

Corrigendum

Corrigendum to “Observer-Based Sliding Mode Control for Stabilization of a Dynamic System with Delayed Output Feedback”

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In the article titled “Observer-Based Sliding Mode Control for Stabilization of a Dynamic System with Delayed Output Feedback” [1] the order of the first and second affiliations was incorrect. The correct order of affiliations is shown above.

References

- [1] B. Wang, P. Shi, H. R. Karimi, and C. Lim, “Observer-based sliding mode control for stabilization of a dynamic system with delayed output feedback,” *Mathematical Problems in Engineering*, vol. 2013, Article ID 537414, 6 pages, 2013.

