

Corrigendum Corrigendum to "Joint Inspection of HD Video and Robot in Substation Based on OCR Technology"

Xiao Liao, Ke Xie, and Zhen Qiu

State Grid Information and Communication Group Co., Ltd, Beijing 100021, China

Correspondence should be addressed to Xiao Liao; liaoxiao@sgitg.sgcc.com.cn

Received 6 February 2022; Accepted 6 February 2022; Published 6 May 2022

Copyright © 2022 Xiao Liao et al. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

In the article titled "Joint Inspection of HD Video and Robot in Substation Based on OCR Technology" [1], the authors wish to correct reference 15, which does not correspond to the paper described in the article. Reference 15 should be corrected as follows [2]:

15. Zahari Taha, Y. R.Tang, K. C.Yap. "Development of an onboard system for flight data collection of a small-scale UAV helicopter", Mechatronics, Vol. 21, Issue 1, PP. 132–144, February 2011. https://doi.org/10.1016/ j.mechatronics.2010.09.008.

References

- X. Liao, K. Xie, and Z. Qiu, "Joint inspection of HD video and robot in substation based on OCR technology," *Mobile Information Systems*, vol. 2021, Article ID 8088574, 10 pages, 2021.
- [2] Z. Taha, Y. R. Tang, and K. C. Yap, "Development of an onboard system for flight data collection of a small-scale UAV helicopter," *Mechatronics*, vol. 21, no. 1, pp. 132–144, 2011.