Exact Traveling Wave Solutions of the Gardner Equation by the Improved $\tan(\Theta(\vartheta))$-Expansion Method and the Wave Ansatz Method

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Nonlinear partial differential equations (NLPDEs) are an inevitable mathematical tool to explore a large variety of engineering and physical phenomena. Due to this importance, many mathematical approaches have been established to seek their traveling wave solutions. In this study, the researchers examine the Gardner equation via two well-known analytical approaches, namely, the improved $\tan(\Theta(\vartheta))$-expansion method and the wave ansatz method. We derive the exact bright, dark, singular, and $W$-shaped soliton solutions of the Gardner equation. One can see that the methods are relatively easy and efficient to use. To better understand the characteristics of the theoretical results, several numerical simulations are carried out.

1. Introduction

The Gardner equation is given as [1–3]

$$u_t + 2\alpha uu_x + 3\beta u_x^2 u_x + \gamma u_{xxx} = 0, \quad (1)$$

where $\alpha$, $\beta$, and $(\gamma > 0)$ are constant values. If the coefficient $\beta > 0$, equation (1) admits two families of solitons and oscillating wave packets (called breathers), whereas if $\beta < 0$, only one category of solitons exists [4].

Equation (1) is also called the combined KdV-mKdV equation. In recent years, partial differential equations have become one of the most widely used fields of mathematics in various branches of science and engineering [5–12]. In this paper, the Gardner equation is examined by using the improved $\tan(\Theta(\vartheta))$-expansion method and the wave ansatz method. Recently, the improved $\tan(\Theta(\vartheta))$-expansion method (ITEM) [13–16] and the wave ansatz method [17–21] have been exploited to integrate a variety of nonlinear partial differential evolution equations (NLPDEs). In the past, several years ago, various methods have been proposed to obtain the solitary solution of this equation. In [22, 23], some kind of solutions of equation (1) were obtained. The Gardner equation (1) for $\alpha > 0$, $\beta < 0$, and $\gamma = 0$ has been studied in [24]. In [25], the authors have studied the attitudes of some solitary solitons for this equation. Many powerful analytic solution methods for solving nonlinear equation (1) have appeared in the open literature, such as the Hirota bilinear method [26], mapping method [25], similarity transformation method [27], generalized exponential rational function method, Jacobi elliptical solution finder method [28], fractional homotopy perturbation transform method [29], Coffey’s series expansion method [30], a unified method including solitary wave solutions, triangular periodic solutions, and Jacobi periodic wave solutions, as well as rational solutions [23], Wadati’s inverse scattering transform and Hirota methods [31, 32], consistent Riccati expansion (CRE) [33], planar dynamical systems approach method [34], Kudryashov method [35], Lie symmetry group method [36], ill-posedness results [37], classification of single traveling wave solutions [38], spectral collocation method [5], the Gardner equation with time-dependent coefficients and forcing term, have been investigated in [39, 40]. For more methods, we refer the readers to [22–40] and the references therein.
This paper consists of several sections. In Section 2, a brief description of the improved \( \tan(\Theta(\varphi)) \)-expansion method is reviewed. With the aid of this method, we will retrieve several sets of solutions for the Gardner equation in Section 3. In Section 4, the method of wave ansatz method is considered and the corresponding solutions in terms of bright, dark, singular, and \( W \)-shaped soliton solutions. Furthermore, some 3D profiles of acquired solutions are also depicted in this section. However, to the best of the authors' knowledge, these two approaches have not been applied for equation (1) in previous studies. Finally, Section 5 concludes the paper.

