

Research Article

Lateral Response Comparison of Unbonded Elastomeric Bearings Reinforced with Carbon Fiber Mesh and Steel

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The vertical and horizontal stiffness used in design of bearings have been established in the last few decades. At the meantime, applicability of the theoretical approach developed to estimate vertical stiffness of the fiber-reinforced bearings has been verified in different academic studies. The suitability of conventional horizontal stiffness equation developed for elastomeric material, mainly for steel-reinforced elastomeric bearings, has not been tested in detail for use of fiber-reinforced elastomeric bearings. In this research, lateral response of fiber mesh-reinforced elastomeric bearings has been determined through experimental tests and the results have been compared by corresponding values pertaining to the steel-reinforced bearings. Within the test program, eight pairs of fiber mesh-reinforced bearings and eight pairs of steel-reinforced bearings are subjected to different levels of compressive stress and cyclic shear strains. Fiber-reinforced elastomeric bearings may be more favorable to be used in seismic regions due to lower horizontal stiffness that can result in mitigation of seismic forces for levels of 100% shear strain. Damping properties of these types of fiber mesh-reinforced bearings depend mostly on the selection of elastomeric material compounds. Suggestions have been made for the lateral response of fiber-reinforced elastomeric bearings. It has also been determined that the classical equation for lateral stiffness based on linear elastic behavior assumptions developed for elastomeric bearings does not always apply to the fiber-reinforced ones.

1. Introduction

Fiber mesh-reinforced elastomeric bearings are becoming popular in the academic researches. Most of the design equations used for fiber mesh-reinforced bearings are adapted from the known elastomeric material behavior or mainly the ones developed for the steel-reinforced elastomeric bearings. Lack of a complete lateral response comparison between full size fiber-reinforced and steel-reinforced bearings and limited amount of research on lateral structural response of fiber-reinforced bearings in the known literature are the main reasons to conduct this research.

Elastomeric bearings reinforced by steel plates are the most common types of the bearings used for seismic isolation or standard bearings of the structures. In an attempt to decrease the weight and cost of these bearings, Kelly [1] introduced a certain type of fiber-reinforced elastomeric bearings

and showed that these bearings can provide adequate vertical stiffness for base isolation.

Fiber-reinforced elastomeric bearings were studied by many researchers during the past decades. Moon et al. [2] manufactured fiber-reinforced elastomeric bearings using different types of fiber reinforcement. They compared the performance of these bearings and concluded that carbon fiber-reinforced bearings have superior performance parameters. Ashkezari et al. [3] manufactured some specimens of multilayer elastomeric seismic isolators reinforced by layers of woven carbon and steel. They concluded that “steel like fiber-reinforced elastomeric isolators” (SLFREI) can be used in seismic isolation of structures. Compared to others, Toopchi-Nezhad et al. [4, 5] studied the lateral response of fiber-reinforced bearings using shake table testing method. Zhang et al. [6] studied the mechanical properties of FRP-based elastomeric isolators after manufacturing and testing

TABLE 1: Properties of steel-reinforced and fiber-reinforced bearings.

Type	a (mm)	b (mm)	R (mm)	t_c (mm)	t_r (mm)	$t_{s\text{ or }f}$ (mm)	n_r	n_s	T_r (mm)	H	Shape factor
S1y	250	400	*	5	8	2.0	7	6	50	62.00	9.28
F1y	250	400	*	5	8	0.125	7	6	50	50.75	9.28
S1z	250	400	*	*	5	2.0	7	6	35	47.00	14.85
F1z	250	400	*	*	5	0.125	7	6	35	35.75	14.85
S2y	300	300	*	5	6	2.0	7	6	40	52.00	12.08
F2y	300	300	*	5	6	0.125	7	6	40	40.75	12.08
S2z	300	300	*	*	5	2.0	7	6	35	47.00	14.50
F2z	300	300	*	*	5	0.125	7	6	35	35.75	14.50
S3y	*	*	100	*	10	2.0	4	3	40	46.00	4.75
F3y	*	*	100	*	10	0.125	4	3	40	40.38	4.75
S3z	*	*	100	*	5	2.0	10	9	50	68.00	9.50
F3z	*	*	100	*	5	0.125	10	9	50	51.13	9.50
S4y	150	150	*	*	4	1.0	12	11	48	59.00	8.75
F4y	150	150	*	*	4	0.125	12	11	48	49.38	8.75
S4z	150	150	*	*	2	1.0	20	19	40	59.00	17.50
F4z	150	150	*	*	2	0.125	20	19	40	42.38	17.50

*Not applicable.

