

## Research Article

# Common Fixed Point Results via Set-Valued Generalized Weak Contraction with Directed Graph and Its Application

Muhammad Shoaib,<sup>1</sup> Muhammad Sarwar ,<sup>1</sup> Kamal Shah ,<sup>1,2</sup> and Nabil Mlaiki<sup>2</sup>

<sup>1</sup>Department of Mathematics, University of Malakand, Chakdara Dir(L), Pakistan

<sup>2</sup>Department of Mathematics and Sciences, Prince Sultan University, Riyadh 11586, Saudi Arabia

Correspondence should be addressed to Muhammad Sarwar; sarwarswati@gmail.com

Received 22 February 2022; Accepted 4 April 2022; Published 9 May 2022

Academic Editor: A. Ghareeb

Copyright © 2022 Muhammad Shoaib et al. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

In this manuscript, common fixed point results for set-valued mapping under generalized  $(\psi, \phi)_1$  and  $(\psi, \phi)_2$  weak contraction without using Hausdorff metric are studied endowing with a graph. To demonstrate the authenticity of the established result, a suitable example and application to integral inclusion are also discussed.

## 1. Introduction

The basic fixed point (F.P) result of Banach [1] has set the basis of metric fixed point theory (FPT) in a complete metric space for contraction mappings. Due to their results, FPT of specific single-valued mappings is interesting in its benefit owning constructive proofs and applications in industrial fields such as physics, computer science, engineering, image processing, telecommunication, and economics.

The theory of set-valued mapping has applications in convex optimization, control theory, economics and differential inclusions, and integral inclusion. Differential inclusions are also used to analyze modeling errors and analyze robustness to bounded perturbations to model physical phenomena such as to model differential games and Coulomb friction and impact [2, 3]. Following the Banach contraction principle (BCP), Nadler [4] presented the idea of set-valued contractions and established that in complete metric space, a set-valued contraction possesses a F.P. Consequently, many authors generalized Nadler F.P theorem in various ways.

Connecting FPT and graph theory, Echenique [5] provided a proof of Tarski fixed point result by using graphs. Espinola and Kirk [6] in 2006 applied fixed point results in graph theory. Recently, two fundamental results have

appeared for FPT with a graph. The first result was given by Jachymski [7] for single-valued mappings and consequently Beg et al. [8] continued Jachymski result for set-valued mappings. Subsequently, Beg et al. [8] extended some results in [9] for set-valued mappings. Recently, Bojor [10] succeeded Jachymski idea for Kannan contractions applying a new postulate called the weak T-connectivity of the graph. Fallahi and Aghanians formulated Chatterjea contractions using graphs in metric spaces endowed with a graph and investigated the existence of F.Ps. Kutbi and Sintunavarat established F.P analysis for set-valued  $\phi$  with graph approach by the generalized Hausdorff distance. Abbas and Nazir [11] got few results for pair of power graphic contraction on a metric space along with a graph. On metric space along with a graph, Abbas et al. [12] established the presence of common F.Ps of set-valued F- contraction mappings. For more details, see [13, 14].

Let  $Q \neq \emptyset$ ,  $\Delta$  represent the diagonal of  $Q \times Q$  and  $\mathbf{G} = (\mathbf{v}(\mathbf{G}), \mathbf{e}(\mathbf{G}))$  be a directed graph (with no parallel edges). The set  $\mathbf{v}(\mathbf{G})$  denoted vertices coincides with  $Q$ , and the set  $\mathbf{e}(\mathbf{G})$  is the edges of the graph furthermore  $\Delta \subseteq \mathbf{e}(\mathbf{G})$ .  $\mathbf{e}^*(\mathbf{G})$  denotes the set all edges which is not loops, i.e.,  $\mathbf{e}^*(\mathbf{G}) = \mathbf{e}(\mathbf{G}) - \Delta$ . If path exist between any two vertices, then a graph  $\mathbf{G}$  is connected. It is weakly connected if  $\tilde{\mathbf{G}}$  is connected; here,  $\tilde{\mathbf{G}}$  is an undirected form of the graph  $\mathbf{G}$ .

A clique,  $C$ , in an undirected graph  $\mathbf{G} = (\mathbf{v}(\mathbf{G}), \mathbf{e}(\mathbf{G}))$  is a subset of the vertices,  $C \subseteq \mathbf{v}(\mathbf{G})$ , such that every two distinct vertices are adjacent. This is equivalent to the condition that the induced subgraph of  $\mathbf{G}$  induced by  $C$  is a complete graph.

Jachymski and Jozwik [15] used the property (P) stated that for any sequence  $\{\vartheta_n\}$  in  $Q$ ; if  $\vartheta_n \rightarrow \vartheta$  and  $(\vartheta_n, \vartheta_{n+1}) \in \mathbf{e}(\mathbf{G})$ , then  $(\vartheta_n, \vartheta) \in \mathbf{e}(\mathbf{G})$ .

A mapping  $T: Q \rightarrow CL(Q)$  is said to be upper semi-continuous if for  $\vartheta_n \in Q$  and  $\eta_n \in T\vartheta_n$  with  $\vartheta_n \rightarrow \vartheta_0$  and  $\eta_n \rightarrow \eta_0$  implies  $\eta_0 \in T\vartheta_0$ .

Assume  $T_1, T_2: Q \rightarrow CL(Q)$ . Set

$$Q_{\{T_1, T_2\}} = \{r \in Q: (r, \vartheta_r) \in \mathbf{e}(\mathbf{G}) \text{ where } \vartheta_r \in T_1(r) \cap T_2(r)\}. \tag{1}$$

*Definition 1.* Consider a metric space  $(Q, d)$ ,  $\mathbf{G} = (\mathbf{v}(\mathbf{G}), \mathbf{e}(\mathbf{G}))$  be a graph such that  $\mathbf{v}(\mathbf{G}) = Q$ , and let  $T: Q \rightarrow CL(Q)$ . If  $(m_1, n_1) \in \mathbf{e}(\mathbf{G})$ ,  $(u_1, v_1) \in \mathbf{e}(\mathbf{G})$  for all  $u_1 \in Tm_1$  and  $v_1 \in Tn_1$ , then  $T$  is said to be graph-preserving.

Motivated from above in the present work, we give common F.P results for generalized  $(\psi, \phi)_1$  and  $(\psi, \phi)_2$  weak contraction, in metric spaces (endowed with a graph). To demonstrate the authenticity of our result, we give suitable example. Also, we discuss application to integral inclusion.