### 2. The Improved \( \tan(\Theta(\varphi)) \)-Expansion Method

In this section, the main algorithm of the improved \( \tan(\Theta(\varphi)) \)-expansion method (ITEM) is explained as follows:

Step 1: using a new definition of wave variable \( \Theta = \mu x - \Theta t \), a general partial differential equation (PDE) such as

\[
\mathcal{N}(u, u_x, u_t, u_{xx}, \ldots) = 0
\]  

(2)

is transformed into an ordinary differential equation (ODE)

\[
\mathcal{N}(u, u', -\mu u', u'', \mu^2 u'', \ldots) = 0.
\]  

(3)

Step 2: suppose that

\[
u(\Theta) = \sum_{k=0}^{m} A_k \left[ p + \tan \left( \frac{\Theta(\varphi)}{2} \right) \right]^k + \sum_{k=1}^{m} B_k \left[ p + \tan \left( \frac{\Theta(\varphi)}{2} \right) \right]^{-k}
\]

(4)

could be constructed as a solution of equation (2), where \( (A_k (0 \leq k \leq m)) \) and \( (B_k (1 \leq k \leq m)) \) with \( A_m \neq 0, B_m \neq 0 \) are unknown parameters, so that \( \Theta = \Theta(\varphi) \) satisfies

\[
\Theta' (\varphi) = a \sin (\Theta) + b \cos (\Theta) + c.
\]

(5)

Taking (5) into account, some solutions are as follows:

Category 1: while \( (a^2 + b^2 - c^2 < 0) \) and \( b-c \neq 0 \), then

\[
\Theta (\varphi) = -2 \tan^{-1} \left[ \frac{a}{b-c} + \frac{\sqrt{c^2 - a^2 - b^2}}{b-c} \right] 
\cdot \tan \left( \frac{\sqrt{c^2 - a^2 - b^2}}{2} (\theta + C) \right).
\]

(6)

Category 2: while \( a^2 + b^2 - c^2 > 0 \) and \( b - c \neq 0 \), then

\[
\Theta (\varphi) = 2 \tan^{-1} \left[ \frac{a}{b} + \frac{\sqrt{b^2 + a^2 - c^2}}{b} \tan \left( \frac{\sqrt{b^2 + a^2 - c^2}}{2} (\theta + C) \right) \right].
\]

(7)

Category 3: while \( (a^2 + b^2 - c^2 > 0) \), \( b \neq 0 \), and \( c = 0 \), then

\[
\Theta (\varphi) = 2 \tan^{-1} \left[ \frac{a}{b} + \frac{\sqrt{b^2 + a^2}}{b} \tan \left( \frac{\sqrt{b^2 + a^2}}{2} (\theta + C) \right) \right].
\]

(8)

Category 4: while \( (a^2 + b^2 - c^2 < 0) \), \( c \neq 0 \), and \( b = 0 \), then

\[
\Theta (\varphi) = 2 \tan^{-1} \left[ \frac{a}{c} + \frac{\sqrt{c^2 - a^2}}{c} \tan \left( \frac{\sqrt{c^2 - a^2}}{2} (\theta + C) \right) \right].
\]

(9)

Category 5: while \( (a^2 + b^2 - c^2 > 0) \), \( b - c \neq 0 \) and \( a = 0 \), then

\[
\Theta (\varphi) = 2 \tan^{-1} \left[ \frac{b + c}{b-c} \tan \left( \frac{\sqrt{b^2 - c^2}}{2} (\theta + C) \right) \right].
\]

(10)

Category 6: while \( a = 0 \) and \( c = 0 \), it resulted that

\[
\Theta (\varphi) = \tan^{-1} \left[ \frac{2 e^{2b (\theta + C)} - 1}{e^{2b (\theta + C)} + 1} \right].
\]

(11)

Category 7: while \( b = 0 \) and \( c = 0 \), it resulted that

\[
\Theta (\varphi) = \tan^{-1} \left[ \frac{2 e^{2a (\theta + C)} - 1}{e^{2a (\theta + C)} + 1} \right].
\]

(12)

Category 8: while \( a^2 + b^2 = c^2 \), it resulted that

\[
\Theta (\varphi) = \tan^{-1} \left[ \frac{(b + c) (a (\theta + C) + 2)}{a^2 (\theta + C)} \right].
\]

(13)

