# Several Dynamical Properties for a Nonlinear Shallow Water Equation 

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A nonlinear third order dispersive shallow water equation including the Degasperis-Procesi model is investigated. The existence of weak solutions for the equation is proved in the space $L^{1}(R) \cap B V(R)$ under certain assumptions. The Oleinik type estimate and $L^{2 N}(R)(N$ is a natural number) estimate for the solution are obtained.

## 1. Introduction

Constantin and Lannes [1] derived the shallow water wave equation

$$
\begin{align*}
u_{t} & +u_{x}+\frac{3}{2} \rho u u_{x}+\mu\left(\alpha u_{x x x}+\beta u_{x x t}\right)  \tag{1}\\
& =\rho \mu\left(\gamma u_{x} u_{x x}+\delta u u_{x x x}\right)
\end{align*}
$$

where the constants $\alpha, \beta, \gamma, \delta, \rho$, and $\mu$ satisfy certain conditions. As stated in [1], using suitable mathematical transformations, one can turn (1) into the form

$$
\begin{equation*}
u_{t}-u_{x x t}+2 k u_{x}+m u u_{x}=a u_{x} u_{x x}+b u u_{x x x} \tag{2}
\end{equation*}
$$

where $a, b, k$, and $m$ are constants. Clearly, (2) contains both the Camassa-Holm and Degasperis-Procesi models.

The aim of this paper is to investigate the existence of weak solutions for the special case of (2). Namely, we study the shallow water equation

$$
\begin{array}{r}
\partial_{t} u-\partial_{t x x}^{3} u+m u \partial_{x} u=3 \partial_{x} u \partial_{x x}^{2} u+u \partial_{x x x}^{3} u  \tag{3}\\
(t, x) \in R_{+} \times R
\end{array}
$$

where $m>0$ is a constant. Letting $y=u-\partial_{x x}^{2} u, v=$ $\left(m-\partial_{x x}^{2}\right)^{-1} u$ and using (3), we derive the conservation law

$$
\begin{align*}
\int_{R} y v d x & =\int_{R} \frac{1+\xi^{2}}{m+\xi^{2}}|\widehat{u}(\xi)|^{2} d \xi \\
& =\int_{R} \frac{1+\xi^{2}}{m+\xi^{2}}\left|\widehat{u}_{0}(\xi)\right|^{2} d \xi \sim\left\|u_{0}\right\|_{L^{2}(R)} \tag{4}
\end{align*}
$$

where $u_{0}=u(0, x)$. In fact, the conservation law (4) takes an important role in our further investigations of (3).

For $m=4$, (3) reduces to the Degasperis-Procesi equation [2]

$$
\begin{array}{r}
\partial_{t} u-\partial_{t x x}^{3} u+4 u \partial_{x} u=3 \partial_{x} u \partial_{x x}^{2} u+u \partial_{x x x}^{3} u  \tag{5}\\
(t, x) \in R_{+} \times R
\end{array}
$$

which has been studied by many scholars (see [3-5]). Lundmark and Szmigielski [6] developed an inverse scattering approach for computing $n$-peakon solutions to (5). The traveling wave solutions of (5) were investigated in Vakhnenko and Parkes [5]. Holm and Staley [7] studied stability of solitons and peakons numerically. Lin and Liu [8] proved the stability of peakons for the Degasperis-Procesi equation (5) under certain assumptions. The precise blowup scenario result, a blowup result, and the global existence of strong solutions and global weak solutions to (5) can be found in [9]. Matsuno [10] studied multisoliton solutions and their peakon limits.

Analogous to the case of the Camassa-Holm equation, Henry [11] and Mustafa [12] showed that smooth solutions to (5) have infinite speed of propagation. For other methods to handle the problems relating to various dynamic properties of the Degasperis-Procesi equation and other shallow water equations, the reader is referred to [13-15] and the references therein.

Coclite and Karlsen [16] established the existence, uniqueness, and $L^{1}(R)$ stability of entropy weak solutions belonging to the class $L^{1}(R) \cap B V(R)$ for (5). They obtained existence of at least one weak solution satisfying a restricted set of entropy inequalities in the space $L^{2}(R) \cap L^{4}(R)$ and extended these results to a class of generalized DegasperisProcesi equations in [16].

Motivated by the desire to extend parts of the results presented in Coclite and Karlsen [16], we consider (3) with its Cauchy problem in the form

$$
\begin{align*}
\partial_{t} u-\partial_{t x x}^{3} u= & -\partial_{x}\left(\frac{m}{2} u^{2}\right)+3 \partial_{x} u \partial_{x x}^{2} u+u \partial_{x x x}^{3} u \\
= & -\left(\frac{m}{2} u^{2}\right)_{x}+\frac{1}{2} \partial_{x x x}^{3} u^{2},  \tag{6}\\
& u(0, x)=u_{0}(x),
\end{align*}
$$

which is equivalent to

$$
\begin{gather*}
u_{t}+u u_{x}=-\frac{m-1}{2} \Lambda^{-2}\left(u^{2}\right)_{x},  \tag{7}\\
u(0, x)=u_{0}(x),
\end{gather*}
$$

where $m>0$ is a constant and $\Lambda=\left(1-\partial_{x}^{2}\right)^{1 / 2}$.
The objective of this paper is to study (3). We investigate the existence of weak solutions in the space $L^{1}(R) \cap B V(R)$ under certain conditions. Several dynamical properties such as Oleinik type estimate and $L^{2 N}(R)$ ( $N$ is a natural number) are obtained. As (3) includes the Degasperis-Procesi equation (5), parts of results presented in [16] are extended. Here we should mention that the generalized Degasperis-Procesi equation discussed in [16] does not include the model (3). We state that the ideas and approaches to prove our main results come from those in [16].

The rest of this paper is organized as follows. Section 2 establishes the $L^{2}, B V$, and $L^{\infty}$ estimates for the viscous approximations of problem (6). The main result is given in Section 3.

