1) > 0, \operatorname{Re}(a_2) > 0, \operatorname{Re}(a_4) > 0), \end{aligned} \quad (31)$$

$$\begin{aligned} X_{90}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c, c, c, c; x, y, z, u) &= \frac{1}{\Gamma(a_1)\Gamma(a_3)} \\ &\cdot \int_0^\infty \int_0^\infty \times e^{-(s+t)} s^{a_1-1} t^{a_3-1} \Phi_3^{(3)}(a_2, a_4; c; sy + tz, tu, s^2x) ds dt (\operatorname{Re}(a_1) > 0, \operatorname{Re}(a_3) > 0), \end{aligned} \quad (32)$$

where ${}_0F_1$, ${}_1F_1$, Ψ_2 , Φ_3 , and $\Phi_3^{(3)}$ are the confluent hypergeometric functions defined by (see [11])

$$\begin{aligned} {}_0F_1(-; c; x) &= \sum_{m=0}^{\infty} \frac{1}{(c)_m} \frac{x^m}{m!}, \\ {}_1F_1(a; c; x) &= \sum_{m=0}^{\infty} \frac{(a)_m}{(c)_m} \frac{x^m}{m!}, \\ \Psi_2(a; b, c; x, y) &= \sum_{m=0}^{\infty} \frac{(a)_{m+n}}{(b)_m (c)_n} \frac{x^m}{m!} \frac{y^n}{n!}, \\ \Phi_3(a; c; x, y) &= \sum_{m,n=0}^{\infty} \frac{(a)_m}{(c)_{m+n}} \frac{x^m}{m!} \frac{y^n}{n!}, \\ \Phi_3^{(3)}(a, b; c; x, y, z) &= \sum_{m,n,p=0}^{\infty} \frac{(a)_m (b)_n}{(c)_{m+n+p}} \frac{x^m}{m!} \frac{y^n}{n!} \frac{z^p}{p!}. \end{aligned} \quad (33)$$

Proof. It is noted that each of the integral representations (27) to (32) can be proved mainly by expressing the series definition of the involved special functions in each integrand, changing the order of the integral sign and the summation, and finally using the following well-known integral formula [12, 17]:

$$\Gamma(z) = \int_0^\infty e^{-t} t^{z-1} dt, \quad (\Re(z) > 0). \quad (34)$$

5. Operator Formulas

Here, we establish some operator identities for functions $X_{85}^{(4)}, X_{86}^{(4)}, \dots, X_{90}^{(4)}$. We begin by recalling the following reciprocally inverse operators (see [3, 18]):

$$\begin{aligned} H_{t_1, \dots, t_i}(a, b) &:= \frac{\Gamma(b)\Gamma(a + \delta_1 + \dots + \delta_i)}{\Gamma(a)\Gamma(b + \delta_1 + \dots + \delta_i)} \\ &= \sum_{k_1, \dots, k_i=0}^{\infty} \frac{(b-a)_{k_1+\dots+k_i} (-\delta_1)_{k_1} \dots (-\delta_i)_{k_i}}{(b)_{k_1+\dots+k_i} k_1! \dots k_i!}, \\ \overline{H}_{t_1, \dots, t_i}(a, b) &:= \frac{\Gamma(a)\Gamma(a + \delta_1 + \dots + \delta_i)}{\Gamma(b)\Gamma(a + \delta_1 + \dots + \delta_i)} \\ &= \sum_{k_1, \dots, k_i=0}^{\infty} \frac{(b-a)_{k_1+\dots+k_i} (-\delta_1)_{k_1} \dots (-\delta_i)_{k_i}}{(1-a-\delta_1-\dots-\delta_i)_{k_1+\dots+k_i} k_1! \dots k_i!}, \end{aligned} \quad (35)$$

where $\delta_j := t_j (\partial/\partial t_j)$, $j = 1, \dots, i$; $i \in \mathbb{N} := \{1, 2, 3, \dots\}$.

Theorem 14. *The following identities hold true:*

$$X_{85}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_3, c_1; x, y, z, u) = H_{y,z}(a_2, a) X_{85}^{(4)}(a_1, a_1, a, a_3, a_1, a, a_3, a_4; c_1, c_2, c_3, c_1; x, y, z, u), \quad (36)$$

$$X_{85}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_3, c_1; x, y, z, u) = H_z(c, c_3) X_{85}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c, c_1; x, y, z, u). \quad (37)$$

Theorem 15. *The following identities hold true:*

$$X_{86}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_2, c_1, c_3, c_1; x, y, z, u) = \overline{H}_{z,u}(a, a_3) X_{86}^{(4)}(a_1, a_1, a_2, a, a_1, a_2, a, a_4; c_2, c_1, c_3, c_1; x, y, z, u), \quad (38)$$

$$X_{86}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_2, c_1, c_3, c_1; x, y, z, u) = \overline{H}_x(c_2, c) X_{86}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c, c_1, c_3, c_1; x, y, z, u). \quad (39)$$

Theorem 16. *The following identities hold true:*

$$X_{87}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_2; x, y, z, u) = H_u(a_4, a) X_{87}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a; c_1, c_2, c_1, c_2; x, y, z, u), \quad (40)$$

$$X_{87}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_2; x, y, z, u) = H_{x,z}(c, c_1) H_{y,u}(c', c_2) X_{87}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c, c', c, c'; x, y, z, u). \quad (41)$$

Theorem 17. *The following identities hold true:*

$$X_{88}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_2, c_1; x, y, z, u) = \overline{H}_{y,z}(a, a_2) \overline{H}_u(a', a_4) X_{88}^{(4)}(a_1, a_1, a, a_3, a_1, a, a_3, a'; c_1, c_2, c_2, c_1; x, y, z, u), \quad (42)$$

$$X_{88}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_2, c_1; x, y, z, u) = H_{x,u}(c, c_1) X_{88}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c, c_2, c_2, c; x, y, z, u). \quad (43)$$

Theorem 18. *The following identities hold true:*

$$X_{89}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_1; x, y, z, u) = H_{x,z,u}(c, c_1) X_{89}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c, c_2, c, c; x, y, z, u), \quad (44)$$

$$X_{89}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c_1, c_2, c_1, c_1; x, y, z, u) = \overline{H}_{x,z,u}(c_1, c) X_{89}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c, c_2, c, c; x, y, z, u). \quad (45)$$

Theorem 19. *The following identities hold true:*

$$X_{90}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c, c, c, c; x, y, z, u) = \overline{H}_u(a, a_4) X_{90}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a; c, c, c, c; x, y, z, u), \quad (46)$$

$$X_{90}^{(4)}(a_1, a_1, a_2, a_3, a_1, a_2, a_3, a_4; c, c, c, c; x, y, z, u) = H_{z,u}(a_3, a) X_{90}^{(4)}(a_1, a_1, a_2, a, a_1, a_2, a, a_4; c, c, c, c; x, y, z, u). \quad (47)$$

Proof. Relations (37) to (47) can be proved by means of Mellin and Mellin–Barnes integral representation methods for hypergeometric functions (see [19]). The details of proofs are omitted. \square

Data Availability

The data used to support the findings of this study are available from the corresponding author upon request.

Conflicts of Interest

The authors declare that they have no conflicts of interest.

Authors' Contributions

All authors contributed equally and significantly to writing this article. All authors read and approved the final manuscript.

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