Category 9: while \( a = b = c = \kappa \), it resulted that

\[
\Theta (\varphi) = 2 \tan^{-1} \left[ e^{b (\theta + C)} - 1 \right].
\]

(14)

Category 10: while \( a = c = \kappa \) and \( b = -\kappa \), it resulted that

\[
\Theta (\varphi) = -2 \tan^{-1} \left[ \frac{e^{b (\theta + C)}}{-1 + e^{2b (\theta + C)}} \right].
\]

(15)

Category 11: while \( c = a \), it resulted that

\[
\Theta (\varphi) = -2 \tan^{-1} \left[ \frac{(a + b) e^{b (\theta + C)} - 1}{(a - b) e^{b (\theta + C)} - 1} \right].
\]

(16)
Category 12: while \(a = c\), it resulted that
\[
\Theta(\vartheta) = 2\tan^{-1}\left(\frac{(b + c)e^{(b+c)\vartheta} + 1}{(b - c)e^{(b+c)\vartheta} - 1}\right). \tag{17}
\]

Category 13: while \(c = -a\), it resulted that
\[
\Theta(\vartheta) = 2\tan^{-1}\left(\frac{b + a}{e^{(b+c)\vartheta} - b - a}\right). \tag{18}
\]

Category 14: while \(b = -c\), it resulted that
\[
\Theta(\vartheta) = -2\tan^{-1}\left(\frac{\alpha e^{(b+c)\vartheta} - c}{e^{(b+c)\vartheta} - 1}\right). \tag{19}
\]

Category 15: while \(b = 0\) and \(a = c\), it resulted that
\[
\Theta(\vartheta) = -2\tan^{-1}\left(\frac{c (\vartheta + C) + 2}{c (\vartheta + C)}\right). \tag{20}
\]

Category 16: while \(a = 0\) and \(b = c\), it resulted that
\[
\Theta(\vartheta) = 2\tan^{-1}[c (\vartheta + C)]. \tag{21}
\]

Category 17: while \(a = 0\) and \(b = -c\), it resulted that
\[
\Theta(\vartheta) = -2\tan^{-1}\left(\frac{1}{c (\vartheta + C)}\right). \tag{22}
\]

Category 18: while \(a = 0\) and \(b = 0\), it resulted that
\[
\Theta(\vartheta) = c\vartheta + C. \tag{23}
\]

Category 19: while \(b = c\), it resulted that
\[
\Theta(\vartheta) = 2\tan^{-1}\left(\frac{e^{a(b+c)\vartheta} - c}{a}\right), \tag{24}
\]

where \((A_k, B_k, k = 1, 2, \ldots, m), a, b\) and \(c\) are the unknown parameters that need to be calculated. To determine the natural number \(m\), one can use the homogeneous balance rule.

Step 3: inserting the formal scheme of (4) into equation (3), and then setting each coefficient of \(\tan ((\Theta(\vartheta))/2)^k, \cot ((\Theta(\vartheta))/2)^k, (k = 0, 1, 2, \ldots)\) to zero, we will arrive to a set of nonlinear equations for \((A_0, A_1, B_0, k = 1, 2, \ldots, m), a, b, c, \mu, \vartheta\) and \(p\).

Step 4: solving the algebraic equations in Step 3, it resulted that substituting \((A_0, A_1, B_1, \ldots, A_m, B_m, \mu, \vartheta, p)\) in (4).

3. Applications of the Gardner Equation via ITEM

In this section, we will examine ITEM for equation (1). To find the traveling solutions for equation (1), we define the wave transformation as \(u = U(\vartheta)\), where \(\vartheta = \mu x - \vartheta t, \mu \neq 0\), and \(\vartheta \neq 0\) to be determined later. Taking \(u = u(\vartheta)\) into account allows us to rewrite equation (1) as the following ordinary differential equation:
\[
-\theta u' + 2\alpha uu' + 3\beta uu'' + \gamma u''' = 0. \tag{25}
\]

Integrating (25) once with respect to \(\vartheta\) and neglecting the resulted integration constants, we obtain
\[
-\theta u + \alpha uu' + \beta uu^2 + \gamma uu'' = 0. \tag{26}
\]

Now, we apply the ITEM to obtain traveling wave solutions of the Gardner equation (1). According to this method, the solution of equation (26) can be written in the form of equation (4).