a number of samples. Calabrese and Kelly [7] reviewed the response of fiber-reinforced bearings and compared the results of finite element analysis with the proposed theoretical approach. Russo et al. [8] studied the shear behavior of fiber-reinforced elastomeric bearings and they proposed a new expression for the horizontal stiffness of the fiber-reinforced bearings. They studied the deformed configuration of fiber-reinforced bearings under shear strains. Hedayati Dezfuli and Alam [9] probed the effect of physical and mechanical properties such as thickness and shear modulus of rubber layers on the performance of the FREIs in bonded applications. Karimzadeh Naghshineh et al. [10] compared the fundamental properties of fiber mesh-reinforced isolators with the conventional steel-reinforced isolators. Toopchi-Nezhad [11] presented two simplified analytical models for horizontal stiffness evaluation of unbonded fiber-reinforced elastomeric bearings.

Carbon fiber mesh with opening described in the study by Karimzadeh Naghshineh et al. [10] was used in this research and details of the reinforcing materials can be found in the study by Karimzadeh Naghshineh et al. [10]. Effects of fiber flexibility on vertical stiffness of the bearings have been studied by Kelly and Takhirov [12]. In previous researches, there is not any experimental study which compares the lateral stiffness of unbonded fiber- and steel-reinforced bearings. In this research, lateral response of fiber- and steel-reinforced bearings in unbonded application will be compared through investigating results of experimental program. To investigate the effect of parameters such as geometry and size on lateral response of fiber-reinforced bearings, eight pairs of fiber-reinforced bearings with different properties are manufactured. Steel-reinforced bearings are manufactured with

the same geometric and elastomeric properties used for fiber-reinforced bearings. Under these conditions, a comprehensive comparison between fiber- and steel-reinforced bearings has been made. For verification purposes, suggestions for the lateral response of fiber-reinforced bearings have been made.

It shall be noted that fiber mesh-reinforced elastomeric bearings are typically manufactured using “cold” manufacturing technique that involves applying bonding agents between layers of fiber mesh and rubber. To eliminate use of bonding agent between elastomeric materials and reinforcing material, vulcanization through high temperatures is selected as the manufacturing process that has also been used in the typical manufacturing method for steel-reinforced bearings. This type of manufacturing process was also used by Russo and Pauletta [13].

2. Materials and Methods

2.1. Test Specimens. Several samples of fiber- and steel-reinforced bearings were manufactured. In manufacturing all of these bearings, high damping natural rubber with the nominal stiffness of 60 Shore A was used. The nominal shear modulus of rubber material was $0.7 \text{ MPa} \pm 0.15 \text{ MPa}$ and the effective damping of rubber compound was around 8%. Geometrical properties of all bearings were presented in Table 1. In Table 1, the type is denoted by three characters in which the first character displays the reinforcement type (F for fiber and S for steel), the second character shows the specimen number (1, 2, 3, or 4), and the third character indicates the shape factor of specimen (z represents a higher shape factor compared to y). In the second and third columns, a is used for width

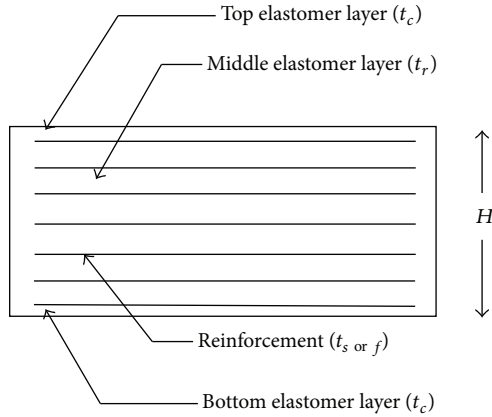


FIGURE 1: Schematic view of bearing parameters.

of the bearing and b is used for the length of the bearing. In the fourth column, R shows radius of circular bearings; in the fifth column, t_c is the thickness of top and bottom cover layers. In the sixth column, t_r is the thickness of middle elastomer layers. In the seventh column, $t_{s \text{ or } f}$ is the thickness of reinforcing steel plates or fiber reinforcement. In the eighth column, n_r is number of elastomer layers with considering the top and bottom cover layers. In the ninth column, n_s is the number of reinforcing layers. In the tenth column, T_r is the total thickness of elastomer layers. In the eleventh column, H is the total thickness of bearing with considering the reinforcement thickness. Shape factor of bearing is usually defined as the ratio of loaded area to force-free area. Figure 1 illustrates the bearings parameters in schematic manner.