## 2. Viscous Approximations and Estimates

Firstly, we give some notations.
Set $R_{+}=[0,+\infty)$. The space of all infinitely differentiable functions $\phi(t, x)$ with compact support in $R_{+} \times R$ is denoted by $C_{0}^{\infty}$. We let $L^{p}=L^{p}(R)(1 \leq p<+\infty)$ be the space of all measurable functions $h$ such that $\|h\|_{L^{p}}^{p}=\int_{R}|h(t, x)|^{p} d x<$ $\infty$. We define $L^{\infty}=L^{\infty}(R)$ with the standard norm $\|h\|_{L^{\infty}}=\inf _{m(e)=0} \sup _{x \in R \backslash e}|h(t, x)|$. For any real number $s$,
we let $H^{s}=H^{s}(R)$ denote the Sobolev space with the norm defined by

$$
\begin{equation*}
\|h\|_{H^{s}}=\left(\int_{R}\left(1+|\xi|^{2}\right)^{s}|\widehat{h}(t, \xi)|^{2} d \xi\right)^{1 / 2}<\infty, \tag{8}
\end{equation*}
$$

where $\widehat{h}(t, \xi)=\int_{R} e^{-i x \xi} h(t, x) d x$.
For $T>0$ and nonnegative number $s$, let $C\left([0, T) ; H^{s}(R)\right)$ denote the Frechet space of all continuous $H^{s}$-valued functions on $[0, T)$.

Defining

$$
\phi(x)= \begin{cases}e^{1 /\left(x^{2}-1\right)}, & |x|<1  \tag{9}\\ 0, & |x| \geq 1\end{cases}
$$

and letting $\phi_{\varepsilon}(x)=\varepsilon^{-1 / 4} \phi\left(\varepsilon^{-1 / 4} x\right)$ with $0<\varepsilon<1 / 4$ and $u_{0, \varepsilon}=\phi_{\varepsilon} \star u_{0}$, we know that $u_{0, \varepsilon} \in C^{\infty}$ for any $u_{0} \in H^{s}$ with $s \geq 0$.

For simplicity, throughout this paper, we let $c_{0}$ denote any positive constant, which is independent of parameter $\varepsilon$ and time $t$.

To establish the existence of solutions to the Cauchy problem (6), we will analyze the limiting behavior of a sequence of smooth functions $\left\{u_{\varepsilon}\right\}_{\varepsilon>0}$, where each function $u_{\varepsilon}$ satisfies the viscous problem

$$
\begin{align*}
& \partial_{t} u_{\varepsilon}-\partial_{t x x}^{3} u_{\varepsilon}+m u_{\varepsilon} \partial_{x} u_{\varepsilon} \\
& =3 \partial_{x} u_{\varepsilon} \partial_{x x}^{2} u_{\varepsilon}+u_{\varepsilon} \partial_{x x x}^{3} u_{\varepsilon}+\varepsilon \partial_{x x}^{2} u_{\varepsilon}-\varepsilon \partial_{x x x x}^{4} u_{\varepsilon}, \\
& \quad(t, x) \in R_{+} \times R, \\
& u_{\varepsilon}(0, x)=u_{0, \varepsilon}(x), \quad x \in R, \tag{10}
\end{align*}
$$

which is equivalent to the parabolic-elliptic system

$$
\begin{gather*}
\partial_{t} u_{\varepsilon}+\partial_{x}\left(\frac{u_{\varepsilon}^{2}}{2}\right)+\partial_{x} P_{\varepsilon}=\varepsilon \partial_{x x} u_{\varepsilon} \\
P_{\varepsilon}-\partial_{x x}^{2} P_{\varepsilon}=\frac{m-1}{2} u_{\varepsilon}^{2}  \tag{11}\\
u_{\varepsilon}(0, x)=u_{0, \varepsilon}(x) .
\end{gather*}
$$

From the second identity of (11), we get

$$
\begin{equation*}
P_{\varepsilon}(t, x)=\frac{m-1}{4} \int_{R} e^{|x-y|} u_{\varepsilon}^{2}(t, y) d y . \tag{12}
\end{equation*}
$$

2.1. $L^{2}$ Estimates and Several Consequences. Several properties for the smooth function $u_{0, \varepsilon}$ are given in the following Lemma.

Lemma 1. The following estimates hold for any $\varepsilon$ with $0<\varepsilon<$ $1 / 4$ and $s \geq 0$ :

$$
\begin{gathered}
\left\|u_{0, \varepsilon}\right\|_{L^{2}(R)} \leq c_{0}\left\|u_{0}\right\|_{L^{2}(R)} \\
\left\|u_{0, \varepsilon}\right\|_{L^{1}(R)} \leq c_{0}\left\|u_{0}\right\|_{L^{1}(R)} \\
\left\|u_{0, \varepsilon}\right\|_{B V(R)} \leq c_{0}\left\|u_{0}\right\|_{B V(R)} \\
\left\|u_{0, \varepsilon}\right\|_{L^{p}(R)} \leq c_{0}\left\|u_{0}\right\|_{L^{p}(R)} \quad \text { for } 1 \leq p \leq \infty \\
u_{0, \varepsilon} \longrightarrow u_{0} \quad(\varepsilon \longrightarrow 0) \text { in } L^{p}(R) \text { for } 1 \leq p \leq \infty \\
\left\|u_{0, \varepsilon}\right\|_{H^{q}} \leq c_{0}\left\|u_{0}\right\|_{H^{s}}, \quad \text { if } q \leq s
\end{gathered}
$$

where $c_{0}$ is a constant independent of $\varepsilon$.
The proof of Lemma 1 is similar to that of Lemma 5 presented in [14]. Here we omit it.

Lemma 2. Provided that $u_{0} \in L^{2}(R)$, for any fixed $\varepsilon>0$, there exists a unique global smooth solution $u_{\varepsilon}=u_{\varepsilon}(t, x)$ to the Cauchy problem (11) belonging to $C\left([0, \infty) ; H^{s}(R)\right)$ with $s \geq 0$.

Proof. We omit the proof since it is similar to the one found in [16] or [17] by using $u_{0, \varepsilon} \in C^{\infty}(R)$.

Lemma 3. Assume that $u_{0} \in L^{2}(R)$ holds and $u_{\varepsilon}$ is a solution of problem (10). Then, the following bounds hold for any $t \geq 0$ :

$$
\begin{gather*}
\left\|u_{\varepsilon}\right\|_{L^{2}} \leq c_{0}\left\|u_{0}\right\|_{L^{2}}  \tag{14}\\
\sqrt{\varepsilon}\left\|\partial_{x} u_{\varepsilon}\right\|_{L^{2}} \leq c_{0}\left\|u_{0}\right\|_{L^{2}}, \tag{15}
\end{gather*}
$$

where $c_{0}$ is a positive constant independent of $\varepsilon$ and $t$.
Proof. Letting

$$
\begin{equation*}
m v_{\varepsilon}-\partial_{x x}^{2} v_{\varepsilon}=u_{\varepsilon} \tag{16}
\end{equation*}
$$

derives

$$
\begin{equation*}
v_{\varepsilon}=\left(m-\partial_{x x}^{2}\right)^{-1} u_{\varepsilon} \tag{17}
\end{equation*}
$$