Balancing the \(u''\) and \(u'''\) in (26), by using homogeneous, one has
\[
3m = m + 2 \implies m = 1. \tag{27}
\]

Taking \(p = 0\) in (27), the solution structure is formulated as
\[
u(\vartheta) = A_0 + A_1 \left[\tan \left(\frac{\Theta(\vartheta)}{2}\right)\right] + B_1 \left[\cot \left(\frac{\Theta(\vartheta)}{2}\right)\right]. \tag{28}
\]

Substituting equation (28) into equation (26) and following the necessary steps of ITEM, we have the following sets of coefficients for the nontrivial solutions of (1) as follows:

Set 1:
\begin{align*}
\mu &= \frac{\sqrt{2}a}{3\sqrt{-a\beta\sqrt{a^2 + b^2 - c^2}}}, \\
\vartheta &= \frac{2a^3\sqrt{2}}{27\beta\sqrt{-a\beta\sqrt{a^2 + b^2 - c^2}}}, \\
A_0 &= \frac{a}{3\beta} \left[1 + a\sqrt{b^2 + a^2 - c^2}\right], \\
A_1 &= \frac{a}{3\beta} \left[\frac{b - c}{\sqrt{b^2 + a^2 - c^2}}\right], \\
B_1 &= 0,
\end{align*}
\]

where \(a, b, c\) are optional constants, and
\[
\vartheta = \frac{-\sqrt{2}a}{3\sqrt{-\beta\sqrt{b^2 + a^2 - c^2}}} x - \frac{2\sqrt{2}a^3}{27\beta\sqrt{-\beta\sqrt{b^2 + a^2 - c^2}}} t, \tag{32}
\]

provided that \(\beta < 0\).

Setting these values in categories 2, 6, 10, and 14 of Section 2, respectively, we acquire the following solutions:
\[ u_1(\theta) = \frac{\alpha}{3\beta} \left( \tanh \left( \frac{\sqrt{a^2 + b^2 - c^2}}{2} \theta - 1 \right) \right), \]  

where \( a^2 + b^2 - c^2 > 0 \) and \( \theta \) is given by (32).

\[ u_2(\theta) = -\frac{\alpha}{3\beta} \left[ 1 + \tan \left( 12 \left( \frac{e^{2\beta\theta} - 1}{e^{2\beta\theta} + 1} \right) \right) \right], \]  

where \( \theta = -\left( \frac{\sqrt{2} a}{3b\sqrt{-\beta Y}} \right) x - \left( \frac{(2\sqrt{2} a^3)}{(27\beta\sqrt{-\beta Y})} \right) t. \)

\[ \theta = -\left( \frac{\sqrt{2} a}{3b\sqrt{-\beta Y}} \right) x - \left( \frac{(2\sqrt{2} a^3)}{(27\beta\sqrt{-\beta Y})} \right) t. \]

\[ u_3(\theta) = -\frac{2\alpha}{3\beta} \frac{c e^{\beta\theta}}{c e^{\theta} - 1}, \]  

where \( \theta = -\left( \frac{\sqrt{2} a}{3b\sqrt{-\beta Y}} \right) x - \left( \frac{(2\sqrt{2} a^3)}{(27\beta\sqrt{-\beta Y})} \right) t. \)