## 2. Fixed Point Results

In our main work, we used the following three classes:

$$\begin{aligned} \Psi &= \left\{ \begin{array}{l} \psi: \mathbb{R}^+ \rightarrow \mathbb{R}^+ \text{ is non-decreasing, continuous mapping such that} \\ \psi(\zeta) = 0 \text{ if and only if } \zeta = 0 \end{array} \right\}, \\ \Phi &= \left\{ \phi: \mathbb{R}^+ \rightarrow \mathbb{R}^+ \text{ non-decreasing } \lim_{n \rightarrow \infty} \phi(\zeta_n) = 0 \Rightarrow \lim_{n \rightarrow \infty} \zeta_n = 0 \right\}, \\ \Psi_1 &= \left\{ \begin{array}{l} \psi_1: \mathbb{R}^5 \rightarrow \mathbb{R}^+ \\ \text{(i) } \psi_1 \text{ is continuous and non-decreasing in each coordinate} \\ \text{(ii) } \psi_1(\zeta_1, \zeta_2, \zeta_3, \zeta_4, \zeta_5) = 0 \text{ implies } \zeta_1 = \zeta_2 = \zeta_3 = \zeta_4 = \zeta_5 = 0 \text{ and} \\ \psi_1(\zeta, \zeta, \zeta, \zeta, \zeta) \leq \zeta \text{ for } \zeta > 0 \end{array} \right\}. \end{aligned} \tag{2}$$

*Definition 2.* Consider a complete  $(Q, d)$  metric space. Assume  $T_1, T_2: Q \rightarrow CL(Q)$  be two set valued mapping. Assume that for each vertex  $r$  in  $\mathbf{G}$  and for each  $\vartheta_r \in T_i(r), i = 1, 2$ , we have  $(r, \vartheta_r) \in \mathbf{e}(\mathbf{G})$ . A pair  $(T_1, T_2)$  is said to be

- (i) A graphic  $(\psi, \phi)_1$  contraction if for any  $r, t \in Q$  with  $(r, t) \in \mathbf{e}(\mathbf{G})$  and  $\vartheta_r \in T_i(r)$ , there exists  $\vartheta_t \in T_j(t)$  for  $i \neq j$  and  $i, j = 1, 2$  and  $(\vartheta_r, \vartheta_t) \in \mathbf{e}^*(\mathbf{G})$  and

$$\psi(d(\vartheta_r, \vartheta_t)) \leq \psi(\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)) - \phi(\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)), \tag{3}$$

hold where  $\psi \in \Psi, \phi \in \Phi$  and  $\psi_1 \in \Psi_1$  and

$$\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t) = \psi_1\left(d(r, t), d(r, \vartheta_r), d(t, \vartheta_t), \frac{d(r, \vartheta_t) + d(t, \vartheta_r)}{2}, \frac{d(t, \vartheta_r) + d(r, \vartheta_t)}{2}\right), \tag{4}$$

$\forall r, t \in Q$ .

- (ii) A graphic  $(\psi, \phi)_2$  contraction if any  $r, t \in Q$  with  $(r, t) \in \mathbf{e}(\mathbf{G})$  and  $\vartheta_r \in T_i(r)$ , there exists  $\vartheta_t \in T_j(t)$  for  $i, j = 1, 2, i \neq j$ ; furthermore,  $(\vartheta_r, \vartheta_t) \in \mathbf{e}^*(\mathbf{G})$  and

$$\psi(d(Tr, Tt)) \leq \psi(\Lambda_{\psi_2}(r, t; \vartheta_r, \vartheta_t)) - \phi(\Lambda_{\psi_2}(r, t; \vartheta_r, \vartheta_t)), \tag{5}$$

hold where  $\psi \in \Psi, \phi \in \Phi$ , and  $\psi_2 \in \Psi_1$  and

$$\Lambda_{\psi_2}(r, t; \vartheta_r, \vartheta_t) = \psi_1\left(\alpha d(r, t) + \beta d(r, \vartheta_r) + \gamma d(t, \vartheta_t) + \sigma_1 \frac{d(r, \vartheta_t) + d(t, \vartheta_r)}{2} + \sigma_2 \frac{d(t, \vartheta_r) + d(r, \vartheta_t)}{2}\right). \tag{6}$$

$\forall r, t \in Q$  and  $\alpha, \beta, \gamma, \sigma_1, \sigma_2 \geq 0$  with  $\alpha + \beta + \gamma + \sigma_1 + \sigma_2 + \sigma_3 \leq 1$ .

**Theorem 1.** Consider a complete  $(Q, d)$  metric space endowed with a directed graph  $\mathbf{G}$  such that  $\mathbf{v}(\mathbf{G}) = Q$  and

$\mathbf{e}(\mathbf{G}) \supseteq \Delta$ . If mapping  $T_1, T_2: Q \rightarrow CL(Q)$  form a graphic  $(\psi, \phi)_1$  contraction, then the following statement holds:

- (i)  $F_x(T_1) \neq \emptyset$  or  $F_x(T_2) \neq \emptyset \Leftrightarrow F_x(T_1) = F_x(T_2) \neq \emptyset$
- (ii)  $Q_{\{T_1, T_2\}} \neq \emptyset$  provided that  $F_x(T_1) \cap F_x(T_2) \neq \emptyset$
- (iii) If  $\mathbf{G}$  is weakly connected and  $Q_{\{T_1, T_2\}} \neq \emptyset$ , then  $F_x(T_1) = F_x(T_2) \neq \emptyset$  provided that either
  - (a)  $T_1$  or  $T_2$  is upper semicontinuous or
  - (b)  $\mathbf{G}$  has property (P) and either  $T_1$  or  $T_2$  is bounded

(iv)  $F_x(T_1) \cap F_x(T_2)$  is a clique of  $\tilde{\mathbf{G}} \Leftrightarrow F_x(T_1) \cap F_x(T_2)$  which is singleton.