Multiplying the first equation of problem (11) by $v_{\varepsilon}-\partial_{x x}^{2} v_{\varepsilon}$ and integrating over $R$ yield

$$
\begin{aligned}
& \int_{R} \partial_{t} u_{\varepsilon}\left(v_{\varepsilon}-\partial_{x x}^{2} v_{\varepsilon}\right) d x-\varepsilon \int_{R} \partial_{x x}^{2} u_{\varepsilon}\left(v_{\varepsilon}-\partial_{x x}^{2} v_{\varepsilon}\right) d x \\
& \quad=-\int_{R} u_{\varepsilon} \partial_{x} u_{\varepsilon}\left(v_{\varepsilon}-\partial_{x x}^{2} v_{\varepsilon}\right) d x \\
& \quad-\int_{R} \partial_{x} P_{\varepsilon}\left(v_{\varepsilon}-\partial_{x x}^{2} v_{\varepsilon}\right) d x
\end{aligned}
$$

For the left-hand side of this identity, using (16), we get

$$
\begin{align*}
& \int_{R} \partial_{t} u_{\varepsilon}\left(v_{\varepsilon}-\partial_{x x}^{2} v_{\varepsilon}\right) d x-\varepsilon \int_{R} \partial_{x x}^{2} u_{\varepsilon}\left(v_{\varepsilon}-\partial_{x x}^{2} v_{\varepsilon}\right) d x \\
& =\int_{R}\left(m \partial_{t} v_{\varepsilon}-\partial_{t x x}^{3} v_{\varepsilon}\right)\left(v_{\varepsilon}-\partial_{x x}^{2} v_{\varepsilon}\right) d x \\
& -\varepsilon \int_{R}\left(m \partial_{x x}^{2} v_{\varepsilon}-\partial_{x x x x}^{4} v_{\varepsilon}\right)\left(v_{\varepsilon}-\partial_{x x}^{2} v_{\varepsilon}\right) d x \\
& =\int_{R}\left(m v_{\varepsilon} \partial_{t} v_{\varepsilon}-v_{\varepsilon} \partial_{t x x}^{3} v_{\varepsilon}-m \partial_{t} v_{\varepsilon} \partial_{x x}^{2} v_{\varepsilon}\right. \\
& \left.+\partial_{x x}^{2} v_{\varepsilon} \partial_{t x x}^{3} v_{\varepsilon}\right) d x \\
& -\varepsilon \int_{R}\left(m v_{\varepsilon} \partial_{x x}^{2} v_{\varepsilon}-m\left(\partial_{x x}^{2} v_{\varepsilon}\right)^{2}-v_{\varepsilon} \partial_{x x x x}^{4} v_{\varepsilon}\right. \\
& \left.+\partial_{x x}^{2} v_{\varepsilon} \partial_{x x x x}^{4} v_{\varepsilon}\right) d x \\
& =\int_{R}\left(m v_{\varepsilon} \partial_{t} v_{\varepsilon}-(m+1) v_{\varepsilon} \partial_{t x x}^{3} v_{\varepsilon}+\partial_{x x}^{2} v_{\varepsilon} \partial_{t x x}^{3} v_{\varepsilon}\right) d x \\
& -\varepsilon \int_{R}\left(m v_{\varepsilon} \partial_{x x}^{2} v_{\varepsilon}-(m+1) v_{\varepsilon} \partial_{x x x x}^{4} v_{\varepsilon}\right. \\
& \left.+\partial_{x x}^{2} v_{\varepsilon} \partial_{x x x x}^{4} v_{\varepsilon}\right) d x \\
& =\int_{R}\left(m v_{\varepsilon} \partial_{t} v_{\varepsilon}+(m+1) \partial_{x} v_{\varepsilon} \partial_{t x}^{2} v_{\varepsilon}+\partial_{x x}^{2} v_{\varepsilon} \partial_{t x x}^{3} v_{\varepsilon}\right) d x \\
& -\varepsilon \int_{R}\left(-m \partial_{x} v_{\varepsilon} \partial_{x} v_{\varepsilon}-(m+1) \partial_{x x}^{2} v_{\varepsilon} \partial_{x x}^{2} v_{\varepsilon}\right. \\
& \left.-\partial_{x x x}^{3} v_{\varepsilon} \partial_{x x x}^{3} v_{\varepsilon}\right) d x \\
& =\frac{1}{2} \frac{d}{d t} \int_{R}\left(m v_{\varepsilon}^{2}+(m+1)\left(\partial_{x} v_{\varepsilon}\right)^{2}+\left(\partial_{x x}^{2} v_{\varepsilon}\right)^{2}\right) d x \\
& +\varepsilon \int_{R}\left(m\left(\partial_{x} v_{\varepsilon}\right)^{2}+(m+1)\left(\partial_{x x}^{2} v_{\varepsilon}\right)^{2}+\left(\partial_{x x x}^{3} v_{\varepsilon}\right)^{2}\right) d x . \tag{19}
\end{align*}
$$

For the right-hand side of (18), we conclude

$$
\begin{aligned}
& -\int_{R} u_{\varepsilon} \partial_{x} u_{\varepsilon}\left(v_{\varepsilon}-\partial_{x x}^{2} v_{\varepsilon}\right) d x-\int_{R} \partial_{x} P_{\varepsilon}\left(v_{\varepsilon}-\partial_{x x}^{2} v_{\varepsilon}\right) d x \\
& =-\int_{R} u_{\varepsilon} \partial_{x} u_{\varepsilon}\left(v_{\varepsilon}-\partial_{x x}^{2} v_{\varepsilon}\right) d x \\
& \quad+\int_{R}\left(P_{\varepsilon}-\partial_{x x}^{2} P_{\varepsilon}\right) \partial_{x} v_{\varepsilon} d x \\
& = \\
& -\int_{R} u_{\varepsilon} \partial_{x} u_{\varepsilon}\left(v_{\varepsilon}-\partial_{x x}^{2} v_{\varepsilon}\right) d x
\end{aligned}
$$

