

Corrigendum

Corrigendum to “Adaptive Nonlinear Tire-Road Friction Force Estimation for Vehicular Systems Based on a Novel Differentiable Friction Model”

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In the paper titled “Adaptive Nonlinear Tire-Road Friction Force Estimation for Vehicular Systems Based on a Novel Differentiable Friction Model” [1], there are two spelling mistakes in the paper as follows:

- (1) F_{-rf} in equation (2) and equation (3) should be F_{-d} .
- (2) $+F_d$ in equation (4) should be $-F_{-rf}$.

References

- [1] Z.-J. Fu, W.-D. Xie, and X.-B. Ning, “Adaptive nonlinear tire-road friction force estimation for vehicular systems based on a novel differentiable friction mode,” *Mathematical Problems in Engineering*, vol. 2015, Article ID 201062, 7 pages, 2015.



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