*Proof.* To prove (i), let  $r^* \in T_1(r^*)$ . Assume  $r^* \notin T_2(r^*)$ , then since  $(T_1, T_2)$  form a graphic  $(\psi, \phi)_1$  contraction, there exists an  $r \in T_2(r)$  with  $(r^*, r) \in \mathbf{e}^*(\mathbf{G})$  such that

$$\psi(d(r^*, r)) \leq \psi(\Lambda_{\psi_1}(r^*, r^*; r^*, r)) - \phi(\Lambda_{\psi_1}(r^*, r^*; r^*, r)), \tag{7}$$

where

$$\begin{aligned} \Lambda_{\psi_1}(r^*, r^*; r^*, r) &= \psi_1\left(d(r^*, r^*), d(r^*, r^*), d(r^*, r), \frac{d(r, r^*) + d(r^*, r^*)}{2}, \frac{d(r^*, r^*) + d(r^*, r)}{2}\right) \\ &\leq \psi_1(d(r^*, r^*), d(r^*, r^*), d(r^*, r), d(r^*, r), d(r^*, r)). \end{aligned} \tag{8}$$

Using property (i) of  $\psi_1$ , we have

$$\Lambda_{\psi_1}(r^*, r^*; r^*, r) \leq d(r^*, r^*), \tag{9}$$

which is contradiction. Hence,  $r^* \in T(r^*)$  and so  $F_x(T_1) \subseteq F_x(T_2)$ . Similarly,  $F_x(T_2) \subseteq F_x(T_1)$ ; therefore,  $F_x(T_1) = F_x(T_2)$ .

To prove (ii), let  $F_x(T_1) \cap F_x(T_2) \neq \emptyset$ , then there exists  $r \in Q$  such that  $r \in T_1(r) \cap T_2(r)$ . As  $\mathbf{e}(\mathbf{G}) \supseteq \Delta$ , we conclude that  $Q_{T_1, T_2} \neq \emptyset$ .

To prove (iii), let  $r_0$  is an arbitrary point of  $Q$ . If  $r_0 \in T_1(r_0)$  or  $r_0 \in T_2(r_0)$ , then the proof is completed. So, we assume that  $r_0 \notin T_i(r_0)$  for  $i \in \{1, 2\}$ . Now, for  $i, j \in \{1, 2\}, i \neq j$  if  $r_1 \in T_i(r_0)$ , then there exists  $r_2 \in T_j(r_1)$  with  $(r_1, r_2) \in \mathbf{e}^*(\mathbf{G})$  such that

$$\psi(d(r_1, r_2)) \leq \psi(\Lambda_{\psi_1}(r_0, r_1; r_1, r_2)) - \phi(\Lambda_{\psi_1}(r_0, r_1; r_1, r_2)), \tag{10}$$

where,

$$\begin{aligned} \Lambda_{\psi_1}(r_0, r_1; r_1, r_2) &= \psi_1\left(d(r_0, r_1), d(r_0, r_1), d(r_1, r_2), \frac{d(r_0, r_2) + d(r_1, r_1)}{2}, \frac{d(r_1, r_1) + d(r_0, r_2)}{2}\right), \\ \Lambda_{\psi_1}(r_0, r_1; r_1, r_2) &= \psi_1\left(d(r_0, r_1), d(r_0, r_1), d(r_1, r_2), \frac{d(r_0, r_2) + d(r_1, r_1)}{2}, \frac{d(r_0, r_2)}{2}\right). \end{aligned} \tag{11}$$

If  $d(r_0, r_1) \leq d(r_1, r_2)$ , then by simple calculation, we get

$$\begin{aligned} \Lambda_{\psi_1}(r_0, r_1; r_1, r_2) &\leq d(r_1, r_2), \\ \psi(d(r_1, r_2)) &\leq \psi(d(r_1, r_2)) - \phi(d(r_1, r_2)), \end{aligned} \tag{12}$$

which gives contradiction; therefore,

$$\Lambda_{\psi_1}(r_0, r_1; r_1, r_2) = d(r_0, r_1), \tag{13}$$

and further we have

$$\psi(d(r_1, r_2)) \leq \psi(d(r_0, r_1)) - \phi(d(r_0, r_1)). \tag{14}$$

Similarly, for the point  $r_2 \in T_j(r_1)$ , there exists  $r_3 \in T_i(r_1)$  with  $(r_2, r_3) \in \mathbf{e}^*(\mathbf{G})$  such that

$$\psi(d(r_2, r_3)) \leq \psi(\Lambda_{\psi_1}(r_1, r_2; r_2, r_3)) - \phi(\Lambda_{\psi_1}(r_1, r_2; r_2, r_3)), \tag{15}$$

where

$$\begin{aligned} \Lambda_{\psi_1}(r_1, r_2; r_2, r_3) &= \psi_1\left(d(r_1, r_2), ((r_1, r_2), d(r_2, r_3), \frac{d(r_1, r_3) + d(r_2, r_2)}{2}, \frac{d(r_2, r_2) + d(r_1, r_3)}{2})\right), \\ \Lambda_{\psi_1}(r_1, r_2; r_2, r_3) &= \psi_1\left(d(r_1, r_2), ((r_1, r_2), d(r_2, r_3), \frac{d(r_1, r_3)}{2}, \frac{d(r_1, r_3)}{1 + d(r_1, r_2)})\right). \end{aligned} \tag{16}$$

If  $d(r_1, r_2) \leq d(r_2, r_3)$ , then

$$\Lambda_{\psi_1}(r_1, r_2; r_2, r_3) \leq d(r_2, r_3), \quad (17)$$

and then

$$\psi(d(r_2, r_3)) \leq \psi(d(r_2, r_3)) - \phi(d(r_2, r_3)), \quad (18)$$

which gives contradiction; therefore

$$\begin{aligned} \Lambda_{\psi_1}(r_1, r_2; r_2, r_3) &= d(r_1, r_2), \\ \psi(d(r_2, r_3)) &\leq \psi(d(r_1, r_2)) - \phi(d(r_1, r_2)). \end{aligned} \quad (19)$$

Continuing this way, for  $r_{2\gamma} \in T_j(r_{2\gamma-1})$ , there exist  $r_{2\gamma+1} \in T_j(r_{2\gamma})$  such that  $(r_{2\gamma}, r_{2\gamma+1}) \in \mathbf{e}^*(\mathbf{G})$  such that

$$\begin{aligned} \psi(d(r_{2\gamma}, r_{2\gamma+1})) &\leq \psi(\Lambda_{\psi_1}(r_{2\gamma-1}, r_{2\gamma}; r_{2\gamma}, r_{2\gamma+1})) \\ &\quad - \phi(\Lambda_{\psi_1}(r_{2\gamma-1}, r_{2\gamma}; r_{2\gamma}, r_{2\gamma+1})), \end{aligned} \quad (20)$$

where

$$\Lambda_{\psi_1}(r_{2\gamma-1}, r_{2\gamma}; r_{2\gamma}, r_{2\gamma+1}) \leq d(r_{2\gamma-1}, r_{2\gamma}). \quad (21)$$