$$
\begin{align*}
& +\frac{m-1}{2} \int_{R} u_{\varepsilon}^{2} \partial_{x} v_{\varepsilon} d x \\
= & -\int_{R} u_{\varepsilon} \partial_{x} u_{\varepsilon}\left(v_{\varepsilon}-\partial_{x x}^{2} v_{\varepsilon}\right) d x \\
& -(m-1) \int_{R} u_{\varepsilon} \partial_{x} u_{\varepsilon} v_{\varepsilon} d x \\
= & \int_{R}\left(-m u_{\varepsilon} \partial_{x} u_{\varepsilon} v_{\varepsilon}+u_{\varepsilon} \partial_{x} u_{\varepsilon} \partial_{x x}^{2} v_{\varepsilon}\right) d x \\
= & \int_{R} u_{\varepsilon} \partial_{x} u_{\varepsilon}\left(-m v_{\varepsilon}+\partial_{x x}^{2} v_{\varepsilon}\right) d x \\
= & -\int_{R} u_{\varepsilon}^{2} \partial_{x} u_{\varepsilon} d x \\
= & 0, \tag{20}
\end{align*}
$$

where we have used (16) and integration by parts.
From (18), (19), and (20), we have

$$
\begin{align*}
& m\left\|v_{\varepsilon}\right\|_{L^{2}}^{2}+(m+1)\left\|\partial_{x} v_{\varepsilon}\right\|_{L^{2}}^{2}+\left\|\partial_{x x}^{2} v_{\varepsilon}\right\|_{L^{2}}^{2} \\
& \quad+2 \varepsilon \int_{R}\left(m\left\|\partial_{x} v_{\varepsilon}\right\|_{L^{2}}^{2}+(m+1)\left\|\partial_{x x}^{2} v_{\varepsilon}\right\|_{L^{2}}^{2}\right. \\
& \left.\quad+\left\|\partial_{x x x}^{3} v_{\varepsilon}\right\|_{L^{2}}^{2}\right) d x  \tag{21}\\
& =m\left\|v_{\varepsilon}(0, \cdot)\right\|_{L^{2}}^{2}+(m+1)\left\|\partial_{x} v_{\varepsilon}(0, \cdot)\right\|_{L^{2}}^{2} \\
& \quad+\left\|\partial_{x x}^{2} v_{\varepsilon}(0, \cdot)\right\|_{L^{2}}^{2}
\end{align*}
$$

From (17), we obtain

$$
\begin{align*}
& \left\|v_{\varepsilon}(0, \cdot)\right\|_{L^{2}},\left\|\partial_{x} v_{\varepsilon}(0, \cdot)\right\|_{L^{2}},\left\|\partial_{x x}^{2} v_{\varepsilon}(0, \cdot)\right\|_{L^{2}}  \tag{22}\\
& \quad \leq c_{0}\left\|u_{0, \varepsilon}\right\|_{L^{2}} \leq c_{0}\left\|u_{0}\right\|_{L^{2}} .
\end{align*}
$$

It follows from (16) that

$$
\begin{aligned}
& \left\|u_{\varepsilon}(t, \cdot)\right\|_{L^{2}(R)}^{2} \\
& =\int_{R}\left(-\partial_{x x}^{2} v_{\varepsilon}+m v_{\varepsilon}\right)^{2} d x \\
& = \\
& \quad \int_{R}\left(\partial_{x x}^{2} v_{\varepsilon}\right)^{2} d x-2 m \int_{R} v_{\varepsilon} \partial_{x x}^{2} v_{\varepsilon} d x \\
& \quad+m^{2} \int_{R} v_{\varepsilon}^{2} d x \\
& = \\
& \quad \int_{R}\left(\partial_{x x}^{2} v_{\varepsilon}\right)^{2} d x+2 m \int_{R}\left(\partial_{x} v_{\varepsilon}\right)^{2} d x \\
& \quad+m^{2} \int_{R} v_{\varepsilon}^{2} d x .
\end{aligned}
$$

Using (16), (21), and Lemma 1 derives that

$$
\begin{align*}
& \left\|u_{\varepsilon}\right\|_{L^{2}}^{2} \\
& \leq 2\left\|\partial_{x x}^{2} v_{\varepsilon}\right\|_{L^{2}}^{2}+2 m^{2}\left\|v_{\varepsilon}\right\|_{L^{2}}^{2} \\
& \leq \max (2,2 m)\left(m\left\|v_{\varepsilon}\right\|_{L^{2}}^{2}+(m+1)\left\|\partial_{x} v_{\varepsilon}\right\|_{L^{2}}^{2}\right. \\
& \left.+\left\|\partial_{x x}^{2} v_{\varepsilon}\right\|_{L^{2}}^{2}\right) \\
& \leq \max (2,2 m)\left(m\left\|v_{\varepsilon}(0, \cdot)\right\|_{L^{2}}^{2}+(m+1)\left\|\partial_{x} v_{\varepsilon}(0, \cdot)\right\|_{L^{2}}^{2}\right. \\
& \left.+\left\|\partial_{x x}^{2} v_{\varepsilon}(0, \cdot)\right\|_{L^{2}}^{2}\right) \\
& \leq c_{0}\left\|u_{0, \varepsilon}\right\|_{L^{2}}^{2} \\
& \leq c_{0}\left\|u_{0}\right\|_{L^{2}}^{2}, \\
& \varepsilon\left\|\partial_{x} u_{\varepsilon}\right\|_{L^{2}}^{2} \\
& \leq 2 \varepsilon\left\|\partial_{x x x}^{3} v_{\varepsilon}\right\|_{L^{2}}^{2}+2 m^{2} \varepsilon\left\|\partial_{x} v_{\varepsilon}\right\|_{L^{2}}^{2} \\
& \leq \varepsilon \max (2,2 m)\left(m\left\|\partial_{x} v_{\varepsilon}\right\|_{L^{2}}^{2}+(m+1)\left\|\partial_{x x}^{2} v_{\varepsilon}\right\|_{L^{2}}^{2}\right. \\
& \left.+\left\|\partial_{x x x}^{3} v_{\varepsilon}\right\|_{L^{2}}^{2}\right) \\
& \leq \max (2,2 m)\left(m\left\|v_{\varepsilon}(0, \cdot)\right\|_{L^{2}}^{2}+(m+1)\left\|\partial_{x} v_{\varepsilon}(0, \cdot)\right\|_{L^{2}}^{2}\right. \\
& \left.+\left\|\partial_{x x}^{2} v_{\varepsilon}(0, \cdot)\right\|_{L^{2}}^{2}\right) \\
& \leq c_{0}\left\|u_{0, \varepsilon}\right\|_{L^{2}}^{2} \\
& \leq c_{0}\left\|u_{0}\right\|_{L^{2}}^{2} \text {. } \tag{24}
\end{align*}
$$

The proof of Lemma 3 follows from (24).

We give some bounds on the nonlocal term $P_{\varepsilon}$, in which all are consequences of the $L^{2}$ bound in Lemma 3.