2.2. Horizontal Shear Stiffness Test Setup. Seismic isolator testing system available in Structure Engineering Laboratory of Middle East Technical University has been designed to test the isolators in horizontal direction under constant vertical load. This system is capable of conducting in-plane horizontal cyclic loading tests, as shown in Figures 2(a) and 2(b). This machine can test a pair of elastomeric bearings by applying vertical pressure and keeping it constant at a desired level and then implementing cyclic displacement control loading in horizontal direction. Load capacity of testing system is about 3000 kN in vertical direction and this value reduces to 600 kN for horizontal direction.

Test setup is composed of two distinct main loading systems in horizontal and vertical directions; loading system in vertical direction is used for applying the desired level of pressure and loading system in horizontal direction is capable of controlling the applied displacement. Loading system in vertical direction with its adjustable upper plate provides testing opportunity for different type and size of bearings. Horizontal loading system is capable of sliding on rails located on vertical support plates to adjust the inserted horizontal load in accordance with the bearing's height. Also, horizontal loading system can be relocated on bottom support plates to increase the horizontal loading capacity. Two linear variable differential transformers (LVDT) placed on middle sliding plate were used to measure the horizontal

displacement of the bearing during shear test. Data acquisition system was run by a PC Windows-based control and acquisition program called StrainSmart 6000 developed by Vishay Precision Group, Wendell, USA. System 6000 features data acquisition rates of up to 10,000 samples per second per channel. It is worth noting that the average sampling rate was 100 per second in all of the tests.

2.3. Test Procedure. Bearings were tested under horizontal displacement control during the horizontal test. Bearings were subjected to shear in pairs under a vertical load equivalent to a pressure of 6.90 and 3.45 MPa. The selected compressive pressures are typical design pressures for this type of bearings. They were tested in cyclic shear, with three fully reversed cycles at three maximum strain levels of 25%, 50%, and 100% based on the total rubber thickness. Horizontal stiffness of the bearings and their equivalent viscous damping ratio were calculated by analyzing the hysteresis loops obtained during this test.

The loading history of the horizontal test for bearings is presented in Figure 3 and this figure depicts the input signal for specimens. Different seismic isolation systems have also been tested at the Middle East Technical University by Pinarbasi et al. [14], Ozkaya et al. [15], and Caner et al. [16].

Loading history of bearings affects the response of the bearings in such a way that, during the first several cycles, the bearing has higher effective horizontal stiffness and damping (scragging effect). By the third cycle, the response of the bearing has stabilized and the responses presented in this study are stabilized response of bearing.

2.4. Investigated Test Parameters for Elastomeric Bearings. Results of horizontal shear test were used to calculate the horizontal stiffness of the bearings. A simple calculation of shear stiffness based on the values of peak force and displacement is defined as

$$K_{\text{eff}}^h = \frac{|F^+| + |F^-|}{|d^+| + |d^-|}, \quad (1)$$

where d^+ and d^- are the maximum positive and maximum negative test displacements, respectively, and F^+ and F^- are the forces at instance of displacements d^+ and d^- , respectively [17]. This stiffness is interpreted as the effective or overall stiffness of the bearing during the test. This stiffness is used to calculate the stored or elastic energy of the bearings during cyclic tests.

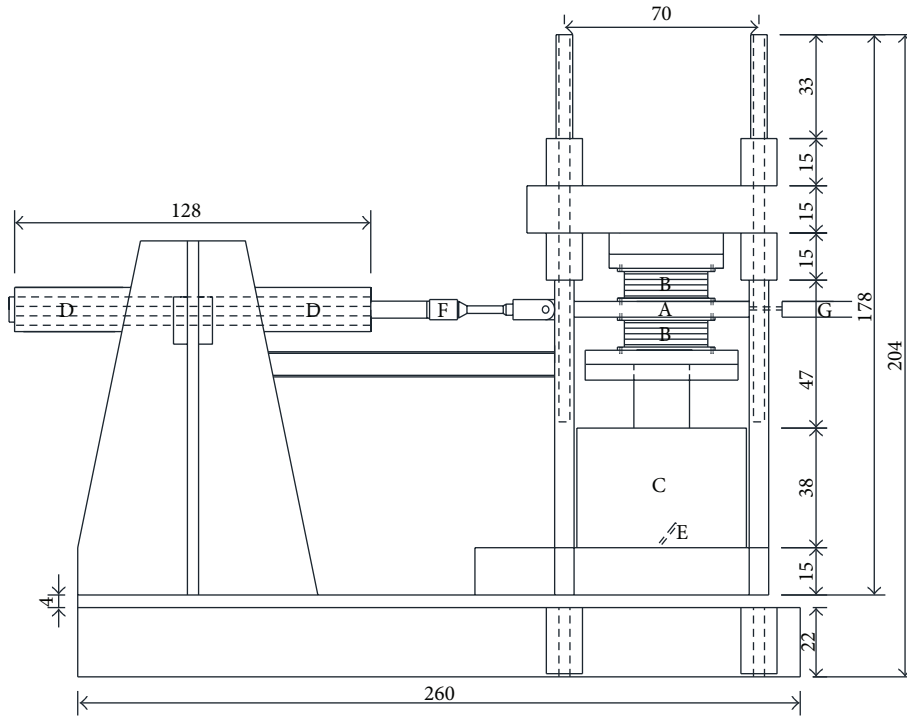
The hysteresis loops were also analyzed to obtain the equivalent viscous damping ratio of the bearing for each test. A hysteresis loop represents the plot of force against displacement, and, therefore, the area contained within such a loop represents the energy dissipated by the bearing.