Therefore,

$$\psi(d(r_{2\gamma}, r_{2\gamma+1})) \leq \psi(d(r_{2\gamma-1}, r_{2\gamma})) - \phi(d(r_{2\gamma-1}, r_{2\gamma})). \quad (22)$$

In similar pattern  $r$  for  $r_{2\gamma+1} \in T_j(r_{2\gamma})$ , there exist  $r_{2\gamma+2} \in T_j(r_{2\gamma+1})$  such that  $(r_{2\gamma+1}, r_{2\gamma+2}) \in \mathbf{e}^*(\mathbf{G})$  such that

$$\begin{aligned} \psi(d(r_{2\gamma+1}, r_{2\gamma+2})) &\leq \psi(\Lambda_{\psi_1}(r_{2\gamma}, r_{2\gamma+1}; r_{2\gamma+1}, r_{2\gamma+2})) \\ &\quad - \phi(\Lambda_{\psi_1}(r_{2\gamma}, r_{2\gamma+1}; r_{2\gamma+1}, r_{2\gamma+2})), \end{aligned} \quad (23)$$

where

$$\Lambda_{\psi_1}(r_{2\gamma}, r_{2\gamma+1}; r_{2\gamma+1}, r_{2\gamma+2}) \leq d(r_{2\gamma-1}, r_{2\gamma}). \quad (24)$$

Therefore,

$$\psi(d(r_{2\gamma}, r_{2\gamma+1})) \leq \psi(d(r_{2\gamma-1}, r_{2\gamma})) - \phi(d(r_{2\gamma-1}, r_{2\gamma})). \quad (25)$$

Hence, we obtain a sequence  $\{r_\gamma\}$  in  $Q$  such that for  $r_\gamma \in T_j(r_{\gamma-1})$ , there exist  $r_{\gamma+1} \in T_j(r_\gamma)$  such that  $(r_\gamma, r_{\gamma+1}) \in \mathbf{e}^*(\mathbf{G})$ , and

$$\psi(d(r_\gamma, r_{\gamma+1})) \leq \psi(d(r_{\gamma-1}, r_\gamma)) - \phi(d(r_{\gamma-1}, r_\gamma)). \quad (26)$$

Let  $d_\gamma = d(r_\gamma, r_{\gamma+1})$ , then the above equation implies that  $d_{\gamma+1} \leq d_\gamma$  for all  $\gamma \geq 1$ . Since  $\{d_\gamma\}$  is a decreasing positive real sequence, there exists  $\xi \geq 0$ , such that

$$\lim_{\gamma \rightarrow \infty} d_\gamma = \xi. \quad (27)$$

We shall show that  $\xi = 0$ ; by applying limit, we have

$$\psi(\xi) \leq \psi(\xi) - \phi(\xi) < \psi(\xi), \quad (28)$$

which is a contradiction; therefore,  $\xi = 0$  which implies that

$$\lim_{\gamma \rightarrow \infty} d_\gamma = 0. \quad (29)$$

Now, we want show that  $\{r_\gamma\}$  is Cauchy. Suppose that  $\{r_\gamma\}$  is not Cauchy. Then, there exist  $\epsilon > 0$  and subsequences  $\{r_{\gamma(\kappa)}\}$  and  $\{r_{\delta(\kappa)}\}$  of  $\{r_\gamma\}$  with  $\gamma(\kappa) > \delta(\kappa) > \kappa$  such that

$$d(r_{\delta(\kappa)}, r_{\gamma(\kappa)}) \geq \epsilon, \quad \forall \kappa \in \mathbb{N}. \quad (30)$$

Moreover, one can choose  $\gamma(\kappa)$  corresponding to  $\delta(\kappa)$  such that it is the smallest possible integer with  $\gamma(\kappa) > \delta(\kappa)$  holding (30); then,

$$d(r_{\delta(\kappa)}, r_{\gamma(\kappa)-1}) < \epsilon, \quad \forall \kappa \in \mathbb{N}, \quad (31)$$

$$\begin{aligned} \psi(d(r_{\delta(\kappa)}, r_{\gamma(\kappa)})) &\leq \psi(\Lambda_{\psi_1}(r_{\gamma(\kappa)-1}, r_{\delta(\kappa)}; r_{\delta(\kappa)}, r_{\gamma(\kappa)})) - \phi(\Lambda_{\psi_1}(r_{\gamma(\kappa)-1}, r_{\delta(\kappa)}; r_{\delta(\kappa)}, r_{\gamma(\kappa)})), \\ \Lambda_{\psi_1}(r_{\gamma(\kappa)-1}, r_{\delta(\kappa)}; r_{\delta(\kappa)}, r_{\gamma(\kappa)}) &= \psi_1(d(r_{\gamma(\kappa)-1}, r_{\delta(\kappa)}), d(r_{\gamma(\kappa)-1}, r_{\delta(\kappa)}), d(r_{\delta(\kappa)}, r_{\gamma(\kappa)})) \\ &\quad \cdot \frac{d(r_{\gamma(\kappa)-1}, r_{\gamma(\kappa)}) + d(r_{\delta(\kappa)}, r_{\delta(\kappa)})}{2}, \frac{d(r_{\delta(\kappa)}, r_{\delta(\kappa)}) + d(r_{\gamma(\kappa)-1}, r_{\gamma(\kappa)})}{2}. \end{aligned} \quad (32)$$

Applying limit  $\kappa \rightarrow \infty$ , we get

$$\lim_{\kappa \rightarrow \infty} \Lambda_{\psi_1}(r_{\gamma(\kappa)-1}, r_{\delta(\kappa)}; r_{\delta(\kappa)}, r_{\gamma(\kappa)}) \leq \epsilon. \quad (33)$$

Taking limit of (32) using (33), (29), and lower semicontinuity of  $\phi$ , we have

$$\psi(\epsilon) \leq \psi(\epsilon) - \phi(\epsilon) < \psi(\epsilon), \quad (34)$$

which is contradiction; therefore,  $r_\gamma$  is a Cauchy sequence. Now, if  $T_i$  is upper semicontinuous (USC), then as  $r_{2\gamma} \in Q$ ,

$r_{2\gamma+1} \in T_i(r_{2\gamma})$  with  $s_{2\gamma} \rightarrow r^*$  and  $r_{2\gamma+1} \rightarrow r^*$  as  $\gamma \rightarrow \infty$  which implies that  $r^* \in T_i(r^*)$ . Using (i), we get  $r^* \in T_i(r^*) = T_j(r^*)$ . Similarly, the result holds when  $T_j$  is upper semicontinuous (USC).

