Corrigendum

Corrigendum to “An Optimized RBF Neural Network Based on Beetle Antennae Search Algorithm for Modeling the Static Friction in a Robotic Manipulator Joint”

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In the article titled “An Optimized RBF Neural Network Based on Beetle Antennae Search Algorithm for Modeling the Static Friction in a Robotic Manipulator Joint” [1], the 1st affiliation should be changed from “School of Mechanical Engineering, Zhejiang University, Hangzhou 310000, China” to the correct affiliation “State Key Laboratory of Fluid Power and Mechatronics Systems, Zhejiang University, Hangzhou 310000, China.” The corrected affiliation is shown in the author information above.

References