The equivalent viscous damping ratio exhibited by the bearing is evaluated in the usual structural engineering fashion [18]:

$$\xi = \frac{W_d}{4\pi W_s}, \quad (2)$$



(a) Testing system



- (A) Push-pull steel plate
 (B) Bearings to be tested (two bearings are tested)
 (C) Hydraulic cylinder (for application of vertical loads)
 (D) Hydraulic cylinder (for application of horizontal loads)
 (E) Load cell in the vertical direction
 (F) Load cell in the horizontal direction
 (G) LVDT

(b) Schematic layout (dimensions: cm)

FIGURE 2: General view of the horizontal shear test equipment.

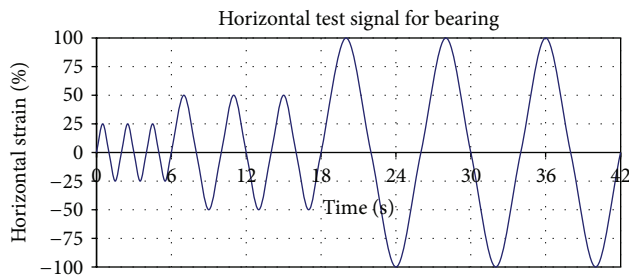


FIGURE 3: Input signal for horizontal shear test with 3.45 MPa and 6.90 MPa vertical preload.

where W_d represents a dissipated energy equal to the hysteresis loop area and W_s corresponds to stored or elastic energy defined by the following formula:

$$W_s = K_{\text{eff}} \frac{d_{\text{max}}^2}{2}. \quad (3)$$

Here, d_{max} is the average of positive and negative maximum displacements and is defined as

$$d_{\text{max}} = \frac{|d^+| + |d^-|}{2}. \quad (4)$$

TABLE 2: Equivalent viscous damping values.

Type and damp ratio	Equivalent viscous damping, $\xi\%$ under vertical pressure (MPa)							
	3.45				6.90			
	Strain level (%)				Strain level (%)			
	25	50	100	Average	25	50	100	Average
S1y	11.6	10.8	13.6	12	8.6	10	9.6	9.4
F1y	10.7	10.7	10.9	10.8	7.5	8.2	9.8	8.5
ξ_s/ξ_f	1.09	1.01	1.25	1.11	1.15	1.23	0.98	1.11
S1z	10.2	13.2	12.5	11.97	6.7	9.2	10.9	8.93
F1z	13.4	16.6	15.0	15.0	7.4	12.1	13.2	10.9
ξ_s/ξ_f	0.76	0.79	0.83	0.80	0.91	0.76	0.83	0.82
S2y	8.4	11.6	13.2	11.07	5.8	8.8	8.7	7.7
F2y	11.7	10.1	8.7	10.2	6.5	10.9	7.9	8.4
ξ_s/ξ_f	0.72	1.15	1.51	1.09	0.90	0.81	1.09	0.92
S2z	7.4	11.3	14.3	11.0	5.3	7.8	12.4	8.5
F2z	9.4	10.4	8.9	9.6	6	9.1	7.6	7.6
ξ_s/ξ_f	0.79	1.09	1.59	1.15	0.88	0.86	1.62	1.12
S3y	5.8	8.5	10.2	8.2	5.2	6.3	7.8	6.4
F3y	6.9	8.5	9.2	8.2	5	5.8	7.2	6.0
ξ_s/ξ_f	0.84	1.00	1.11	1.00	1.04	1.09	1.09	1.07
S3z	8.5	6.9	7.7	7.7	5.1	5	6.3	5.5
F3z	6	7.8	8	7.3	5.7	5.5	7.5	6.2
ξ_s/ξ_f	1.42	0.89	0.97	1.06	0.88	0.90	0.84	0.88
S4y	10.1	11.4	10.5	10.7	9.9	8.8	9.9	9.5
F4y	9.8	9.3	8.4	9.2	9.8	8.6	8	8.8
ξ_s/ξ_f	1.03	1.23	1.26	1.16	1.01	1.02	1.23	1.08
S4z	9.7	10.3	8.8	9.6	9.7	8.1	9.5	9.1
F4z	10.8	10.1	9.7	10.2	10	8.7	8.4	9.0
ξ_s/ξ_f	0.90	1.02	0.91	0.94	0.98	0.93	1.14	1.01

The linear viscous model assumes that the energy dissipated in each cycle is linear with the frequency and quadratic with the displacement [18].