Assume that  $F$  is continuous. Since  $s_{2\gamma}$  converges to  $r^*$  as  $\gamma \rightarrow \infty$  and  $(r_{2\gamma}, r_{2\gamma+1}) \in \mathbf{e}(\mathbf{G})$ , we have  $(r_{2\gamma}, r^*) \in \mathbf{e}^*(\mathbf{G})$ . For  $r_{2\gamma} \in T_j(r_{2\gamma-1})$ , there exists  $\vartheta_\gamma \in T_i(r^*)$  such that  $(r_{2\gamma}, \vartheta_\gamma) \in \mathbf{e}^*(\mathbf{G})$ . As  $\{r_\gamma\}$  is bounded,  $\limsup_{\gamma \rightarrow \infty} \vartheta_\gamma = \vartheta^*$  and  $\liminf_{\gamma \rightarrow \infty} \vartheta_\gamma = \vartheta_*$  both exist. Assume that  $\vartheta^* \neq r^*$ . Since  $(T_1, T_2)$  form a graphic  $F_1$ -contraction,

$$\psi(d(r_{2n}, r_3)) \leq \psi(\Lambda_{\psi_1}(r_{2\gamma-1}, r^*; r_{2\gamma}, \vartheta_\gamma)) - \phi(\Lambda_{\psi_1}(r_{2\gamma-1}, r^*; r_{2\gamma}, \vartheta_\gamma)), \tag{35}$$

where

$$\Lambda_{\psi_1}(r_{2\gamma-1}, r^*; r_{2\gamma}, \vartheta_\gamma) = \psi_1 \left( d(r_{2\gamma-1}, r^*), d(r_{2\gamma-1}, r_{2\gamma}), d(r^*, \vartheta_\gamma), \frac{d(r_{2\gamma}, \vartheta_\gamma) + d(r_2, r_2)}{2}, \frac{d(r_2, r_2) + d(r_{2\gamma}, \vartheta_\gamma)}{2} \right). \tag{36}$$

By applying limit and after simple calculation, we get contradiction; hence,  $\vartheta^* = r^*$ . Similarly, taking the liminf gives  $\vartheta^* = r^*$ . Since  $\vartheta_\gamma \in T_i(r^*)$  for all  $\gamma \geq 1$  and  $T_i(r^*)$  is closed set, it follows that  $r^* \in T_i(r^*)$ . Now, from (i), we get  $r^* \in T_i(r^*)$  and hence  $F_x(T_1) = F_x(T_2)$ .

To prove (iv), assume the set  $F_x(T_1) \cap F_x(T_2)$  is a clique of  $\tilde{\mathbf{G}}$ . We have shown that  $F_x(T_1) \cap F_x(T_2)$  is singleton set. Assume on contrary that there exist  $\vartheta$  and  $\nu$  such that

$\vartheta, \nu \in F_x(T_1) \cap F_x(T_2)$  but  $\vartheta \neq \nu$ . As  $(\vartheta, \nu) \in \mathbf{e}^*(\mathbf{G})$  and  $T_1$  and  $T_2$  form a graphic  $F_1$ - contraction, so for  $(\vartheta_s, \vartheta_t) \in \mathbf{e}^*(\mathbf{G})$  which implies

$$\psi(d(\vartheta, \nu)) \leq \psi(\Lambda_{\psi_1}(\vartheta, \nu; \vartheta, \nu)) - \phi(\Lambda_{\psi_1}(\vartheta, \nu; \vartheta, \nu)), \tag{37}$$

where

$$\Lambda_{\psi_1}(\vartheta, \nu; \vartheta, \nu) = \psi_1 \left( d(\vartheta, \nu), d(\vartheta, \vartheta), d(\nu, \nu), \frac{d(r_{2\gamma}, \vartheta_\gamma) + d(r_2, r_2)}{2}, \frac{d(r_2, r_2) + d(r_{2\gamma}, \vartheta_\gamma)}{2} \right), \tag{38}$$

which is a contradiction. Hence,  $\vartheta = \nu$ . Conversely, if  $F_x(T_1) \cap F_x(T_2)$  is singleton, then it follows  $F_x(T_1) \cap F_x(T_2)$  is a clique of  $\tilde{\mathbf{G}}$ .

By the same technique, it is essay to prove the following result.  $\square$

**Theorem 2.** Consider a complete  $(Q, d)$  metric space endowed with a directed graph  $\mathbf{G}$  such that  $\mathbf{v}(\mathbf{G}) = Q$  and  $\mathbf{e}(\mathbf{G}) \supseteq \Delta$ . If mapping  $T_1, T_2: Q \rightarrow CL(Q)$  make a graphic  $(\psi, \phi)_2$  contraction, then the following statement holds:

- (i)  $F_x(T_1) \neq \emptyset$  or  $F_x(T_2) \neq \emptyset \Leftrightarrow F_x(T_1) = F_x(T_2) \neq \emptyset$ ;
- (ii)  $Q_{\{T_1, T_2\}} \neq \emptyset$  provided that  $F_x(T_1) \cap F_x(T_2) \neq \emptyset$ ;
- (iii)  $\mathbf{G}$  is weakly connected and  $Q_{\{T_1, T_2\}} \neq \emptyset$ , then  $F_x(T_1) = F_x(T_2) \neq \emptyset$  provided that either
  - (a)  $T_1$  or  $T_2$  is upper semicontinuous(USC) or
  - (b)  $\mathbf{G}$  has property (P) and either  $T_1$  or  $T_2$  is bounded;
- (iv)  $F_x(T_1) \cap F_x(T_2)$  is a clique of  $\tilde{\mathbf{G}} \Leftrightarrow F_x(T_1) \cap F_x(T_2)$  which is singleton.

Now, we give example which satisfying Theorem 1.