Set 2:

\[ \mu = \frac{\sqrt{2}a}{3\sqrt{-\beta Y} \sqrt{a^2 + b^2 - c^2}}, \]  

\[ \theta = \frac{2a^3 \sqrt{2}}{27\beta \sqrt{-\beta Y} \sqrt{a^2 + b^2 - c^2}}, \]  

\[ A_0 = -\frac{\alpha}{3\beta} \left( 1 + a \sqrt{\frac{b^2 + a^2 - c^2}{b^2 + a^2}} \right), \]  

\[ A_1 = 0, \]  

\[ B_1 = -\frac{\alpha}{3\beta} \frac{b + c}{\sqrt{b^2 + a^2 - c^2}}, \]  

\[ u(\theta) = A_0 + B_1 \left[ \cot \left( \frac{\Theta(\theta)}{2} \right) \right], \]  

where \( a, b, \) and \( c \) are optional constants, and

\[ \Theta(\theta) = -\frac{\sqrt{2}a}{3\sqrt{-\beta Y} \sqrt{b^2 + a^2 - c^2}} x - \frac{2\sqrt{2}a^3}{27\beta \sqrt{-\beta Y} \sqrt{b^2 + a^2 - c^2}} t, \]  

provided that \( \beta < 0. \)

Setting these values in categories 3, 5, and 6 of Section 2, respectively, we obtain

\[ u_4(\theta) = -\frac{\alpha}{3\beta} \left( 1 + \tanh \left( \frac{\sqrt{a^2 + b^2}}{2} \theta \right) \right) \left( \frac{\sqrt{a^2 + b^2} + a}{a + \sqrt{a^2 + b^2} \tanh \left( \frac{\sqrt{a^2 + b^2}}{2} \theta \right)} \right), \]  

where \( \theta = -\left( \frac{\sqrt{2} a}{3\sqrt{-\beta Y} \sqrt{a^2 + b^2}} \right) x - \left( \frac{(2\sqrt{2} a^3)}{(27\beta\sqrt{-\beta Y} \sqrt{a^2 + b^2})} \right) t. \)

\[ u_5(\theta) = -\frac{\alpha}{3\beta} \frac{\tanh \left( \frac{\sqrt{b^2 - c^2}}{2} \theta \right)}{\tanh \left( \frac{\sqrt{b^2 - c^2}}{2} \theta \right)}, \]  

where \( b^2 - c^2 > 0 \) and \( \theta = -\left( \frac{\sqrt{2} a}{3\sqrt{-\beta Y} \sqrt{b^2 - c^2}} \right) x - \left( \frac{(2\sqrt{2} a^3)}{(27\beta\sqrt{-\beta Y} \sqrt{b^2 - c^2})} \right) t.

\[ u_6(\theta) = -\frac{\alpha}{3\beta} \frac{\tan \left( 12 \left( \frac{e^{2\beta\theta} - 1}{e^{2\beta\theta} + 1} \right) \right)}{\tan \left( 12 \left( \frac{e^{2\beta\theta} - 1}{e^{2\beta\theta} + 1} \right) \right)}, \]  

where \( \theta = -\left( \frac{\sqrt{2} a}{3b\sqrt{-\beta Y}} \right) x - \left( \frac{(2\sqrt{2} a^3)}{27\beta\sqrt{-\beta Y}} \right) t. \)

Set 3:

\[ a = c = 0, \]  

\[ \mu = -\frac{\sqrt{3} \alpha}{6b\sqrt{-\gamma \beta}}, \]  

\[ \theta = -\frac{\sqrt{2} \alpha^3}{27\beta \sqrt{-\gamma \beta}} \]  

\[ A_0 = -\frac{\alpha}{3\beta}, \]  

\[ A_1 = \frac{\alpha}{6\beta}, \]  

\[ B_1 = -\frac{\alpha}{6\beta}, \]  

\[ u(\theta) = A_0 + A_1 \tan \left( \frac{\Theta(\theta)}{2} \right) + B_1 \cot \left( \frac{\Theta(\theta)}{2} \right), \]  

where \( b \) is an optional and \( \beta < 0 \) must be held.