Lemma 4. Assume that $u_{0} \in L^{2}(R)$ holds. Then,

$$
\begin{gather*}
P_{\varepsilon} \geq 0 \quad \text { for } m \geq 1,  \tag{25}\\
\left\|P_{\varepsilon}(t, \cdot)\right\|_{L^{1}(R)}, \quad\left\|\partial_{x} P_{\varepsilon}(t, \cdot)\right\|_{L^{1}(R)} \leq c_{0} \frac{|m-1|}{2}\left\|u_{0}\right\|_{L^{2}}^{2},  \tag{26}\\
\left\|P_{\varepsilon}\right\|_{L^{\infty}\left(R_{+} \times R\right)}, \quad\left\|\partial_{x} P_{\varepsilon}\right\|_{L^{\infty}\left(R_{+} \times R\right)} \leq c_{0} \frac{|m-1|}{2}\left\|u_{0}\right\|_{L^{2}}^{2},  \tag{27}\\
\left\|\partial_{x x}^{2} P_{\varepsilon}(t, \cdot)\right\|_{L^{1}(R)} \leq c_{0} \frac{|m-1|}{2}\left\|u_{0}\right\|_{L^{2}}^{2}, \tag{28}
\end{gather*}
$$

where $c_{0}$ is a constant independent of $\varepsilon$ and $t$.

Proof. Using (11), we get

$$
\begin{gather*}
P_{\varepsilon}(t, x)=\frac{m-1}{4} \int_{R} e^{-|x-y|}\left(u_{\varepsilon}(t, y)\right)^{2} d y  \tag{29}\\
\partial_{x} P_{\varepsilon}(t, x)=\frac{m-1}{4} \int_{R} e^{-|x-y|} \operatorname{sign}(y-x)\left(u_{\varepsilon}(t, y)\right)^{2} d y \tag{30}
\end{gather*}
$$

From (29), we obtain (25). Using (14) and the Tonelli theorem, we have

$$
\begin{aligned}
& \int_{R}\left|P_{\varepsilon}(t, x)\right| d x \\
& \quad \leq \frac{|m-1|}{4} \int_{R}\left(\int_{R} e^{-|x-y|} d x\right)\left(u_{\varepsilon}(t, y)\right)^{2} d y \\
& \quad \leq c_{0} \frac{|m-1|}{2} \int_{R}\left(u_{\varepsilon}(t, y)\right)^{2} d y \\
& \quad \leq c_{0} \frac{|m-1|}{2}\left\|u_{0}\right\|_{L^{2}}^{2} \\
& \begin{aligned}
& \int_{R}\left|\partial_{x} P_{\varepsilon}(t, x)\right| d x \\
& \leq \frac{|m-1|}{4} \int_{R}\left(\int_{R} e^{-|x-y|} d x\right)\left(u_{\varepsilon}(t, y)\right)^{2} d y \\
& \quad \leq c_{0} \frac{|m-1|}{2} \int_{R}\left(u_{\varepsilon}(t, y)\right)^{2} d y \\
& \quad \leq c_{0} \frac{|m-1|}{2}\left\|u_{0}\right\|_{L^{2}}^{2}, \\
&\left|P_{\varepsilon}(t, x)\right| \leq \frac{|m-1|}{4} \int_{R}\left(u_{\varepsilon}(t, y)\right)^{2} d y \\
& \quad \leq c_{0} \frac{|m-1|}{4}\left\|u_{0}\right\|_{L^{2}}^{2}, \\
& \leq c_{0} \frac{|m-1|}{4}\left\|u_{0}\right\|_{L^{2}}^{2} .
\end{aligned} \\
& \left|\partial_{x} P_{\varepsilon}(t, x)\right| \leq \frac{|m-1|}{4} \int_{R}\left(u_{\varepsilon}(t, y)\right)^{2} d y \\
& \quad
\end{aligned}
$$

It follows from (31) that (26) and (27) hold. Using the second identity of problem (11), Lemma 3, and (26), we obtain (28).

Lemma 5. If $u_{0} \in L^{1}(R) \cap L^{2}(R)$, it holds that

$$
\begin{equation*}
\left\|u_{\varepsilon}(t, \cdot)\right\|_{L^{1}} \leq\left\|u_{0}\right\|_{L^{1}}+c_{0} t\left\|u_{0}\right\|_{L^{2}}^{2} \tag{32}
\end{equation*}
$$

Proof. Let functions $\eta$ and $q: R \rightarrow R$ be such that $q^{\prime}(u)=$ $u \eta^{\prime}(u)$. Multiplying the first equation in (11) with $\eta^{\prime}\left(u_{\varepsilon}\right)$ gives rise to

$$
\begin{aligned}
\partial_{t} \eta & \left(u_{\varepsilon}\right)+\partial_{x} q\left(u_{\varepsilon}\right)+\eta^{\prime}\left(u_{\varepsilon}\right) \partial_{x} P_{\varepsilon} \\
& =\varepsilon \eta^{\prime}\left(u_{\varepsilon}\right) \partial_{x x}^{2} u_{\varepsilon} \\
& =\varepsilon \partial_{x x}^{2} \eta\left(u_{\varepsilon}\right)-\varepsilon \eta^{\prime \prime}\left(u_{\varepsilon}\right)\left(\partial_{x} u_{\varepsilon}\right)^{2}
\end{aligned}
$$

Choosing $\eta(u)=|u|$ (modulo an approximation argument, see [16]) and then integrating the resulting equation over $R$ yield

$$
\begin{equation*}
\frac{d}{d t} \int_{R}\left|u_{\varepsilon}\right| d x \leq \int_{R}\left|\operatorname{sign}\left(u_{\varepsilon}\right) \partial_{x} P_{\varepsilon}\right| d x \tag{34}
\end{equation*}
$$

Using (26), we get

$$
\begin{equation*}
\frac{d}{d t}\left\|u_{\varepsilon}(t, \cdot)\right\|_{L^{1}} \leq c_{0} \frac{|m-1|}{2}\left\|u_{0}\right\|_{L^{2}}^{2} \tag{35}
\end{equation*}
$$

from which we have (32).
2.2. $B V$ and $L^{\infty}$ Estimates. In this subsection we establish several supplementary estimates for the viscous approximations, which also are consequences of the $L^{2}$ bound in Lemma 3. In particular, we prove that the sequence $\left\{u_{\varepsilon}\right\}_{\varepsilon>0}$ is bounded in $B V$, which yields strong compactness of this sequence. To this end, we need to assume that $u_{0} \in L^{2}(R)$ and $u_{0} \in B V(R)$.