**Example 1.** Let  $Q = \{r_\gamma = (\gamma(\gamma + 1)/2): \gamma \in N\} = \mathbf{v}(\mathbf{G})$

$$\mathbf{e}(\mathbf{G}) = \left\{ \frac{(r, t)}{t} = 2r, \forall r, t \in \mathbf{v}(\mathbf{G}) \right\}, \tag{39}$$

$$\mathbf{e}^*(\mathbf{G}) = \left\{ \frac{(r, t)}{t} \neq 2r, \forall r, t \in \mathbf{v}(\mathbf{G}) \right\}.$$

Let  $\mathbf{v}(\mathbf{G})$  be endowed with usual metric space. Let  $T_1, T_2: Q \times Q \rightarrow P(Q)$ ,  $\phi: \mathbb{R}^+ \rightarrow \mathbb{R}^+$ , and  $\psi: \mathbb{R}^+ \rightarrow \mathbb{R}^+$  define by

$$T_1(r) = \{r_2\},$$

$$T_2(r) = \begin{cases} \{r_2\}, & \text{if } r = r_2, \\ \{r_1, r_\gamma\}, & \text{if } r = r_\gamma, \end{cases}$$

$$\phi(t) = \frac{t}{4} \tag{40}$$

$$\psi(t) = \frac{t}{2}$$

$$\psi_1(\varsigma_1, \varsigma_2, \varsigma_3, \varsigma_4, \varsigma_5) = \max\{\varsigma_1, \varsigma_2, \varsigma_3, \varsigma_4, \varsigma_5\}.$$

For  $(\vartheta_r, \vartheta_t) \in \mathbf{e}(\mathbf{G})$ , we discuss the following cases:

*Case 1.1.* If  $r = r_1, t = r_\delta$  for  $\delta > 2$ , then for  $\vartheta_r = r_2 \in T_1(r)$ , there exist  $\vartheta_t = r_{\delta-1} \in T_2(t)$  such that

$$\psi(d(\vartheta_r, \vartheta_t)) = \frac{d(\vartheta_r, \vartheta_t)}{2} = \frac{d(r_2, r_{\delta-1})}{2}$$

$$= \frac{\delta^2 - \delta - 2}{4} \leq \frac{\delta^2 + \delta - 2}{4}$$

$$\leq \frac{\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)}{2}$$

$$\leq \psi(\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)) - \phi(\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)). \tag{41}$$

Case 1.2. If  $r = r_\gamma$  and  $t = r_{\gamma+1}$  for  $\gamma > 1$ , then for  $\vartheta_r = r_2 \in T_1(r)$ , there exist  $\vartheta_t = r_{\gamma-1} \in T_2(t)$  such that

$$\begin{aligned} \psi(d(\vartheta_r, \vartheta_t)) &= \frac{d(\vartheta_r, \vartheta_t)}{2} = \frac{d(r_2, r_{\gamma-1})}{2} \\ &= \frac{\delta^2 - \delta - 2}{4} \leq \frac{\delta^2 + \delta - 2}{4} \\ &\leq \frac{\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)}{2} \\ &\leq \psi(\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)) - \phi(\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)). \end{aligned} \quad (42)$$

Case 1.3. If  $r = r_\gamma$  and  $t = r_\delta$  for  $\delta > \gamma > 1$ , then for  $\vartheta_r = r_2 \in T_1(r)$ , there exist  $\vartheta_t = r_{\gamma-1} \in T_2(t)$  such that

$$\begin{aligned} \psi(d(\vartheta_r, \vartheta_t)) &= \frac{d(\vartheta_r, \vartheta_t)}{2} = \frac{d(r_2, r_{\gamma-1})}{2} \\ &= \frac{\gamma^2 - \gamma - 2}{4} \leq \frac{\gamma^2 + \gamma - 2}{4} \\ &\leq \frac{\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)}{2} \\ &\leq \psi(\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)) - \phi(\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)). \end{aligned} \quad (43)$$

Now, for  $r, t \in Q, \vartheta_r \in T_2(r)$ , there exist  $\vartheta_t \in T_1(r)$  such that  $(\vartheta_r, \vartheta_t) \in \mathbf{e}^*(\mathbf{G})$ , we consider the following cases.

Case 1.4. If  $r = r_\gamma$  and  $t = r_1$  for  $\gamma > 1$ , then for  $\vartheta_r = r_{\gamma-1} \in T_2(r)$ , there exist  $\vartheta_t = r_2 \in T_1(t)$  such that

$$\begin{aligned} \psi(d(\vartheta_r, \vartheta_t)) &= \frac{d(\vartheta_r, \vartheta_t)}{2} = \frac{d(r_{\gamma-1}, r_2)}{2} \\ &= \frac{\gamma^2 - \gamma - 2}{4} \leq \frac{\gamma^2 + \gamma - 2}{4} \\ &\leq \frac{\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)}{2} \\ &\leq \psi(\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)) - \phi(\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)). \end{aligned} \quad (44)$$

Case 1.5. If  $r = r_\gamma$  and  $t = r_\delta$  for  $\delta > \gamma > 1$ , then for  $\vartheta_r = r_{\gamma-1} \in T_2(r)$ , there exist  $\vartheta_t = r_2 \in T_1(t)$  such that

$$\begin{aligned} \psi(d(\vartheta_r, \vartheta_t)) &= \frac{d(\vartheta_r, \vartheta_t)}{2} = \frac{d(r_{\gamma-1}, r_2)}{2} \\ &= \frac{\gamma^2 - \gamma - 2}{4} \leq \frac{\gamma^2 + \gamma - 2}{4} \\ &\leq \frac{\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)}{2} \\ &\leq \psi(\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)) - \phi(\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)). \end{aligned} \quad (45)$$

### 3. Application to Integral Inclusion

Set-valued (SV) F.P results are explored extensively and have interesting application in integral and differential inclusion [16–19]. In this section, we derive sufficient conditions for the solutions of Fredholm-type integral inclusion. Set of all continuous function defined on  $[\zeta, \xi]$  is denoted by  $W = C[\zeta, \xi]$ . Define  $d: W \times W \rightarrow \mathbf{R}^+$ , by  $d(r, t) = \sup_{t \in [\zeta, \xi]} |r - t|$ , which is a complete metric space on  $W$ . Assume that the metric is endowed with a graph  $\mathbf{G}$ . Consider the integral inclusion

$$r(\zeta) \in \phi(\zeta) + \int_{\zeta}^{\xi} K(\zeta, \eta, r(\eta))d\eta, \quad \zeta \in [\zeta, \xi], \quad (46)$$

where  $K: [\zeta, \xi] \times [\zeta, \xi] \times \mathbf{R} \rightarrow P_{cv}(\mathbf{R})$ , where  $P_{cv}(\mathbf{R})$  is the family (collection) of nonempty compact and convex subsets of  $\mathbf{R}$ . For each  $r \in C([\zeta, \xi], \mathbf{R})$ , the operator  $K(\cdot, \cdot, r)$  is lower semicontinuous. Further, the function  $\phi: [\zeta, \xi] \rightarrow \mathbf{R}$  is continuous.