Setting these values in categories 1, 6, and 13 of Section 2, respectively, we obtain

\[ u_7 = -\frac{\alpha}{6\beta} \frac{\left( \tanh \left( \frac{b(2\theta)}{2} \right) + 1 \right)^2}{\tanh \left( \frac{b(2\theta)}{2} \right)}, \]  

\[ u_8 = -\frac{\alpha}{6\beta} \frac{\left( \tanh \left( \frac{12 \tan^{-1} \left( \left( e^{2\beta \theta} - 1 \right) \left( e^{2\beta \theta} + 1 \right) \right) + 1 \right)^2 \tan \left( 12 \tan^{-1} \left( \left( e^{2\beta \theta} - 1 \right) \left( e^{2\beta \theta} + 1 \right) \right) + 1 \right) \right)}{\tan \left( 12 \tan^{-1} \left( \left( e^{2\beta \theta} - 1 \right) \left( e^{2\beta \theta} + 1 \right) \right) + 1 \right) + 1} \right)^2 \]  

\[ u_9 = -\frac{\alpha}{3\beta} \frac{e^{2b\theta}}{e^{2b\theta} - b^2}, \]  

where

\[ \theta = -\frac{\sqrt{2} \alpha}{6b\sqrt{-\beta \gamma}} + \frac{\sqrt{2} \alpha^3}{27b\sqrt{-\beta \gamma}} t. \]
It is worth to note that one can find some more new exact solitary solutions from solutions (31), (38), and (45).

4. Applications of the Wave Ansatz Method

In what follows, and based on the wave ansatz method, several types of soliton wave solutions for the Gardner equation (1) are presented which is based on the wave ansatz method (see the previous study [24]).

4.1. Bright Soliton. To retrieve bright optical solutions of the Gardner equation, we use the following scheme [41]:

\[
 u(x, t) = \frac{A}{(D + \cosh \tau)^{m}},
\]

(48)

where

\[
 \tau = B(x - \nu t),
\]

(49)

where \(A, B,\) and \(\nu\) are disposal parameters.

Putting these values of (48) into (1) and some calculations, one obtains

\[
 - \frac{3\beta A^3 nB \sinh \tau}{(D + \cosh \tau)^{3m+1}} - \frac{2\alpha A^2 nB \sinh \tau}{(D + \cosh \tau)^{2m+1}} - \frac{AB\gamma n(n+2)(n+1)(D^2 - 1) \sinh \tau}{(D + \cosh \tau)^{m+1}} - \frac{AB\gamma n(n+2)(2n+1) \sinh \tau}{(D + \cosh \tau)^{m+2}} - \frac{ABn\gamma n^2 \gamma n^2 - \nu) \sinh \tau}{(D + \cosh \tau)^{m+1}} = 0.
\]

(50)

From (50), equating the exponents \(3n + 1\) and \(n + 3\) yields

\[
 n = 1.
\]

(51)

So, solving equation (50) turns to the following equation:

\[
 - \frac{AB\gamma n^2 \gamma n^2 - \nu) \sinh \tau}{(D + \cosh \tau)^{m+1}} = 0.
\]

(52)

Due to the fact that the functions \(1/(D + \cosh \tau)^{j}\) for \(j = 2, 3,\) and \(4\) are linearly independent, equation (52) will introduce a system of equations for the unknown parameters. Solving this system, one gets

\[
 \nu = \gamma B^2,
\]

(53)

\[
 A = \frac{3\gamma B^2 D}{\alpha},
\]

(54)

\[
 D = \frac{2\alpha}{\sqrt{18\beta \gamma B^2 + 4\alpha^2}}.
\]

(55)

Putting (55) into (54) yields

\[
 A = \frac{6\gamma B^2}{\sqrt{18\beta \gamma B^2 + 4\alpha^2}}.
\]

(56)

Thus, for an arbitrary constant \(B,\) the 1-soliton solution of (1) is given by

\[
 u(x, t) = \frac{6\gamma B^2}{2\alpha + \sqrt{18\beta \gamma B^2 + 4\alpha^2} \cosh(Bx - \gamma B^3 t)},
\]

(57)

provided

\[
 9 B^2 \beta \gamma + 2 \alpha^2 > 0.
\]

(58)

4.2. Dark Soliton. To retrieve dark solutions of the equation, we use the structure [41]

\[
 u(x, t) = (A + B \tanh \tau)^n,
\]

(59)

where

\[
 \tau = \mu(x - \nu t),
\]

(60)

where \(A, B, \mu,\) and \(\nu\) are unknown parameters.