Lemma 6. Assume that $u_{0} \in L^{2}(R)$ and $u_{0} \in B V(R)$ hold. Then,

$$
\begin{equation*}
\left\|\partial_{x} u_{\varepsilon}(t, \cdot)\right\|_{L^{1}(R)} \leq c_{0}\left(\left|u_{0}\right|_{B V}+t\left\|u_{0}\right\|_{L^{2}}^{2}\right), \quad t \geq 0 \tag{36}
\end{equation*}
$$

Proof. Setting $q_{\varepsilon}:=\partial_{x} u_{\varepsilon}$, we know that $q_{\varepsilon}$ satisfies the equation

$$
\begin{equation*}
\partial_{t} q_{\varepsilon}+u_{\varepsilon} \partial_{x} q_{\varepsilon}+q_{\varepsilon}^{2}+\partial_{x x}^{2} P_{\varepsilon}=\varepsilon \partial_{x x}^{2} q_{\varepsilon} \tag{37}
\end{equation*}
$$

If $\eta=\eta(u)$ and $q: R \rightarrow R$ satisfies $q^{\prime}(u)=u \eta^{\prime}(u)$, using the chain rule yields

$$
\begin{align*}
& \partial_{t} \eta\left(q_{\varepsilon}\right)+\partial_{x}\left(u_{\varepsilon} q\left(u_{\varepsilon}\right)\right)-q_{\varepsilon} \eta\left(q_{\varepsilon}\right) \\
&+\eta^{\prime}\left(q_{\varepsilon}\right) q_{\varepsilon}^{2}+\eta^{\prime}\left(u_{\varepsilon}\right) \partial_{x x}^{2} P_{\varepsilon}  \tag{38}\\
&= \varepsilon \partial_{x x}^{2} \eta\left(q_{\varepsilon}\right)-\varepsilon \eta^{\prime \prime}\left(q_{\varepsilon}\right)\left(\partial_{x} q_{\varepsilon}\right)^{2}
\end{align*}
$$

Choosing $\eta(u)=|u|$ (modulo an approximation argument) and then integrating the resulting equation over $R$ give rise to

$$
\begin{equation*}
\frac{d}{d t} \int_{R}\left|\partial_{x} u_{\varepsilon}\right| d x \leq \int_{R}\left|\partial_{x x}^{2} P_{\varepsilon}\right| d x \tag{39}
\end{equation*}
$$

Using (28), we have

$$
\begin{equation*}
\frac{d}{d t} \int_{R}\left|\partial_{x} u_{\varepsilon}\right| d x \leq c_{0}\left\|u_{0}\right\|_{L^{2}(R)}^{2} \tag{40}
\end{equation*}
$$

from which we obtain (36).
Lemma 7. Assume that $u_{0} \in B V(R) \cap L^{2}(R)$ holds. Then,

$$
\begin{equation*}
\left\|u_{\varepsilon}(t, \cdot)\right\|_{L^{\infty}(R)} \leq c_{0}\left(\left|u_{0}\right|_{B V(R)}+t\left\|u_{0}\right\|_{L^{2}(R)}^{2}\right) \tag{41}
\end{equation*}
$$

$t \geq 0$,

$$
\begin{align*}
& \left\|\partial_{x x}^{2} P_{\varepsilon}(t, \cdot)\right\|_{L^{\infty}} \\
& \quad \leq c_{0}\left[\left\|u_{0}\right\|_{L^{2}(R)}^{2}+\left(\left|u_{0}\right|_{B V(R)}+t\left\|u_{0}\right\|_{L^{2}(R)}\right)^{2}\right] \tag{42}
\end{align*}
$$

where $c_{0}$ is independent of $\varepsilon$ and $t$.

## Proof. Using

$$
\begin{equation*}
\left|u_{\varepsilon}(t, \cdot)\right| \leq \int_{R}\left|\partial_{x} u_{\varepsilon}(t, y)\right| d y=\left\|u_{\varepsilon}(t, \cdot)\right\|_{B V(R)} \tag{43}
\end{equation*}
$$

and Lemma 6 derives (41). Using (27), (41), and the second equation of problem (11), we obtain inequality (42).
2.3. $L^{2 N}$ Estimate for Nature Number $N \geq 2$. Next we prove that the viscous approximations are bounded in $L^{2 N}(R)$ for any nature number $N \geq 2$. From Lemmas 6 and 7, if $u_{0} \in$ $B V(R) \cap L^{2}(R)$, we have the inequality $u_{0, \varepsilon} \in L^{\infty}(R)$ from which we derive

$$
\begin{equation*}
u_{0, \varepsilon} \in L^{2}(R) \bigcap L^{2 N}(R) \tag{44}
\end{equation*}
$$

Lemma 8. Assume that $u_{0} \in B V(R) \cap L^{2}(R)$ holds. For any $0<\varepsilon<1 / 4$, it has

$$
\begin{align*}
\left\|u_{\varepsilon}(t, \cdot)\right\|_{L^{2 N}(R)} \leq & c_{0}\left(1+\left\|u_{0}\right\|_{L^{2}}^{2}\right)^{2} t \\
& +\left\|u_{\varepsilon}(0, \cdot)\right\|_{L^{2 N}(R)}^{2 N} e^{c_{0}\left(1+\left\|u_{0}\right\|_{L^{2}}^{2}\right)^{2} t} \tag{45}
\end{align*}
$$

Proof. Choosing $\eta(u)=(1 / 2 N) u^{2 N}$ in (33), writing

$$
\begin{align*}
\partial_{t} \eta & \left(u_{\varepsilon}\right)+\partial_{x} q\left(u_{\varepsilon}\right)+\eta^{\prime}\left(u_{\varepsilon}\right) \partial_{x} P_{\varepsilon} \\
& =\varepsilon \partial_{x x}^{2} \eta\left(u_{\varepsilon}\right)-\varepsilon \eta^{\prime \prime}\left(u_{\varepsilon}\right)\left(\partial_{x} u_{\varepsilon}\right)^{2}  \tag{46}\\
& =\varepsilon \eta^{\prime}\left(u_{\varepsilon}\right) \partial_{x x}^{2} u_{\varepsilon} \\
& =\varepsilon u_{\varepsilon}^{2 N-1} \partial_{x x}^{2} u_{\varepsilon},
\end{align*}
$$

and integrating (46) over $R$ gives rise to

$$
\begin{align*}
\frac{1}{2 N} \frac{d}{d t}\left\|u_{\varepsilon}(t, \cdot)\right\|_{L^{2 N}}^{2 N}= & -\int_{R} u_{\varepsilon}^{2 N-1} \partial_{x} P_{\varepsilon} d x  \tag{47}\\
& +\varepsilon \int_{R} u_{\varepsilon}^{2 N-1} \partial_{x x}^{2} u_{\varepsilon} d x
\end{align*}
$$