Define  $T: C([\zeta, \xi], \mathbf{R}) \rightarrow CL(C[\zeta, \xi], \mathbf{R})$  by,

$$\text{Tr}(\zeta) = \left\{ \vartheta \in C([\zeta, \xi], \mathbf{R}): \vartheta \in \phi(\zeta) + \int_{\zeta}^{\xi} K(\zeta, \eta, r(\eta))d\eta \right\}, \quad (47)$$

$r \in C([\zeta, \xi], \mathbf{R})$ , and set  $K_r: K(\zeta, \eta, r(\eta)), \zeta, \eta \in [\zeta, \xi]$ . Now, for  $K: [\zeta, \xi] \times [\zeta, \xi] \times \mathbf{R} \rightarrow P_{cv}(\mathbf{R})$ , by Michael's selection theorem, there exist a continuous operator  $m_s: [\zeta, \xi] \times [\zeta, \xi] \rightarrow \mathbf{R}$  with  $m_r \in K_r$

$$\phi(\zeta) + \int_{\zeta}^{\xi} K(\zeta, \eta, r(\eta))d\eta \in \text{Tr}(\zeta). \quad (48)$$

This implies that  $\text{Tr} \neq \emptyset$ . Therefore,  $\text{Tr}$  is closed [18].

**Theorem 3.** Assume that the following assumptions holds:

(A<sub>1</sub>) There exist a continuous function  $G: [\zeta, \xi] \times [\zeta, \xi] \rightarrow [0, \infty)$  such that

$$H(K(\zeta, \eta, r), K(\zeta, \eta, t)) \leq G(\zeta, \eta) \Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t), \quad (49)$$

for each  $\zeta, \eta \in [\zeta, \xi]$ .

(A<sub>2</sub>)  $\sup_{\zeta \in [\zeta, \xi]} \int_{\zeta}^{\xi} |G(\zeta, \eta)| \leq (1/2)$ .

(A<sub>3</sub>) Assume that for every vertex  $r$  in  $\mathbf{G}$  and for every  $\vartheta_r \in T_i(r), i = 1, 2$ , we have  $(r, \vartheta_r) \in \mathbf{e}(\mathbf{G})$ .

(A<sub>4</sub>) If any  $r, t \in Q$  with  $(r, t) \in \mathbf{e}(\mathbf{G})$  and  $\vartheta_r \in T_i(r)$ , there exists  $\vartheta_t \in T_j(t)$  for  $i, j = 1, 2$  and  $i \neq j$  such that  $(\vartheta_r, \vartheta_t) \in \mathbf{e}^*(\mathbf{G})$ .

Then, the integral inclusion (46) has a solution.

*Proof.* Let  $r, t \in W$  be such that  $t \in Ts$ . Then, we have  $m_r(\zeta, \eta) \in K_r(\zeta, \eta)$  for  $\zeta, \eta \in [\zeta, \xi]$  such that  $u(\zeta) = \phi(\zeta) + \int_{\zeta}^{\xi} m_r(\zeta, \eta, s(\eta))d\eta$ . On other side, hypothesis ensures that there exist  $v(\zeta, \eta) \in \Lambda_t(\zeta, \eta)$  such that

$$|m_r(\zeta, \eta) - v(\zeta, \eta)| \leq G(\zeta, \eta) \Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t). \quad (50)$$

Consider the set valued operator  $S$  defined by

$$S(\zeta, \eta) = \Lambda_t(\zeta, \eta) \cap \{w \in \mathbf{R}: |m_r(\zeta, \eta) - v(\zeta, \eta)| \leq G(\zeta, \eta)\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)\} \quad (51)$$

Since the operator  $T$  is lower semicontinuous, there exists  $m_t: [\zeta, \xi] \times [\zeta, \xi] \rightarrow \mathbf{R}$  such that  $m_t(\zeta, r) \in S(\zeta, \eta)$  for each  $\zeta, \eta \in [\zeta, \xi]$ ; thus,

$$\begin{aligned} \vartheta_r(\zeta) &= \phi(\zeta) + \int_{\zeta}^{\xi} m_r(\zeta, \eta, r(\eta))d\eta \in \phi(\zeta) \\ &+ \int_{\zeta}^{\xi} K(\zeta, \eta, r(\eta))d\eta, \quad \zeta \in [\zeta, \xi]. \end{aligned} \quad (52)$$

Now, we have

$$\begin{aligned} d(\vartheta_r(\zeta), \vartheta_t(\zeta)) &= \sup_{\zeta \in [\zeta, \xi]} |\vartheta_r(\zeta) - \vartheta_t(\zeta)| \\ &\leq \sup_{\zeta \in [\zeta, \xi]} \left( \int_{\zeta}^{\xi} |m_r(\zeta, \eta, r(\eta)) - m(\zeta, \eta, t(\eta))|d\eta \right) \\ &\leq \sup_{\zeta \in [\zeta, \xi]} \left( \int_{\zeta}^{\xi} G(\zeta, \eta)\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)d\eta \right) \\ &\leq \Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t) \sup_{\zeta \in [\zeta, \xi]} \int_{\zeta}^{\xi} G(\zeta, \eta)d\eta \\ &\leq \frac{\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)}{2}, \end{aligned} \quad (53)$$

and we have

$$\begin{aligned} \psi(d(\vartheta_r(\zeta), \vartheta_t(\zeta))) &\leq \psi(\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)) \\ &- \phi(\Lambda_{\psi_1}(r, t; \vartheta_r, \vartheta_t)). \end{aligned} \quad (54)$$

By taking  $\psi(\zeta) = \zeta$ ,  $\phi(\zeta) = (\zeta/2)$ . From Theorem 1, the integral inclusion (46) has a solution.  $\square$