Inserting (59) into (1) gives

\[
 - \frac{AB\gamma n^2 \gamma n^2 - \nu) \sinh \tau}{(D + \cosh \tau)^{m+1}} = 0.
\]
\[
- \left[ \frac{3 \beta n u}{B} \right] (A + B \tanh t)^{3n+1} + \left[ \frac{6 \beta n u A}{B} \right] (A + B \tanh t)^{3n} - \left[ \frac{3 \beta n (B^2 - A^2)}{B} \right] \\
\cdot (A + B \tanh t)^{3n-1} - \left[ \frac{2 \alpha n u}{B} \right] (A + B \tanh t)^{2n+1} \\
+ \left[ \frac{2 \alpha n u A}{B} \right] (A + B \tanh t)^{2n} - \left[ \frac{2 \alpha n (A^2 - B^2)}{B} \right] (A + B \tanh t)^{2n-1} - \left[ \frac{\gamma n (n + 2)(n + 1)}{B^3} \right] (A + B \tanh t)^{n+3} \\
+ \left[ \frac{6 \gamma n \mu^3 A(n + 1)^2}{B^3} \right] (A + B \tanh t)^{n+2} - \left[ \frac{\mu n (3 \gamma \mu^2 n(5 A^2 - B^2)(n + 1) + 2 \gamma \mu^2 (3 A^2 - B^2) - B^2)}{B^3} \right] (A + B \tanh t)^{n+1} \\
+ \left[ \frac{2 A \mu n (2 \gamma \mu^2 n(5 A^2 - 3 B^2) + 2 \gamma \mu^2 (A^2 - B^2) - B^2)}{B^3} \right] \\
\cdot (A + B \tanh t)^n - \left[ \frac{\mu n (A^2 - B^2)(5 A^2 - 3 B^2)(n - 1) + 2 \gamma \mu^2 (3 A^2 - B^2) - B^2)}{B^3} \right] (A + B \tanh t)^{n-1} \\
+ \left[ \frac{6 \gamma n \mu^3 A(n - 1)^2(3 A^2 - B^2)}{B^3} \right] (A + B \tanh t)^{n-2} - \left[ \frac{\gamma n (n - 1)(n - 2)(A^2 - B^2)}{B^3} \right] (A + B \tanh t)^{n-3} = 0. \\
\]

After some algebra, we conclude that
\[
\mu = \sqrt{-2} \frac{\gamma B}{\gamma}, \quad (62)
\]
\[
\gamma = \frac{3 B^2 \beta^2 - \alpha^2}{3 \beta}, \quad (63)
\]
\[
A = -\frac{\alpha}{3 \beta}, \quad (64)
\]

The dark soliton solution of equation (1) is obtained as
\[
u(x, t) = (A + B \tanh (\mu (x - vt)))^n, \quad (65)
\]
to exist, from (62), the following restriction is obtained
\[
\beta < 0. \quad (66)
\]

4.3. Singular Soliton. To extract the singular solitons of the Gardner equation (1), the following structure is examined by [41]
\[
u(x, t) = \frac{A}{(D + \sinh t)^n}, \quad (67)
\]
with \( \tau \) is defined by (49).