Dynamic response of an isolated structure depends mainly on the horizontal stiffness of isolators. The following equation for horizontal stiffness, K_h , is based on the simple analysis that can be found in strength of material text books and is used for both steel and fiber reinforcement conditions, although the equation is developed for elastomeric materials:

$$K_h = \frac{AG}{T_r}, \quad (5)$$

where K_h is horizontal stiffness of bearing (kN/m), G is shear modulus of elastomer (MPa), T_r is total thickness of elastomeric material (mm), and A is plan area of the bearing (mm^2).

3. Test Results and Discussion

Results of horizontal shear test are presented in this part. In Table 2, a comparison of numerical values of the damping of

both types of bearings at different strain levels is presented. The average damping of the bearing is the arithmetic mean of the damping values during all the cycles. As it is clear from the presented results in Table 2, there is not that much of difference between the average values of damping pertaining to the fiber mesh- and steel-reinforced bearings. The maximum difference between the average damping ratios is about 20%. The main source of energy dissipation in these elastomeric bearings is rubber compound and selection of reinforcement material is believed not to result in big difference in damping values. The damping values in this kind of fiber- and steel-reinforced bearing are within reasonable tolerances.

Horizontal effective stiffness test results of the bearings are presented in Table 3. The horizontal stiffness of the steel-reinforced bearings and that of fiber mesh-reinforced bearings do not differ much for large size bearings which had higher stiffness compared to the small sizes as expected. Larger specimens are more stable to rollover due to their geometrical properties and high ratios of area to elastomer thickness and rollover starts at high levels of shear strain in these bearings.

The same observation cannot be made for the small size bearings due to the early rollover response of the fiber mesh-reinforced bearings that decreased the stiffness at larger strain values significantly as shown in Figures 4(a)–4(d). In all of the shear tests, as strain level increases, effective stiffness of bearings decreases. Increase in vertical preload resulted in higher values of horizontal stiffness.

For Type 1 bearings, large size ones, at lower strain levels (up to 50%), stiffness of fiber-reinforced bearings was slightly greater than the steel-reinforced ones. As strain level increases, rollover of fiber-reinforced bearings commenced and this phenomenon led to a decrease in stiffness. In Type 2 bearings, stiffness of fiber-reinforced bearings at lower strain levels is greater than steel-reinforced ones but as rollover starts their stiffness decreases drastically. For Types 3 and 4 bearings, decrease in stiffness developed at lower strain levels. This observation could be attributed to the small size of the bearings because rollover deformation is affected by the ratio between the bearing thickness and base side length and bearings with smaller ratios have more potential to develop rollover response than larger specimens. In larger specimens, rollover starts at larger levels of strain compared to small size bearings. In steel-reinforced bearings, the same observation of rollover happens at larger strain levels compared to fiber-reinforced bearings. The governing trend in the tested specimens is that as strain level increases the difference between the effective stiffness of the steel-reinforced bearings and that of fiber-reinforced bearings increases and the amount of increase depends on several parameters such as size and vertical pressure.

The minimum divergence in stiffness of 1% is observed at high compressive stress levels for the bearings with larger plan area and thicker total elastomeric layers. The maximum divergence in stiffness of 78% is observed at low compressive stress levels for the small size bearing with lower total thickness of elastomeric materials.

The conventional horizontal stiffness presented in (5) has two components, one being material property and the other being size. The material property is presented by shear modulus G and the size index is presented by A/T_r ratio. In all the tests, the shear modulus G is the same. Therefore, a relationship for size effect versus correction factor is developed within this research. The nonlinear relationship between horizontal stiffness of steel-reinforced bearings and that of fiber mesh-reinforced bearings can be represented by

$$\frac{K_{(\text{eff})s}}{K_{(\text{eff})f}} = f\left(\frac{A}{T_r}\right) = \alpha, \quad (6)$$

where $K_{(\text{eff})s}$ is horizontal effective stiffness of steel-reinforced bearings, $K_{(\text{eff})f}$ is horizontal effective stiffness of fiber mesh-reinforced bearings, and α is nonlinear correction factor for size effect.