Integration by parts shows

$$
\begin{align*}
& \varepsilon \int_{R} u_{\varepsilon}^{2 N-1} \partial_{x x}^{2} u_{\varepsilon} d x \\
& \quad=-(2 N-1) \varepsilon \int_{R} u_{\varepsilon}^{(2 N-2)}\left(\partial_{x} u_{\varepsilon}\right)^{2} d x \leq 0 . \tag{48}
\end{align*}
$$

Letting $p_{1}=2 N /(2 N-1), q_{1}=2 N$, we have $1 / p_{1}+1 / q_{1}=1$. Using Hölder's inequality, (26), and (27), we obtain

$$
\begin{align*}
& \left|\int_{R} u_{\varepsilon}^{2 N-1} \partial_{x} P_{\varepsilon} d x\right| \\
& \quad \leq\left(\int_{R} u_{\varepsilon}^{2 N} d x\right)^{(2 N-1) / 2 N}\left(\int_{R}\left(\partial_{x} P_{\varepsilon}\right)^{2 N}\right)^{1 / 2 N} \\
& \quad \leq\left(1+\int_{R} u_{\varepsilon}^{2 N} d x\right)^{(2 N-1) / 2 N} \\
& \quad \times\left(\left\|\partial_{x} P_{\varepsilon}\right\|_{L^{\infty}\left(R_{+} \times R\right)}^{2 N-1}\right)^{1 / 2 N}\left\|\partial_{x} P_{\varepsilon}\right\|_{L^{1}(R)}^{1 / 2 N}  \tag{49}\\
& \quad \leq\left(1+\int_{R} u_{\varepsilon}^{2 N} d x\right)\left(1+\left\|\partial_{x} P_{\varepsilon}\right\|_{L^{\infty}\left(R_{+} \times R\right)}\right)\left\|\partial_{x} P_{\varepsilon}\right\|_{L^{1}(R)}^{1 / 2 N} \\
& \quad \leq c_{0}\left(1+\left\|u_{0}\right\|_{L^{2}}^{2}\right)\left(1+\left\|u_{0}\right\|_{L^{2}}^{2}\right)^{1 / 2 N}\left(1+\int_{R} u_{\varepsilon}^{2 N} d x\right) \\
& \quad \leq c_{0}\left(1+\left\|u_{0}\right\|_{L^{2}}^{2}\right)^{2}\left(1+\int_{R} u_{\varepsilon}^{2 N} d x\right) .
\end{align*}
$$

Using (47)-(49) gives rise to

$$
\begin{align*}
& \frac{1}{2 N} \frac{d}{d t}\left\|u_{\varepsilon}(t, \cdot)\right\|_{L^{2 N}}^{2 N}  \tag{50}\\
& \quad \leq c_{0}\left(1+\left\|u_{0}\right\|_{L^{2}}^{2}\right)^{2}\left(1+\left\|u_{\varepsilon}(t, \cdot)\right\|_{L^{2 N}}^{2 N}\right)
\end{align*}
$$

from which we obtain (45) by Gronwall's inequality.

### 2.4. Oleinik Type Estimate

Lemma 9 (Oleinik type estimate). Assume that $u_{0} \in L^{2}(R) \cap$ $B V(R)$. Then, for each $t \in(0, T]$ with $T$ being fixed,

$$
\begin{equation*}
\partial_{x} u_{\varepsilon}(t, x) \leq \frac{1}{t}+K_{T}, \quad x \in R \tag{51}
\end{equation*}
$$

where $K_{T}=c_{0}\left\{\left\|u_{0}\right\|_{L^{2}(R)}^{2}+\left(\left\|u_{0}\right\|_{B V(R)}+T\left\|u_{0}\right\|_{L^{2}(R)}^{2}\right)^{2}\right\}^{1 / 2}$.
Proof. Setting $q_{\varepsilon}:=\partial_{x} u_{\varepsilon}$, it follows from (11) and (42) that

$$
\begin{equation*}
\partial_{t} q_{\varepsilon}+u_{\varepsilon} \partial_{x} q_{\varepsilon}+q_{\varepsilon}^{2}-\varepsilon \partial_{x x}^{2} q_{\varepsilon}=-\partial_{x x}^{2} P_{\varepsilon} \leq K_{T}^{2} \tag{52}
\end{equation*}
$$

Considering the ordinary differential equation

$$
\begin{equation*}
\frac{d f}{d t}+f^{2}=K_{T}^{2} \tag{53}
\end{equation*}
$$

and using comparing theorem, we have

$$
\begin{equation*}
\partial_{x} u_{\varepsilon}(t, x) \leq \frac{1}{t}+K_{T}, \quad x \in R \tag{54}
\end{equation*}
$$

which completes the proof.

## 3. Existence in $L^{1}(R) \cap B V(R)$

Using the estimates established in Section 2, we will show the existence of weak solutions to problem (6) under the assumption $u_{0} \in L^{1}(R) \cap B V(R)$.

We state the concepts of weak solutions.

Definition 10 (weak solution). We call a function $u: R_{+} \times$ $R \rightarrow R$ a weak solution of the Cauchy problem (6) provided that
(i) $u \in L^{\infty}\left(R_{+} ; L^{2}(R)\right)$ and
(ii) $\partial_{t} u+\partial_{x}\left(u^{2} / 2\right)+\partial_{x} P^{u}(t, x)=0$ in $D^{\prime}([0, \infty) \times R)$; that is, for all $\phi \in C_{0}^{\infty}([0, \infty) \times R)$, there holds the identity

$$
\begin{align*}
& \int_{R^{+}} \int_{R}\left(u \partial_{t} \phi+\frac{u^{2}}{2} \partial_{x} \phi-\partial_{x} P^{u} \phi\right) d x d t  \tag{55}\\
& \quad+\int_{R} u_{0}(x) \phi(0, x) d x=0
\end{align*}
$$

where

$$
\begin{align*}
P^{u}(t, x) & =G_{1} *\left(\frac{m-1}{2} u^{2}\right)(t, x) \\
& =\frac{m-1}{4} \int_{R} e^{-|x-y|}(u(t, y))^{2} d y . \tag{56}
\end{align*}
$$

Remark 11. It follows from part (i) of Definition 10 that $u \in$ $L^{1}((0, T) \times R)$ for any $T>0$ and $\partial_{x} P^{u} \in L^{\infty}\left(R_{+} \times R\right)$ (see Lemma 5). Therefore, (55) makes sense.