Substituting (67) into (1), we obtain
\[
- \frac{3 \beta A^3 n B \cosh \tau}{(D + \sinh t)^{3n+1}} - \frac{2 \alpha A^2 n B \cosh \tau}{(D + \sinh t)^{3n+1}} \\
- \frac{A B^3 \gamma n (n + 2)(n + 1)(D^2 + 1) \cosh \tau}{(D + \sinh t)^{n+3}} \\
+ \frac{A B^3 D \gamma n (n + 1)(2 n + 1) \cosh \tau}{(D + \sinh t)^{n+1}} - \frac{A B \mu (B^2 \gamma n^2 - \gamma) \cosh \tau}{(D + \sinh t)^{n+1}} = 0. \quad (68)
\]

Considering the balancing principle indicates (51), vanishing all the coefficients of \( (\cosh \tau / [D + \sinh t])^j \) for \( j = 2, 3, \) and 4 to zero in (68), one gets
\[
\nu = B \gamma, \quad (69)
\]
\[
A = \frac{6 B^2 \gamma}{\sqrt{-18 B^2 \beta \gamma - 4 \alpha^2}}, \quad (70)
\]
\[
D = \frac{2 \alpha}{\sqrt{-18 B^2 \beta \gamma - 4 \alpha^2}}. \quad (71)
\]

From (70) and (71), one concludes that if
\[
9 B^2 \beta \gamma + 2 \alpha^2 < 0 \quad (72)
\]
holds, the soliton solution
u(x,t) = \frac{A}{D + \sinh(Bx - B^3 ct)}

(73)

is achieved as a singular solution for the Gardner equation (1). In this solution, A is given by (70), D is shown in (71), and B is an optional constant chosen in such a way that (72) holds.

4.4. W-Shaped Soliton. Now, we explore some exact solutions of the Gardner equation in the form of [41]

\[ u(x,t) = A + D \sech(\tau) \]

(74)

where \( \tau \) is the same as (49).

Substituting (74) into (1), we, respectively, obtain

\[-BD \sech(\tau) \tanh(\tau) \left[ -6B^2 \gamma + 3D^2 \beta \right] \sech^2(\tau) + (6A D \beta + 2D \alpha) \sech(\tau) + 3A^2 \beta + B^3 \gamma + 2A \alpha - \gamma \] = 0.

(75)

Now, equation (75) holds whenever we have

\[ \gamma = \frac{3B^2 \beta \gamma - \alpha^2}{3\beta} \]

(76)

\[ A = -\frac{\alpha}{3\beta} \]

(77)

\[ D = \pm B \sqrt{\frac{2\gamma}{\beta}} \]

(78)

which will be valid for

\[ \beta < 0. \]

(79)

Consequently, the solution (74) with sign “+” in equation (78) is obtained as

\[ u(x,t) = -\frac{\alpha}{3\beta} + B \sqrt{\frac{2\gamma}{\beta}} \sech\left( Bx - \frac{3B^3 \beta \gamma - B \alpha^2}{3\beta} t \right) \]

(80)

Moreover, for bright soliton pulse and with sign “-” in equation (78), we obtain
The correctness of all given solutions has been confirmed with Maple by substituting them back into the original equation. To better understand the characteristics of the soliton solution, we plot equations (57), (65), (73) (80), and (81) of equation (1) by taking different values of parameters $\alpha, \beta,$ and $y$ within the interval $(x, t) \in [-10, 10] \times [-10, 10]$ in Figures 1–7, respectively.

5. Concluding Remarks and Observations

In this research, we exerted the improved tan$(\Theta (\varphi))$-expansion and wave ansatz method as two useful mathematical tools to construct solitary solutions for the Gardner equation. These two methods for equation (1) have not been reported in the literature so far, to achieve the category of bright, dark, singular, and W-shaped soliton solutions. For a better understanding of the solutions, numerical results have also been included. On the other hand, the results are quite reliable for solving the Gardner equation. The results attest to the efficiency of the proposed method. These two powerful methods can also be applied to other nonlinear partial differential equations with time-dependent coefficients and their systems.

Data Availability

No data were used to support this study.

Conflicts of Interest

The authors declare that they have no conflicts of interest.

References