It has been experimentally determined that the α factor can be obtained from best fit curve using Figure 5:

$$\alpha = 6.09 \left(\frac{A}{T_r}\right)^{-0.23}. \quad (7)$$

Therefore, the effective horizontal stiffness of fiber mesh-reinforced bearings can be recommended for 100% strain:

$$K_{(\text{eff})f} = \frac{G}{6.09} \left(\frac{A}{T_r}\right)^{1.23}, \quad \frac{A}{T_r} \leq 3000. \quad (8)$$

No correction is suggested for A/T_r values exceeding 3000 mm²/mm and the effective stiffness for elastomeric material in (5) can be applied to fiber mesh-reinforced bearings. For strain levels less than 100%, linear interpolation for the values given in Table 3 can be recommended to use.

The proposed equation does not take account of the particular rollover deformation of fiber-reinforced bearings, but as in the studies by Kelly [19, 20], for example, the expression for estimating the rollout stability limit changes by only 5 percent when the compression load is doubled. So this equation can be used to determine the horizontal stiffness of the fiber-reinforced bearings in the range of discussed pressures (3.45–6.90 MPa).

Unbonded small size fiber-reinforced bearings can develop very low horizontal stiffness compared to steel-reinforced bearings and this may be considered as an advantage in design as long as rollover deformations of the bearings are stable. It shall be noted that the rollover did not develop any instability during tests. The reason is that all the specimens had curves with increasing resisting force at an increase of the applied shear deformation. No zero or negative tangent stiffness was observed in test results and after unloading there was not any residual deformation in the bearings. All the bearings sustained the applied load and strain levels and no visible damage was developed in bearings as shown in Figure 6.

It can be concluded that effective lateral stiffness of fiber-reinforced bearings is affected by several parameters such as geometrical properties, strain level, and vertical preload. It can be stated that rollover response of fiber-reinforced bearing is beneficial if the bearing remains stable horizontally.

Hysteresis loops obtained in horizontal shear test for selected bearings are plotted in terms of horizontal displacement versus horizontal load as shown in Figures 7(a)–7(d). In this figure, horizontal axis corresponds to displacement of bearings (mm) and vertical axis corresponds to horizontal force (kN). Horizontal stiffness for a single bearing is considered to be the half of the values since the tests are conducted simultaneously on two bearings.

4. Conclusion

Test results of new types of fiber mesh-reinforced elastomeric bearings and conventional isolators are compared. The observations made during the tests can be summarized as follows.

- (i) The conventional horizontal stiffness used in design of elastomeric materials does not always apply to the fiber mesh-reinforced bearings. At high levels of shear strain, there is a significant deviation in horizontal stiffness of small size fiber mesh-reinforced bearings compared to steel-reinforced bearings. A nonlinear