## 4. Conclusion

Common fixed point results for single-valued mappings are used to solve nonlinear integral, functional, and matrix equations, etc. However, the studies of the set-valued mapping generalize the concept of single valued mappings. Such studies have been applied to prove the existence of solution for integral and differential inclusion and existence of equilibria in game theory. The result of Abbas et al. [12] generalized many results for set-valued mapping related with F-contraction while our results generalized many results related with weak-contraction; for detail, Alber and Guerre-Delabriere [20] established results for single valued mapping and relax contraction condition in form of weak contraction. Then, Doric [21] proved common fixed point for generalized  $(\psi, \phi)$ -weak contractions. Dutta and Choudhury [22] generalized the result in metric space. Loung and Thuan [23] and Rhoades [24] also used weak contraction in this line and established fixed point results in metric spaces. Similarly Zhang and Song [25] further explored the results for generalized  $\phi$ -weak contractions. Our

results generalized the mention results and many more in this direction for set-valued mapping induced with graph without using Hausdorff metric.

## Data Availability

No data were used in the manuscript.

## Conflicts of Interest

The authors declare that they have no conflicts of interest.

## Acknowledgments

The author N. Mlaiki would like to thank Prince Sutan University Riyadh, Saudi Arabia for Paying the APC and for the support through the TAS research lab.

## References

- [1] S. Banach, "Sur les opérations dans les ensembles abstraits et leur application aux équations intégrales," *Fundamenta Mathematicae*, vol. 3, pp. 133–181, 1922.
- [2] A. F. Filippov, *Differential Equations with Discontinuous Right-Hand Sides*, Kluwer Academic Publishers, Alphen aan den Rijn, Netherlands, 1988.
- [3] N. N. Krasovskii and A. I. Subbotin, *Game-theoretical Control Problems*, Springer-Verlag, Berlin, Germany, 1988.
- [4] S. B. Nadler, "Multivalued contraction mappings," *Pacific Journal of Mathematics*, vol. 30, Article ID 475488, 1969.
- [5] F. Echenique, "A short and constructive proof of Tarski's fixed-point theorem," *International Journal of Game Theory*, vol. 33, no. 2, pp. 215–218, 2005.
- [6] R. Espinola and W. A. Kirk, "Fixed point theorems in R-trees with applications to graph theory," *Topology and its Applications*, vol. 153, pp. 1046–1055, 2006.
- [7] J. Jachymski, "The contraction principle for mappings on a metric space with a graph," *Proceedings of the American Mathematical Society*, vol. 136, pp. 1359–1373, 2008.
- [8] I. Beg, A. R. Butt, and S. Radojević, "The contraction principle for set valued mappings on a metric space with a graph," *Computers & Mathematics with Applications*, vol. 60, no. 5, pp. 1214–1219, 2010.
- [9] M. A. Kutbi and W. Sintunavarat, "Fixed point analysis for multi-valued operators with graph approach by the generalized Hausdorff distance," *Fixed Point Theory and Applications*, vol. 2014, no. 1, p. 142, 2014.
- [10] F. Bojor, "Fixed points of Kannan mappings in metric spaces endowed with a graph," *Analele Universitatii "Ovidius" Constanta-Seria Matematica*, vol. 20, no. 1, pp. 31–40, 2012.
- [11] M. Abbas and T. Nazir, "Common fixed point of a power graphic contraction pair in partial metric spaces endowed with a graph," *Fixed Point Theory and Applications*, vol. 20, p. 8, 2013.
- [12] M. Abbas, M. R. Alfuraidan, M. R. Alfuraidan, and T. Nazir, "Common fixed points of multivalued F-contractions on metric spaces with a directed graph," *Carpathian Journal of Mathematics*, vol. 32, no. 1, pp. 1–12, 2016.
- [13] M. R. Alfuraidan, "Remarks on Caristi's fixed point theorem in metric spaces with a graph," *Fixed Point Theory and Applications*, vol. 240, 2014.

- [14] J. Tiammee and S. Suantai, "Coincidence point theorems for graph-preserving multi-valued mappings," *Fixed Point Theory and Applications*, vol. 70, 2014.
- [15] J. Jachymski and I. Jozwik, "Nonlinear contractive conditions: a comparison and related problems," *Banach Center Publications*, vol. 77, pp. 123–146, 2007.
- [16] S. Abdullah Al-Mezel and J. Ahmad, "Generalized fixed-point results for almost  $(\alpha, F\sigma)$ -contractions with applications to Fredholm integral inclusions," *Symmetry*, vol. 11, no. 9, 2019.
- [17] H. H. Al-Sulami Jamshaid Ahmad, N. Hussain, and A. Latif, "Solutions to fredholm integral inclusions via generalized fuzzy contractions," *Mathematics*, vol. 7, no. 9, 2019.
- [18] A. Sintam Arian, "Integral inclusions of Fredholm type relative to multivalued  $\phi$  contractions," *Fixed Point Theory*, vol. 3, pp. 361–368, 2002.
- [19] M. Usman, A. T. Kamran, and M. Postolachec, "Solution of Volterra integral inclusion in b-metric spaces via new fixed point theorem," *Nonlinear Analysis: Modelling and Control*, vol. 22, no. 1, pp. 17–30, 2017.
- [20] Y. I. Alber and S. Guerre-Delabriere, "Principles of weakly contractive maps in Hilbert spaces, new results in operator theory," *New Results in Operator Theory and its Applications*, vol. 98, pp. 7–22, 1997.
- [21] D. Doric, "Common fixed point for generalized  $(\psi, \phi)$ -weak contractions," *Applied Mathematics Letters*, vol. 22, pp. 1896–1900, 2009.
- [22] P. N. Dutta and B. S. Choudhury, "A generalization of contractive principle in metric space," *Fixed Point Theory and Applications*, vol. 2008, pp. 1–8, 2010.
- [23] N. V. Loung and N. X. Thuan, "A fixed point theorem for weakly contractive mapping in metric spaces," *International Journal of Math Analysis*, vol. 4, pp. 233–242, 2010.
- [24] B. E. Rhoades, "Some theorems on weakly contractive maps," *Nonlinear Analysis: Theory, Methods & Applications*, vol. 47, no. 4, pp. 2683–2693, 2001.
- [25] Q. Zhang and Y. Song, "Fixed point theory for generalized  $\phi$ -weak contractions," *Applied Mathematics Letters*, vol. 22, pp. 75–78, 2009.