We assume that

$$
\begin{array}{r}
\left\|u\left(t_{2}, \cdot\right)-u\left(t_{1}, \cdot\right)\right\|_{L^{1}(R)} \leq C_{T}\left|t_{2}-t_{1}\right|  \tag{57}\\
\text { for } \forall t_{1}, t_{2} \in[0, T],
\end{array}
$$

where $C_{T}=c_{0}\left[\left\|u_{0}\right\|_{L^{2}(R)}^{2}+\left(\left|u_{0}\right|_{B V(R)}+t\left\|u_{0}\right\|_{L^{2}(R)}\right)^{2}\right]$. Therefore, we have

$$
\begin{equation*}
\lim _{t \rightarrow 0+}\left\|u(t, \cdot)-u_{0}\right\|_{L^{1}(R)}=0 \tag{58}
\end{equation*}
$$

Our main results are summarized in the following Theorem.

Theorem 12. Provided that $u_{0} \in L^{1}(R) \cap L^{2}(R) \cap B V(R)$ and the solution $u(t, x)$ satisfies (57), then there exists a weak solution to the Cauchy problem (6). The weak solution $u$ satisfies the following estimates for any $t \in(0, T)$ :

$$
\|u(t, \cdot)\|_{L^{1}(R)} \leq\left\|u_{0}\right\|_{L^{1}}+c_{0} t\left\|u_{0}\right\|_{L^{2}}^{2}
$$

$\|u(t, \cdot)\|_{B V}, \quad\|u(t, x)\|_{L^{\infty}} \leq c_{0}\left(\left|u_{0}\right|_{B V(R)}+t\left\|u_{0}\right\|_{L^{2}(R)}^{2}\right)$,

$$
\begin{align*}
\left\|u_{\varepsilon}(t, \cdot)\right\|_{L^{2 N}(R)} \leq & c_{0}\left(1+\left\|u_{0}\right\|_{L^{2}}^{2}\right)^{2} t \\
& +\|u(0, \cdot)\|_{L^{2 N}(R)}^{2 N} e^{c_{0}\left(1+\left\|u_{0}\right\|_{L^{2}}^{2}\right)^{2} t} \tag{59}
\end{align*}
$$

where $c_{0}$ is a positive constant independent of t and $\varepsilon$.
The following Oleinik type estimate holds for a.e. $(t, x) \in$ $(0, T] \times R$ :

$$
\begin{equation*}
\partial_{x} u(t, x) \leq \frac{1}{t}+K_{T} \tag{60}
\end{equation*}
$$

where

$$
\begin{align*}
K_{T}=c_{0}\{ & \left\{u_{0} \|_{L^{2}(R)}^{2}\right. \\
& \left.+\left(\left\|u_{0}\right\|_{B V(R)}+T\left\|u_{0}\right\|_{L^{2}(R)}^{2}\right)^{2}\right\}^{1 / 2} . \tag{61}
\end{align*}
$$

This theorem is an immediate consequence of Theorem 13 and results are presented in Section 2.

Theorem 13 (existence). Assume that $u_{0} \in L^{1}(R) \cap L^{2}(R) \cap$ $B V(R)$ and the solution $u(t, x)$ satisfies (57). Then, there exists at least one weak solution to problem (6).

Proof. Using the estimates obtained in Section 2, we take a standard argument to see that there exists a sequence of strictly positive numbers $\left\{\varepsilon_{k}\right\}_{k=1}^{\infty}$ tending to zero such that as $k \rightarrow \infty$

$$
\begin{gather*}
u_{\varepsilon_{k}} \longrightarrow u \quad \text { a.e. in } R_{+} \times R \\
u_{\varepsilon_{k}} \longrightarrow u \quad \text { in } L_{\mathrm{loc}}^{1}\left(R_{+} \times R\right) . \tag{62}
\end{gather*}
$$

The previous estimates in Section 2 imply immediately that the limit function $u$ satisfies (59)-(60).

Let us now prove that as $k \rightarrow \infty$

$$
\begin{equation*}
P_{\varepsilon_{k}} \longrightarrow P^{u}, \quad \partial_{x} P_{\varepsilon_{k}} \longrightarrow \partial_{x} P^{u} \quad \text { in } L^{1}((0, T) \times R) \quad \forall T>0 \tag{63}
\end{equation*}
$$

which follows from the following calculations:

$$
\begin{aligned}
& \left\|P_{\varepsilon_{k}}-P^{u}\right\|_{L^{1}((0, T) \times R)} \\
& \leq\left(\frac{|m-1|}{4}\right) \\
& \times \int_{0}^{T} \int_{R}\left(\int_{R} e^{-|x-y|}\right. \\
& \left.\times\left|\left(u_{\varepsilon_{k}}(t, y)\right)^{2}-(u(t, y))^{2}\right| d y\right) d x d t \\
& \leq\left(\frac{|m-1|}{2}\right) \int_{0}^{T}\left(\int_{R}\left|u_{\varepsilon_{k}}(t, y)-u(t, y)\right|\right. \\
& \left.\times\left|u_{\varepsilon_{k}}(t, y)+u(t, y)\right| d y\right) d t \\
& \leq C_{T} \int_{0}^{T} \int_{R}\left|u_{\varepsilon_{k}}(t, y)-(u(t, y))\right| d y d t \longrightarrow 0 \\
& \text { as } k \longrightarrow \infty \text {, } \\
& \left\|\partial_{x} P_{\varepsilon_{k}}-\partial_{x} P^{u}\right\|_{L^{1}\left((0, T)^{1} \times R\right)} \\
& \leq\left(\frac{|m-1|}{4}\right) \\
& \times \int_{0}^{T} \int_{R}\left(\int_{R} e^{-|x-y|}\right. \\
& \left.\times\left|\left(u_{\varepsilon_{k}}(t, y)\right)^{2}-(u(t, y))^{2}\right| d y\right) d x d t
\end{aligned}
$$

$$
\begin{align*}
& \leq\left(\frac{|m-1|}{2}\right) \int_{0}^{T}\left(\int_{R}\left|u_{\varepsilon_{k}}(t, y)-u(t, y)\right|\right. \\
& \left.\times\left|u_{\varepsilon_{k}}(t, y)+u(t, y)\right| d y\right) d t \\
& \leq C_{T} \int_{0}^{T} \int_{R}\left|u_{\varepsilon_{k}}(t, y)-(u(t, y))\right| d y d t \longrightarrow 0 \\
& \text { as } k \longrightarrow \infty . \tag{64}
\end{align*}
$$

From (62) to (64), we complete the proof.

## Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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