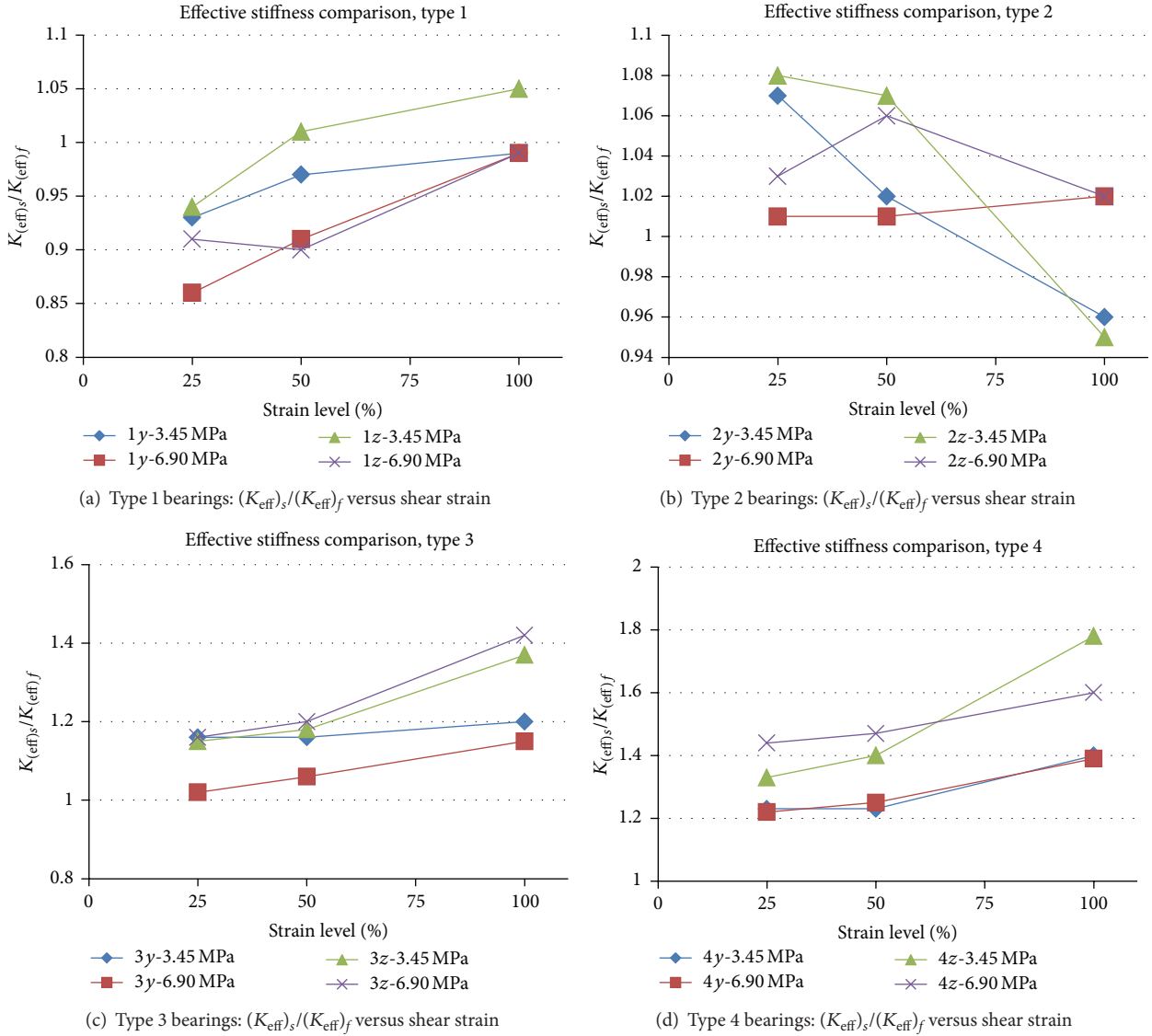


FIGURE 4: Comparison of effective stiffness of steel-reinforced and fiber-reinforced bearings.

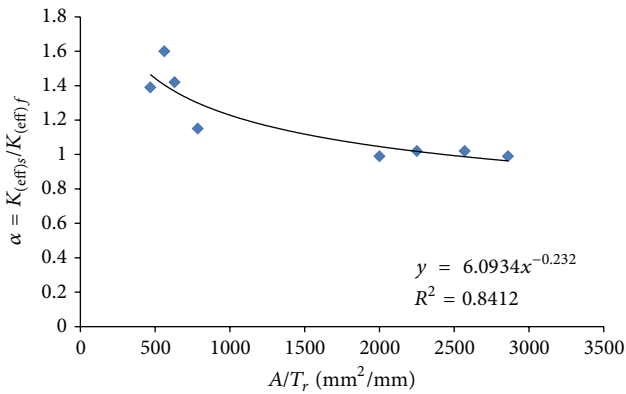


FIGURE 5: Suggested correction factor for horizontal stiffness for fiber mesh-reinforced bearings at 100% strain level.

equation is suggested as a correction factor for fiber-reinforced bearing horizontal stiffness computations to account for this divergence.

- (ii) The tests under different compressive loads revealed that the horizontal stiffness slightly increases under high compressive loads and proposed correction factor can be applied for both investigated cases in this research within a reasonable tolerance.
- (iii) Damping values in both fiber- and steel-reinforced bearings are similar since the same elastomeric material is used in both reinforcement conditions. Damping is typically provided by the selection of elastomeric material.

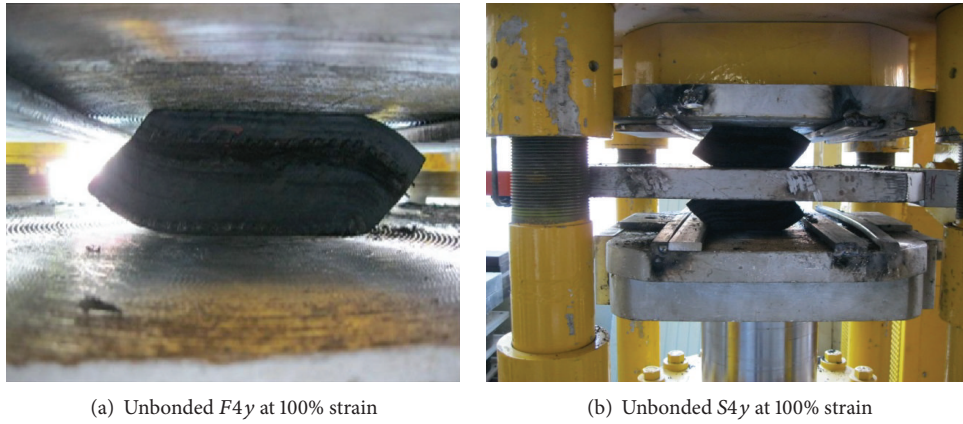


FIGURE 6: Deformation mode shape of fiber mesh-reinforced bearings.

TABLE 3: Effective stiffness values.

Type and stiffness ratio	Effective stiffness K_{eff}^h (kN/m)					
	Vertical pressure (MPa)					
	3.45 Strain level (%)			6.90 Strain level (%)		
	25	50	100	25	50	100
S1y	2221	1866	1619	2363	1995	1822
F1y	2383	1931	1633	2730	2187	1827
K_s/K_f	0.93	0.97	0.99	0.86	0.91	0.99
S1z	3438	2725	2387	3787	3005	2633
F1z	3674	2708	2278	4164	3326	2663
K_s/K_f	0.94	1.01	1.05	0.91	0.90	0.99
S2y	2519	2086	1784	2772	2307	2133
F2y	2347	2053	1865	2757	2296	2080
K_s/K_f	1.07	1.02	0.96	1.01	1.01	1.02
S2z	2962	2420	2035	3270	2755	2420
F2z	2737	2256	2135	3180	2602	2374
K_s/K_f	1.08	1.07	0.95	1.03	1.06	1.02
S3y	944	762	657	918	793	707
F3y	811	656	548	898	751	617
K_s/K_f	1.16	1.16	1.20	1.02	1.06	1.15
S3z	669	559	507	716	609	562
F3z	582	472	371	615	508	395
K_s/K_f	1.15	1.18	1.37	1.16	1.20	1.42
S4y	570	440	429	595	472	445
F4y	464	358	306	485	375	321
K_s/K_f	1.23	1.23	1.40	1.22	1.25	1.39
S4z	725	581	558	769	612	537
F4z	543	414	313	535	415	323
K_s/K_f	1.33	1.40	1.78	1.44	1.47	1.6

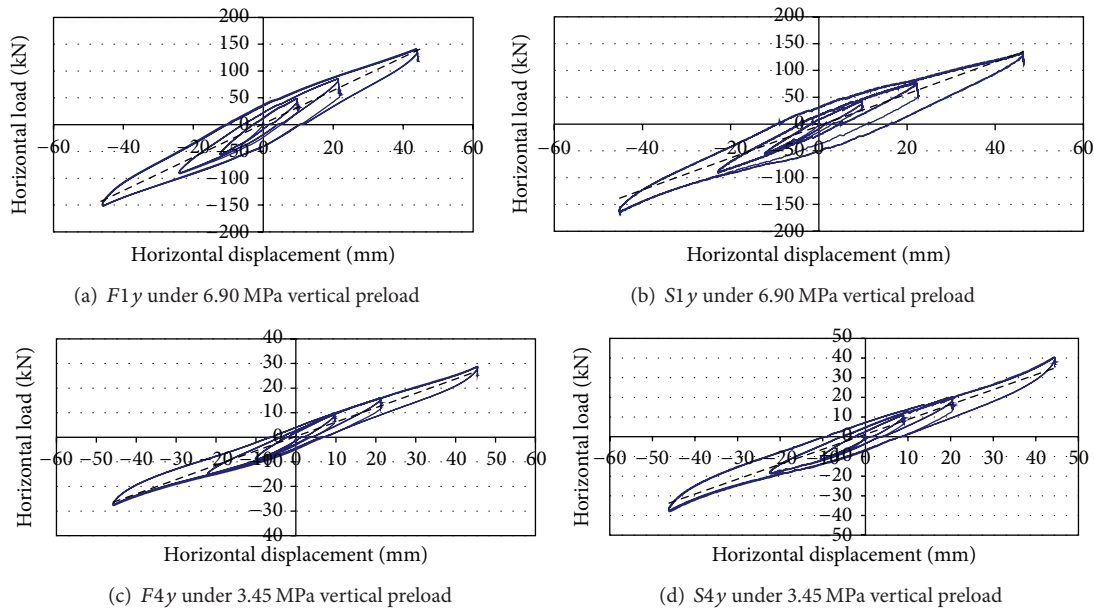


FIGURE 7: Horizontal shear test results for some of the specimens (horizontal load versus horizontal displacement for a pair of bearings).

Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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